

recall the significance of $\mu_i = \frac{\partial G}{\partial n_i}$

the change in energy associated with the change in the amount of mass in the system.

The Gibbs-Duhem expression arises from the fact that intensive properties are not affected by the size of the system, but extensive properties are.... So, for each phase we can write

dG , the change in the Gibbs energy is

$$dG = \sum_{i=1}^j n_i d\mu_i + \underbrace{\sum_{i=1}^j \mu_i dn_i}_{\text{the intensive part}}$$

using the expression for $dG = -SdT + VdP + \sum_i \mu_i dn_i$
we get the Gibbs-Duhem expression for each phase

$$-SdT + VdP - \sum_i n_i d\mu_i = 0$$

thus, for any group of coexisting phases we can write the following relation for each phase in the system.

$$\sum_i n_i d\mu_i = \bar{V}dP - \bar{S}dT$$

so - first let's consider a ^{10/31/01} ~~component~~^④ 2 component system
and a univariant equilibrium -

recall that in a one component system at
a univariant equilibrium we showed that

$$\frac{dT}{dP} = \frac{\Delta V}{\Delta S} \dots$$

for two components and 3 phases (A, B and C)
the Gibbs-Duhem looks like the following ...

$$x_{1A} d\mu_1 + x_{2A} d\mu_2 = \bar{V}_A dP - \bar{S}_A dT$$

$$x_{1B} d\mu_1 + x_{2B} d\mu_2 = \bar{V}_B dP - \bar{S}_B dT$$

$$x_{1C} d\mu_1 + x_{2C} d\mu_2 = \bar{V}_C dP - \bar{S}_C dT$$

rearranging ...

$$\bar{S}_A = \bar{V}_A \left. \frac{dP}{dT} \right|_{3\phi} - x_{1A} \left. \frac{d\mu_1}{dT} \right|_{3\phi} - x_{2A} \left. \frac{d\mu_2}{dT} \right|_{3\phi}$$

$$\bar{S}_B = \bar{V}_B \left. \frac{dP}{dT} \right|_{3\phi} - x_{1B} \left. \frac{d\mu_1}{dT} \right|_{3\phi} - x_{2B} \left. \frac{d\mu_2}{dT} \right|_{3\phi}$$

$$\bar{S}_C = \bar{V}_C \left. \frac{dP}{dT} \right|_{3\phi} - x_{1C} \left. \frac{d\mu_1}{dT} \right|_{3\phi} - x_{2C} \left. \frac{d\mu_2}{dT} \right|_{3\phi}$$

— we can solve this system of equations using
Crane's rule because these equations are equal,

$$\left. \frac{dP}{dT} \right|_{3\phi} = \begin{vmatrix} \bar{S}_A & x_{1A} & x_{2A} \\ \bar{S}_B & x_{1B} & x_{2B} \\ \bar{S}_C & x_{1C} & x_{2C} \end{vmatrix} \begin{vmatrix} \bar{V}_A & x_{1A} & x_{2A} \\ \bar{V}_B & x_{1B} & x_{2B} \\ \bar{V}_C & x_{1C} & x_{2C} \end{vmatrix}$$

← ratio of
these
determinants

Note that for a one component system the ③ equivalent expression would be

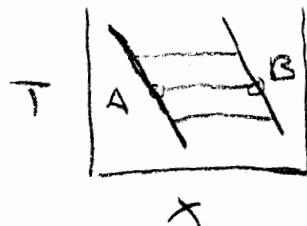
$$\frac{dP}{dT} = \frac{\left[\begin{array}{c} \bar{s}_A x_{1A} \\ \bar{s}_B x_{1B} \end{array} \right]}{\left[\begin{array}{c} \bar{V}_A x_{1A} \\ \bar{V}_B x_{1B} \end{array} \right]} \quad \text{since } x_{1A} = x_{1B} = 1$$

this reduces to

$$\frac{dP}{dT} = \frac{\Delta S_{rxn}}{\Delta V_{rxn}}$$

now consider the case where we have a 2 phase coexistence in a binary system

for example



we use the relation $x_{1A} = 1 - x_{2A}$ and substitute

*(The real
the Gibbs
Duhem eqns
give each
phase, we
have 4 unknowns $d\mu_1$, $d(\mu_2 - \mu_1)$, dP & dT)*

$$\begin{cases} (1-x_{2A})d\mu_1 + x_{2A}d\mu_2 = \bar{V}_A dP - \bar{s}_A dT \\ d\mu_1 + x_{2A}d(\mu_2 - \mu_1) = \bar{V}_A dP - \bar{s}_A dT \end{cases}$$

we also

~~the total differential is $d(\mu_2 - \mu_1)$~~
~~can also be written as:~~

$$dG_A = \left(\frac{\partial G}{\partial P}_{T,x} \right) dP + \left(\frac{\partial G}{\partial T}_{P,x} \right) dT + \left(\frac{\partial G}{\partial x} \right)_{T,P} dx_2$$

$$= \Delta V_A dP - \Delta S_A dT + G_{xxA} > 0 \text{ for coexisting phases}$$

(4)

$$dG_A = (\bar{V}_{2A} - \bar{V}_{1A})dP - (\bar{S}_{2A} - \bar{S}_{1A})dT + \Delta_{xx}dX_2$$

$$dG_A = d(\mu_2 - \mu_1)_A$$

) slopes of tangent planes are the
same for two phases
in equilibrium

so rearrange & solve

$$d(\mu_2 - \mu_1) = (\bar{V}_{2A} - \bar{V}_{1A})dP - (\bar{S}_{2A} - \bar{S}_{1A})dT + \Delta_{xx}dX_2$$

$$d\mu_1 + X_{2A} d(\mu_2 - \mu_1) = -\bar{S}_A dT + \bar{V}_A dP$$

$$d\mu_1 + X_{2B} d(\mu_2 - \mu_1) = -\bar{S}_B dT + \bar{V}_B dP$$

$$d\mu_1^* = -X_{2A} d(\mu_2 - \mu_1) - \bar{S}_A dT + \bar{V}_A dP$$

$$d\mu_{11}^* = -X_{2B} d(\mu_2 - \mu_1) - \bar{S}_B dT + \bar{V}_B dP$$

$$0 = (X_{2B} - X_{2A}) d(\mu_2 - \mu_1) + (\bar{S}_B - \bar{S}_A) dT - (\bar{V}_B - \bar{V}_A) dP$$

plugging in the expression for

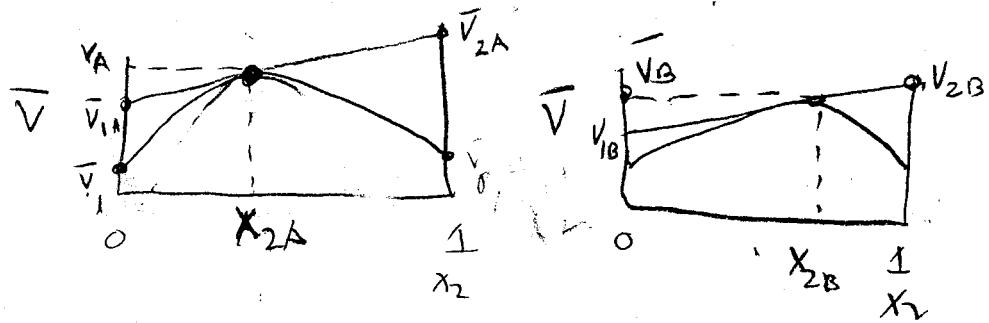
$$d(\mu_2 - \mu_1)$$

$$\frac{(x_{2B} - x_{2A}) d(\mu_2 - \mu_1)}{=} = (\bar{V}_B - \bar{V}_A) dP - (\bar{S}_B - \bar{S}_A) dT \quad (3)$$

$$(x_{2B} - x_{2A}) [(\bar{V}_{2A} - \bar{V}_{1A}) dP - (\bar{S}_{2A} - \bar{S}_{1A}) dT + \Delta_{xx} dx_2] = \\ (\bar{V}_B - \bar{V}_A) dP - (\bar{S}_B - \bar{S}_A) dT$$

$$(x_{2B} - x_{2A}) \Delta_{xx} dx_2 = [(\bar{V}_B - \bar{V}_A) - (\bar{V}_{2A} - \bar{V}_{1A})(x_{2B} - x_{2A})] dP \\ + [(\bar{S}_{2A} - \bar{S}_{1A})(x_{2B} - x_{2A}) - (\bar{S}_B - \bar{S}_A)] dT$$

2nd
deriv
of G
wrt comp
goes to zero
since $dx_2 = 0$



wilker et al., discuss ①

concerned with crystal / melt buoyancy

the effects of multi-component equilibs.

p. 318 bottom left last sent.

p. 319 - changes in slope
of liquidus
- why not important

left-hand side
2nd point
several points