

TR_1D_model1_SS\discretize_boundary_deriv.m

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% TR_1D_model1_SS\discretize_boundary_deriv.m
%
% function [c1,c2,c3,iflag] = ...
%   discretize_boundary_deriv(z1,z2,z3);
%
% This procedure uses Lagrange interpolation to
% calculate the coefficients multiplying the values
% of a field at a boundary point and two interior
% points normal to the boundary that discretize
% the normal first derivative operator at the boundary.
%
% INPUT :
% ======
% z1          REAL
%   the value of the normal coordinate (z) at the boundary
% z2          REAL
%   the value of the normal coordinate at the first point
%   within the interior
% z3          REAL
%   the value of the normal coordinate at the second point
%   within the interior
%----- * = z1
%           * = z2
%           * = z3
%
% OUTPUT :
% ======
% c1          REAL
%   the coefficient multiplying the field value at z1 in
%   the discretized form of the normal derivative operator
% c2          REAL
%   the coefficient multiplying the field value at z2 in
%   the discretized form of the normal derivative operator
% c3          REAL
%   the coefficient multiplying the field value at z3 in
%   the discretized form of the normal derivative operator
% iflag      INT
%   this integer flag tells how the routine has performed
%   its job :
%   iflag < 0, exit with error
%   iflag = 0, incomplete
%   iflag = 1, successful completion
%
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% 7/2/2001
%
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% Version as of 7/23/2001

function [c1,c2,c3,iflag] = ...
    discretize_boundary_deriv(z1,z2,z3);

iflag = 0;

func_name = 'discretize_boundary_deriv';

% This integer flag controls the level of action
% to take in the case of an assertion or called
% routine failure.
i_error = 2;

% check input

% z1, z2, z3
check_real=1; check_sign=0; check_int=0;
assert_scalar(i_error,z1,'z1', ...
    func_name,check_real,check_sign,check_int);
assert_scalar(i_error,z2,'z2', ...
    func_name,check_real,check_sign,check_int);
assert_scalar(i_error,z3,'z3', ...
    func_name,check_real,check_sign,check_int);

% check that these z values are distinct
i_distinct = 1;
if(z1==z2)
    i_distinct = 0;
end
if(z1==z3)
    i_distinct = 0;
end
if(z2==z3)
    i_distinct = 0;
end
if(i_distinct == 0)
    iflag = -1;
    message = [func_name, ': ', ...
        'Input z1,z2,z3 are not distinct'];
    if(i_error ~= 0)
        if(i_error > 1)
            save dump_error.mat;
        end
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    error(message);
else
    return;
end
end

%PDL> c1 = (2*z1 - z2 - z3) / ( (z1-z2)*(z1-z3) )

c1 = (2*z1 - z2 - z3) / ( (z1-z2)*(z1-z3) );

%PDL> c2 = (2*z1 - z1 - z3) / ( (z2-z1)*(z2-z3) )

c2 = (2*z1 - z1 - z3) / ( (z2-z1)*(z2-z3) );

%PDL> c3 = (2*z1 - z1 - z2) / ( (z3-z1)*(z3-z2) )

c3 = (2*z1 - z1 - z2) / ( (z3-z1)*(z3-z2) );

iflag = 1;

return;
```