

Fundamental Equations, Equilibrium, Free Energy, Maxwell Relations

- Fundamental Equations relate functions of state to each other using 1st and 2nd Laws

$$1^{\text{st}} \text{ law with expansion work: } dU = \delta q - p_{\text{ext}}dV$$

↖
need to express δq in
terms of state variables
because δq is path dependent

$$\text{Use 2}^{\text{nd}} \text{ law: } \delta q^{\text{rev}} = TdS$$

$$\text{For a } \underline{\text{reversible}} \text{ process } p_{\text{ext}} = p \text{ and } \delta q = \delta q^{\text{rev}} = TdS$$

$$\text{So..... } \mathbf{** dU = TdS - pdV **}$$

This fundamental equation only contains state variables

Even though this equation was derived for a reversible process, the equation is always correct and valid for a closed (no mass transfer) system, even in the presence of an irreversible process. This is because U , T , S , p , and V are all functions of state and independent of path.

AND The "best" or "natural" variables for U are S and V ,

$$\mathbf{** U(S,V) **}$$

$$** \boxed{U(S,V)} **$$

$$\text{From } dU = TdS - pdV \Rightarrow ** \boxed{\left(\frac{\partial U}{\partial S}\right)_V = T \quad ; \quad \left(\frac{\partial U}{\partial V}\right)_S = -p} **$$

We can write similar equations for enthalpy

$$H = U + pV \Rightarrow dH = dU + d(pV) = dU + pdV + Vdp$$

↖
inserting $dU = TdS - pdV$

$$\Rightarrow ** \boxed{dH = TdS + Vdp} **$$

The natural variables for H are then S and p

$$** \boxed{H(S,p)} **$$

$$\text{From } dH = TdS + Vdp \Rightarrow ** \boxed{\left(\frac{\partial H}{\partial S}\right)_p = T \quad ; \quad \left(\frac{\partial H}{\partial Vp}\right)_S = V} **$$

We can use these equations to find how S depends on T.

$$\text{From } dU = TdS - pdV \Rightarrow \boxed{\left(\frac{\partial S}{\partial T}\right)_V = \frac{1}{T} \left(\frac{\partial U}{\partial T}\right)_V = \frac{C_V}{T}}$$

$$\text{From } dH = TdS + Vdp \Rightarrow \boxed{\left(\frac{\partial S}{\partial T}\right)_p = \frac{1}{T} \left(\frac{\partial H}{\partial T}\right)_p = \frac{C_p}{T}}$$

Criteria for Spontaneous Change

The 2nd Law gave the Clausius inequality for spontaneous change

$$dS > \delta q / T_{\text{surr.}}$$

The 1st law gave us $dU = \delta q + \delta w$

Putting the two together, assuming only pV work, gives us the following general criterion for spontaneous change:

$$** \boxed{dU + p_{\text{ext}}dV - T_{\text{surr}}dS < 0} **$$

Equilibrium is when there is no possible change of state that would satisfy this inequality.

We can now use the general criterion above under specific conditions

- Consider first an isolated system ($q=w=0, \Delta V=0, \Delta U=0$)

Since $dU=0$ and $dV=0$, from the general criterion above, then

$$\boxed{(dS)_{U,V} > 0}$$

is the criterion for spontaneity for an isolated system

And equilibrium for an isolated system is then achieved when entropy is maximized. At maximum entropy, no spontaneous changes can occur.

- Consider now S and V constant

$$\Rightarrow \boxed{(dU)_{S,V} < 0}$$

is the criterion for spontaneity under constant V and S

At constant S and V, equilibrium is achieved when energy is minimized

- Consider now S constant and $p=p_{\text{ext}}$ constant

$$\Rightarrow dU + pdV < 0 \Rightarrow d(U + pV) < 0$$

\swarrow
=H

So

$$\Rightarrow \boxed{(dH)_{S,p_{\text{ext}}} < 0}$$

is the criterion for spontaneity under constant S and constant $p=p_{\text{ext}}$.

- Consider now H constant and $p=p_{\text{ext}}$ constant

$$dU + pdV - T_{\text{surr}}dS < 0$$

but $dU + pdV = dH$, which is 0 (H is constant)

$$\text{So } \boxed{(dS)_{H,p=p_{\text{ext}}} > 0}$$

is the criterion for spontaneity under constant H and constant $p=p_{\text{ext}}$.

Now let's begin considering cases that are experimentally more controllable.

- Consider now constant $T=T_{\text{surr}}$ and constant V

$$\Rightarrow dU - TdS < 0 \Rightarrow d(U - TS) < 0$$

Define $A = U - TS$, the Helmholtz Free Energy

$$\text{Then } (dA)_{V, T=T_{\text{surr}}} < 0$$

is the criterion for spontaneity under constant $T=T_{\text{surr}}$ and constant V .

For constant V and constant $T=T_{\text{surr}}$, equilibrium is achieved when the Helmholtz free energy is minimized.

We now come to the most important and applicable constraint:

- Consider now constant $T=T_{\text{surr}}$ and constant $p=p_{\text{ext}}$.

$$(dU + pdV - TdS) < 0 \Rightarrow d(U + pV - TS) < 0$$

Define $G = U + pV - TS$, the Gibbs Free Energy

(can also be written as $G = A + pV$ and $G = H - TS$)

$$\text{Then } (dG)_{p=p_{\text{ext}}, T=T_{\text{surr}}} < 0$$

is the criterion for spontaneity under constant $T=T_{\text{surr}}$ and constant $p=p_{\text{ext}}$.

At constant $p=p_{\text{ext}}$ and constant $T=T_{\text{surr}}$, equilibrium is achieved when the Gibbs free energy is minimized.

Consider the process:



Under constant $p=p_{\text{ext}}$ and $T=T_{\text{surr}}$,

$$\begin{array}{ll} \Delta G < 0 & A \rightarrow B \text{ is spontaneous} \\ \Delta G = 0 & A \text{ and } B \text{ are in equilibrium} \\ \Delta G > 0 & \text{then } B \rightarrow A \text{ is spontaneous} \end{array}$$

Maxwell Relations

- With the free energies

$$\begin{array}{ll} \text{Helmholtz free energy} & A = U - TS \\ \text{Gibbs free energy} & G = H - TS \end{array}$$

we've introduced all our state functions. For closed systems,

$$\begin{array}{ll} U(S, V) & \Rightarrow dU = TdS - pdV \\ H(S, p) & \Rightarrow dH = TdS + Vdp \\ A(T, V) & \Rightarrow dA = -SdT - pdV \\ G(T, p) & \Rightarrow dG = -SdT + Vdp \end{array}$$

Fundamental equations

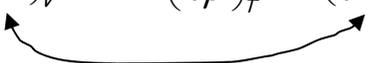
From $dA = \left(\frac{\partial A}{\partial T}\right)_V dT + \left(\frac{\partial A}{\partial V}\right)_T dV$

and $dG = \left(\frac{\partial G}{\partial T}\right)_p dT + \left(\frac{\partial G}{\partial p}\right)_T dp$

$$\begin{array}{ll} \left(\frac{\partial A}{\partial T}\right)_V = -S & \left(\frac{\partial A}{\partial V}\right)_T = -p \\ \left(\frac{\partial G}{\partial T}\right)_p = -S & \left(\frac{\partial G}{\partial p}\right)_T = V \end{array}$$

The Maxwell relations: $\frac{\partial^2 A}{\partial V \partial T} = \frac{\partial^2 A}{\partial T \partial V}$ and $\frac{\partial^2 G}{\partial p \partial T} = \frac{\partial^2 G}{\partial T \partial p}$

now allow us to find how S depends on V and p .

$$\Rightarrow \left(\frac{\partial S}{\partial V} \right)_T = \left(\frac{\partial p}{\partial T} \right)_V \quad \left(\frac{\partial S}{\partial p} \right)_T = - \left(\frac{\partial V}{\partial T} \right)_p$$


These can be obtained from an equation of state.

We can now also relate U and H to p - V - T data.

$$\left. \begin{aligned} \left(\frac{\partial U}{\partial V} \right)_T &= T \left(\frac{\partial S}{\partial V} \right)_T - p = T \left(\frac{\partial p}{\partial T} \right)_V - p \\ \left(\frac{\partial H}{\partial p} \right)_T &= T \left(\frac{\partial S}{\partial p} \right)_T + V = V - T \left(\frac{\partial V}{\partial T} \right)_p \end{aligned} \right\} \rightarrow U \text{ and } H \text{ from equations of state!}$$

- For an ideal gas $pV = nRT$

$$\left(\frac{\partial p}{\partial T} \right)_V = \frac{nR}{V} = \frac{p}{T} \Rightarrow \left(\frac{\partial U}{\partial V} \right)_T = 0$$

$$\left(\frac{\partial V}{\partial T} \right)_p = \frac{nR}{p} = \frac{V}{T} \Rightarrow \left(\frac{\partial H}{\partial p} \right)_T = 0$$

This proves that for an ideal gas $U(T)$ and $H(T)$, functions of T only. We had assumed this was true from Joule and Joule-Thomson expansion experiments. Now we know it is rigorously true.