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% nlin_fit_kinetics_setup
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% nlin_fit_kinetics_setup.m  
%  
% This MATLAB m-file sets up the problem of  
% fitting the rate constants for the network  
% of two reactions :  
% A + B --> C  
% C + B --> D  
%  
% The two parameters to be fixed are the rate  
% constants for each reaction.  
%  
% The data to be fit are the concentrations of  
% species A, C, and D for various times for  
% several experiments of initial concentrations  
% of A and B.  
%  
% K. Beers  
% MIT ChE  
% 12/9/2001
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% First, we set the true values of the rate constants.
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k1 = 1;  
k2 = 10;
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% We now set the experimental conditions.
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Param_fix.num_experiments = 3;  
Param_fix.conc_init = zeros(3,4);  
Param_fix.num_time_data = zeros(3,1);  
Param_fix.time_data = zeros(3,8);  
% experiment # 1  
Param_fix.conc_init(1,:) = [1 1 0 0];  
Param_fix.num_time_data(1) = 8;  
Param_fix.time_data(1,1:8) = [0 0.2 0.4 0.6 0.8 1.0 1.2 1.4];  
% experiment # 2  
Param_fix.conc_init(2,:) = [1 2 0 0];  
Param_fix.num_time_data(2) = 6;  
Param_fix.time_data(2,1:6) = [0 0.2 0.4 0.6 0.8 1.0];  
% experiment # 3  
Param_fix.conc_init(3,:) = [1 3 0 0];  
Param_fix.num_time_data(3) = 6;  
Param_fix.time_data(3,1:6) = [0 0.2 0.4 0.6 0.8 1.0];
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% We now generate the data for each experiment using  
% the true values of the rate constants.
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theta_true = [k1; k2];  
y = nlin_fit_kinetics(theta_true,Param_fix);
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% To this we add a random noise according to a  
% normal distribution.
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std_dev = 0.01;
y = y + std_dev*randn(length(y),1);

% We now call the nonlinear parameter estimation
% routine for this data, using the true values
% as the initial guess.
calc_yhat = 'nlin_fit_kinetics';
theta_guess = theta_true;
alpha_CI = 0.05;
Options.atol = 1e-6;
Options.verbose = 2;
[theta,theta_CI,yhat,yhat_CI,Stats,iflag] = ...
    simple_nonlinear_LS(...  
y,calc_yhat,theta_guess,alpha_CI,Options,Param_fix);

% We now plot the experimental data along with the
% model predictions and the confidence intervals.
count_master = 0;
Afig = figure;
Cfig = figure;
Dfig = figure;
for iexp=1:3
    count = count_master;
    if(iexp == 1)
        symbol = 'o';
    elseif(iexp == 2)
        symbol = 's';
    else
        symbol = 'd';
    end
    % plot experimental data
    time_vect = Param_fix.time_data(iexp,1:Param_fix.num_time_data(iexp));
    A_data = y(count+1:count+Param_fix.num_time_data(iexp));
    count = count + Param_fix.num_time_data(iexp);
    C_data = y(count+1:count+Param_fix.num_time_data(iexp));
    count = count + Param_fix.num_time_data(iexp);
    D_data = y(count+1:count+Param_fix.num_time_data(iexp));
    figure(Afig);
    plot(time_vect,A_data,symbol);
    figure(Cfig);
    plot(time_vect,C_data,symbol);
    figure(Dfig);
    plot(time_vect,D_data,symbol);
    % plot model predictions
    count = count_master;
    A_data = yhat(count+1:count+Param_fix.num_time_data(iexp));
    count = count + Param_fix.num_time_data(iexp);
    C_data = yhat(count+1:count+Param_fix.num_time_data(iexp));
    count = count + Param_fix.num_time_data(iexp);
    D_data = yhat(count+1:count+Param_fix.num_time_data(iexp));
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figure(Afig); hold on;
plot(time_vect,A_data);
figure(Cfig); hold on;
plot(time_vect,C_data);
figure(Dfig); hold on;
plot(time_vect,D_data);
% plot lower CI interval on predictions
count = count_master;
A_data = yhat(count+1:count+Param_fix.num_time_data(iexp)) - ...
    yhat_CI(count+1:count+Param_fix.num_time_data(iexp));
count = count + Param_fix.num_time_data(iexp);
C_data = yhat(count+1:count+Param_fix.num_time_data(iexp)) - ...
    yhat_CI(count+1:count+Param_fix.num_time_data(iexp));
count = count + Param_fix.num_time_data(iexp);
D_data = yhat(count+1:count+Param_fix.num_time_data(iexp)) - ...
    yhat_CI(count+1:count+Param_fix.num_time_data(iexp));
figure(Afig); hold on;
plot(time_vect,A_data,'.-');
figure(Cfig); hold on;
plot(time_vect,C_data,'.-');
figure(Dfig); hold on;
plot(time_vect,D_data,'.-');
% plot upper CI interval on predictions
count = count_master;
A_data = yhat(count+1:count+Param_fix.num_time_data(iexp)) + ...
    yhat_CI(count+1:count+Param_fix.num_time_data(iexp));
count = count + Param_fix.num_time_data(iexp);
C_data = yhat(count+1:count+Param_fix.num_time_data(iexp)) + ...
    yhat_CI(count+1:count+Param_fix.num_time_data(iexp));
count = count + Param_fix.num_time_data(iexp);
D_data = yhat(count+1:count+Param_fix.num_time_data(iexp)) + ...
    yhat_CI(count+1:count+Param_fix.num_time_data(iexp));
figure(Afig); hold on;
plot(time_vect,A_data,'.-');
figure(Cfig); hold on;
plot(time_vect,C_data,'.-');
figure(Dfig); hold on;
plot(time_vect,D_data,'.-');
clear A_data C_data D_data;
% update the master count vector
count_master = count_master + 3*Param_fix.num_time_data(iexp);
end
% Then, add the labels to each graph.
figure(Afig);
xlabel('time');
ylabel('[A]');
title('Concentration of species A');
figure(Cfig);
xlabel('time');
ylabel('[C]');
title('Concentration of species C');
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figure(Dfig);
xlabel('time');
ylabel('[D]');
title('Concentration of species D');
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