

AERO

ASTRO



# 16.682 - Prototyping Avionics Spring 2006

LECTURE 3

February 15, 2006

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# Outline

- **More on Components**
  - Resistors, Capacitors, Inductors: ideal vs. real
  - First and second order systems
  - Diodes
- **Amplifiers**

# Last time...

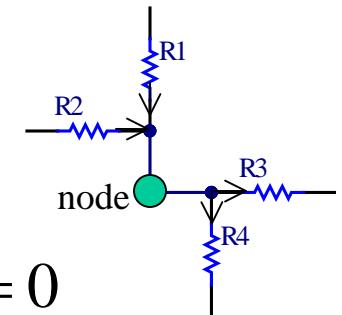
- **Four component laws**

- $v = iR$
- $i = C \frac{dv}{dt}$
- $v = L \frac{di}{dt}$
- $P = iv = i^2 R = \frac{v^2}{R}$

- **Two network laws**

- **KCL - Kirchoff's Current Law**

$$\sum_{\text{In/out of node}} i_n = 0$$

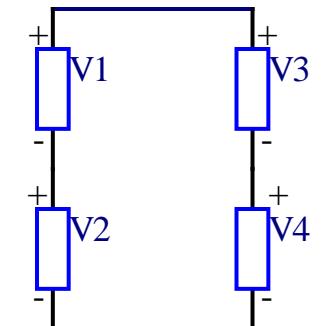


$$i_1 + i_2 + i_3 + i_4 = 0$$

- **KVL - Kirchoff's Voltage Law**

$$\sum_{\text{Around a loop}} v_n = 0$$

Around a loop



$$V_1 + V_2 = V_3 + V_4$$



# Ideal vs. Real

- Ideal

- Wire



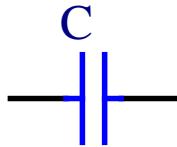
- $R=0, C=0, L=0$

- Resistor



- $C=0, L=0$

- Capacitor



- $R=0, L=0$

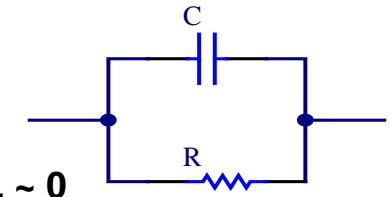
- Inductor



- $R=0, C=0$

- Real

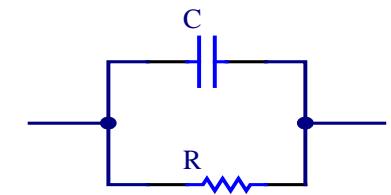
- Real
- $R \neq 0, C \neq 0, L \sim 0$



- $C \sim 0, L \sim 0$



- $R \neq 0, L \sim 0$

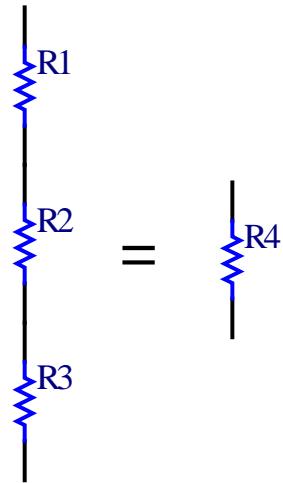


- $R \neq 0, C \sim 0$



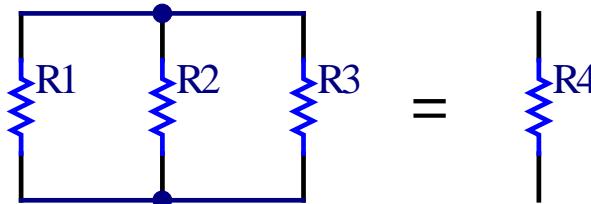
# Review of Resistors

- **Serial**



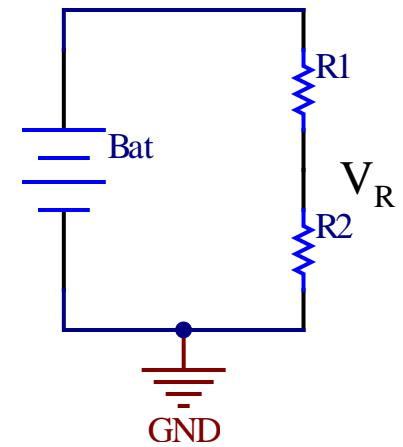
$$R_1 + R_2 + R_3 = R_4$$

- **Parallel**



$$\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} = \frac{1}{R_4}$$

- **Voltage divider**



- **For two resistors**

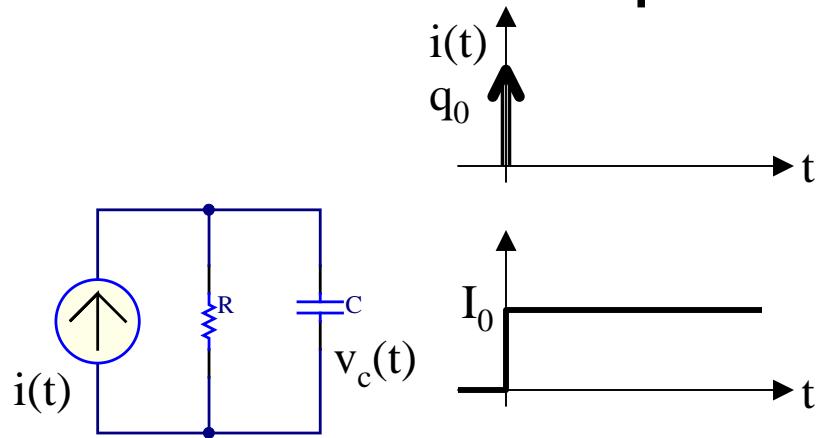
$$R_4 = \frac{R_1 R_2}{R_1 + R_2}$$

$$V_R = V_{\text{Bat}} \frac{R_2}{R_1 + R_2}$$

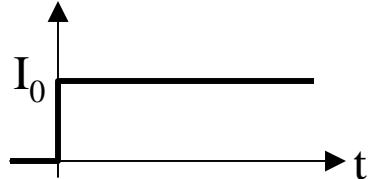


# First Order Systems

- Relation of different inputs

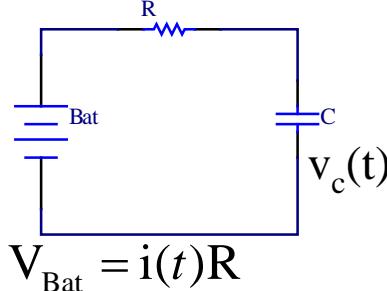


$$V_{\text{out}} = \frac{q_0}{C} e^{-\frac{t}{RC}}$$

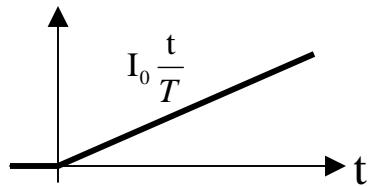


$$V_{\text{out}} = I_0 R \left( 1 - e^{-\frac{t}{RC}} \right)$$

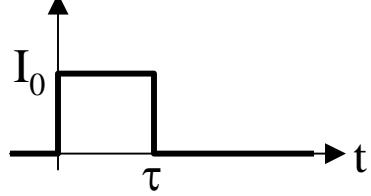
or



$$V_{\text{Bat}} = i(t)R$$

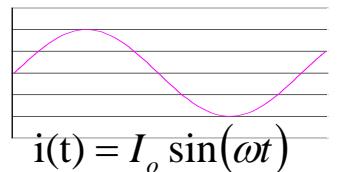


$$V_{\text{out}} = \frac{I_0 R}{T} \left( t + RC \left( e^{-\frac{t}{RC}} - 1 \right) \right)$$

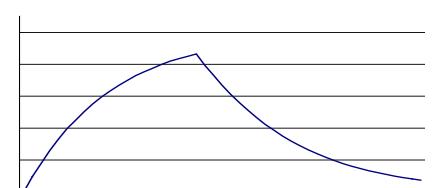
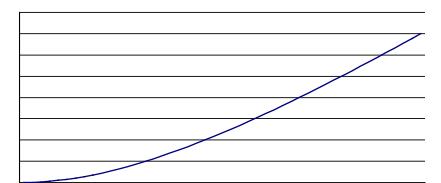
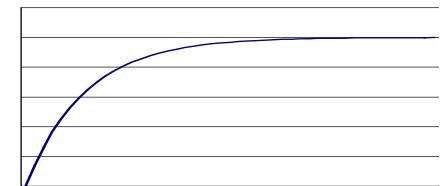
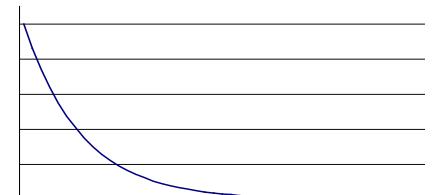


$$0 < t < \tau \rightarrow V_{\text{out}} = I_0 R \left( 1 - e^{-\frac{t}{RC}} \right)$$

$$t > \tau \rightarrow V_{\text{out}} = I_0 R \left( 1 - e^{-\frac{\tau}{RC}} \right) e^{\frac{(t-\tau)}{RC}}$$

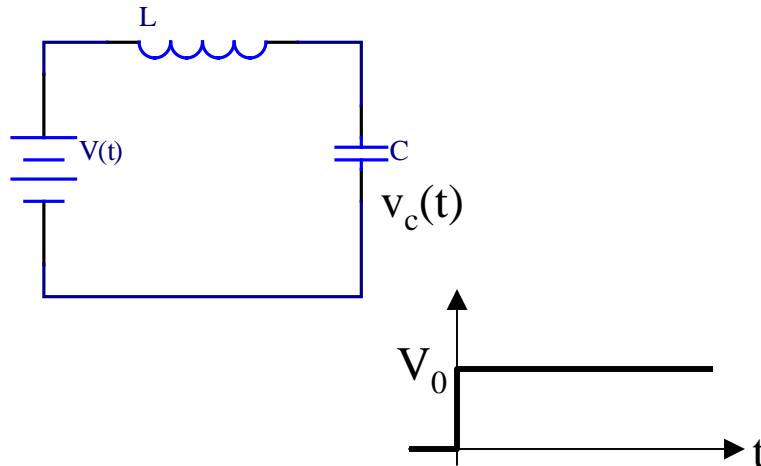


$$V_{\text{out}} = \frac{I_0 R}{\sqrt{1+(\omega RC)^2}} \sin(\omega t - \tan^{-1}(\omega RC))$$



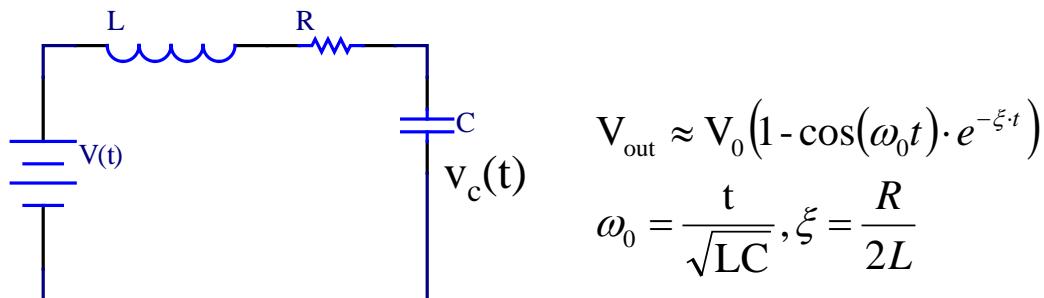
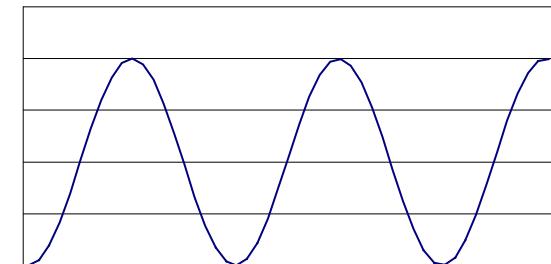
# Second Order Systems

- Circuits that combine capacitors and inductors are higher order



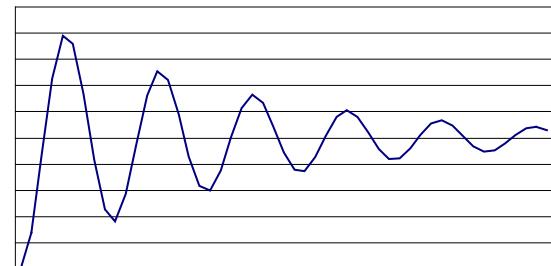
$$V_{\text{out}} = V_0(1 - \cos(\omega_0 t))$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$



$$V_{\text{out}} \approx V_0(1 - \cos(\omega_0 t) \cdot e^{-\xi \cdot t})$$

$$\omega_0 = \frac{1}{\sqrt{LC}}, \xi = \frac{R}{2L}$$

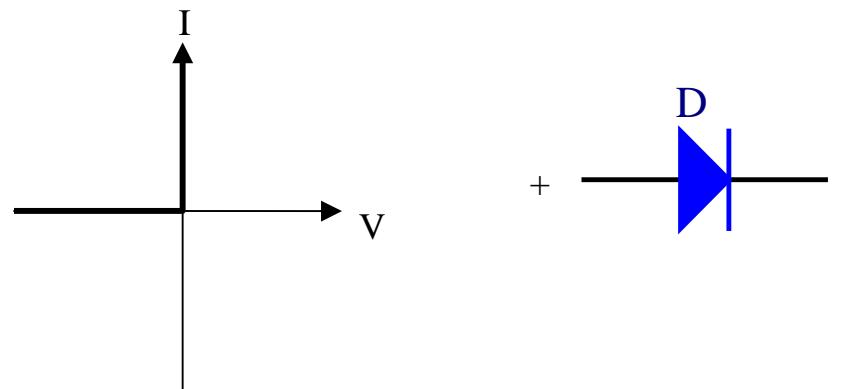


Resistor adds dampening

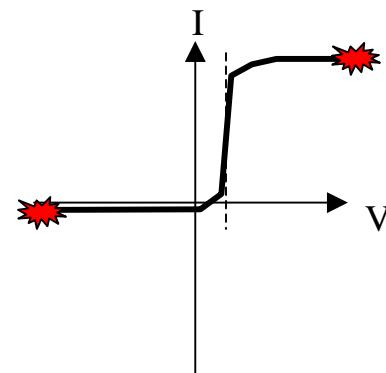


# Diodes

- Ideal



- Real



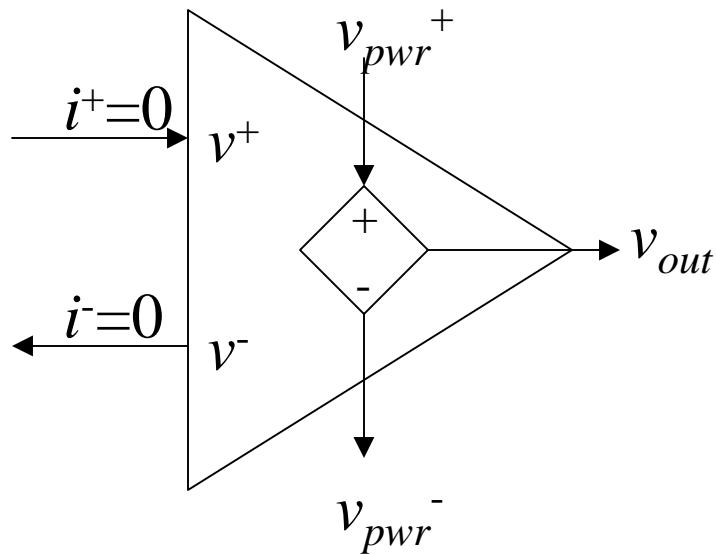
- Does not allow current flow when voltage is reversed
  - Stops all current
- Allows infinite current flow when positive voltage is applied

- Voltage drop: minimum voltage before current can go through
- Current leak: small amount of current goes through in reverse
- Maximum/Minimum voltage in both forward and reverse
- Maximum current in forward



# Introduction to Operational Amplifiers

- Utilize an “external” power source to amplify/modify an input signal
  - Allow the use of feedback to closely track the signal



- Adjusts the output voltage  $V_{out}$  to try make  $v^+$  and  $v^-$  be the same
  - The user adds elements (wires, resistors, capacitors, etc) which create current loops between the output and inputs to create feedback loops