

# Factor analysis techniques in single-particle aerosol mass spectrometry

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# Single-particle aerosol mass spectrometry

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The figure is from

Thomson, D.S., M.E. Schein, and D.M. Murphy, Particle analysis by laser mass spectrometry WB-57 instrument overview, *Aerosol Science and Technology*, 33, 153-169, 2000. Please see Figure 1.

# The challenge

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Murphy, D. M., A. M. Middlebrook, and M. Warshawsky, Cluster analysis of data from the Particle Analysis by Laser Mass Spectrometry (PALMS) instrument, *Aerosol Sci. Technol.*, 37, 382-391, 2003.

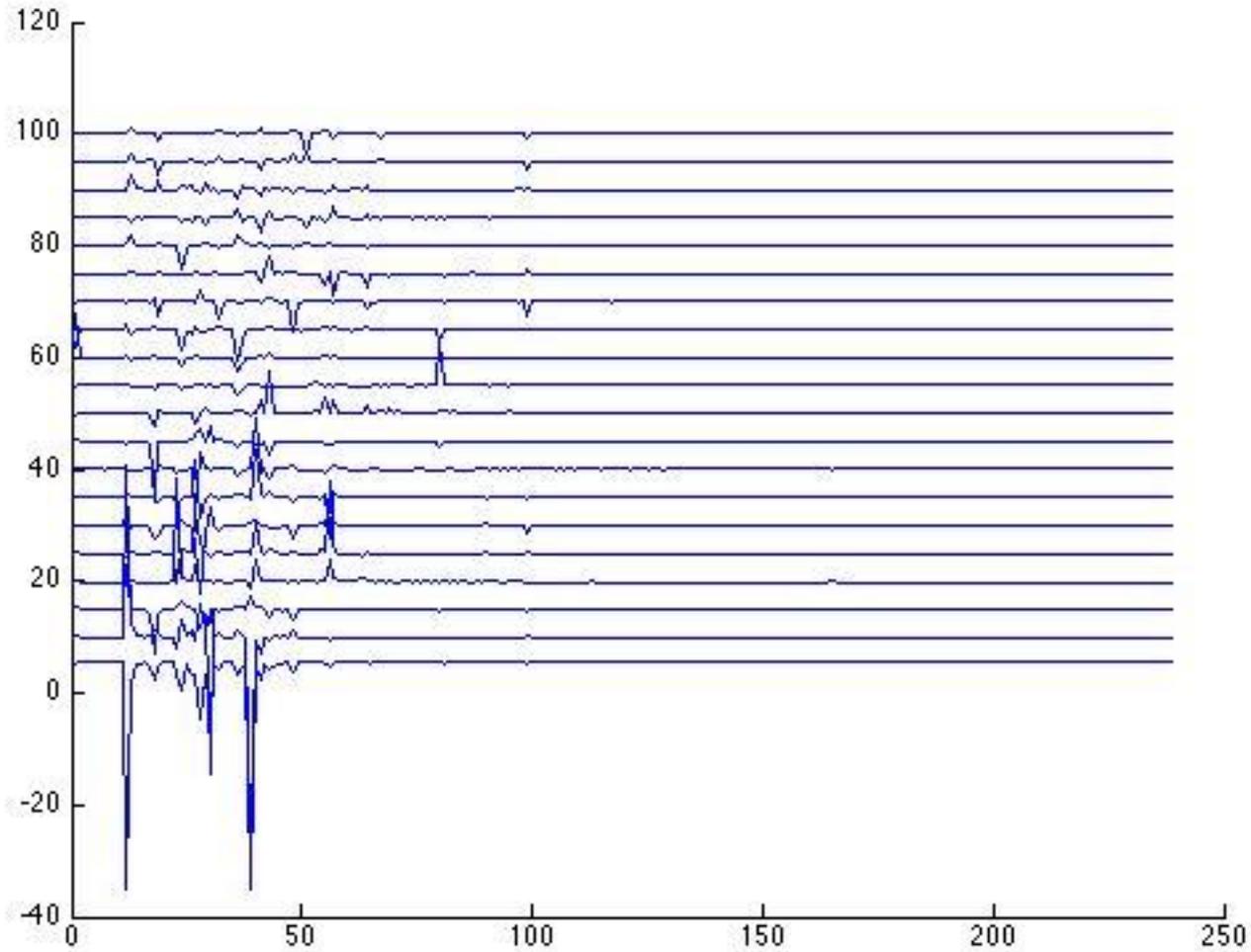
# Principal component analysis

Probabilistic PCA: PCA together with EM to handle large data sets and missing values. Algorithm written by Jakob Verbeek, et al. 2002.

If  $y$  is a data vector and  $x$  is a vector of principal components,

- E-step: estimate  $x$  vectors and missing values of  $y$
- M-step: maximize the expected joint log-likelihood of  $x$  and  $y$

# Principal component analysis



# Independent component analysis

1. Starts with the principal components derived from the previous algorithm.

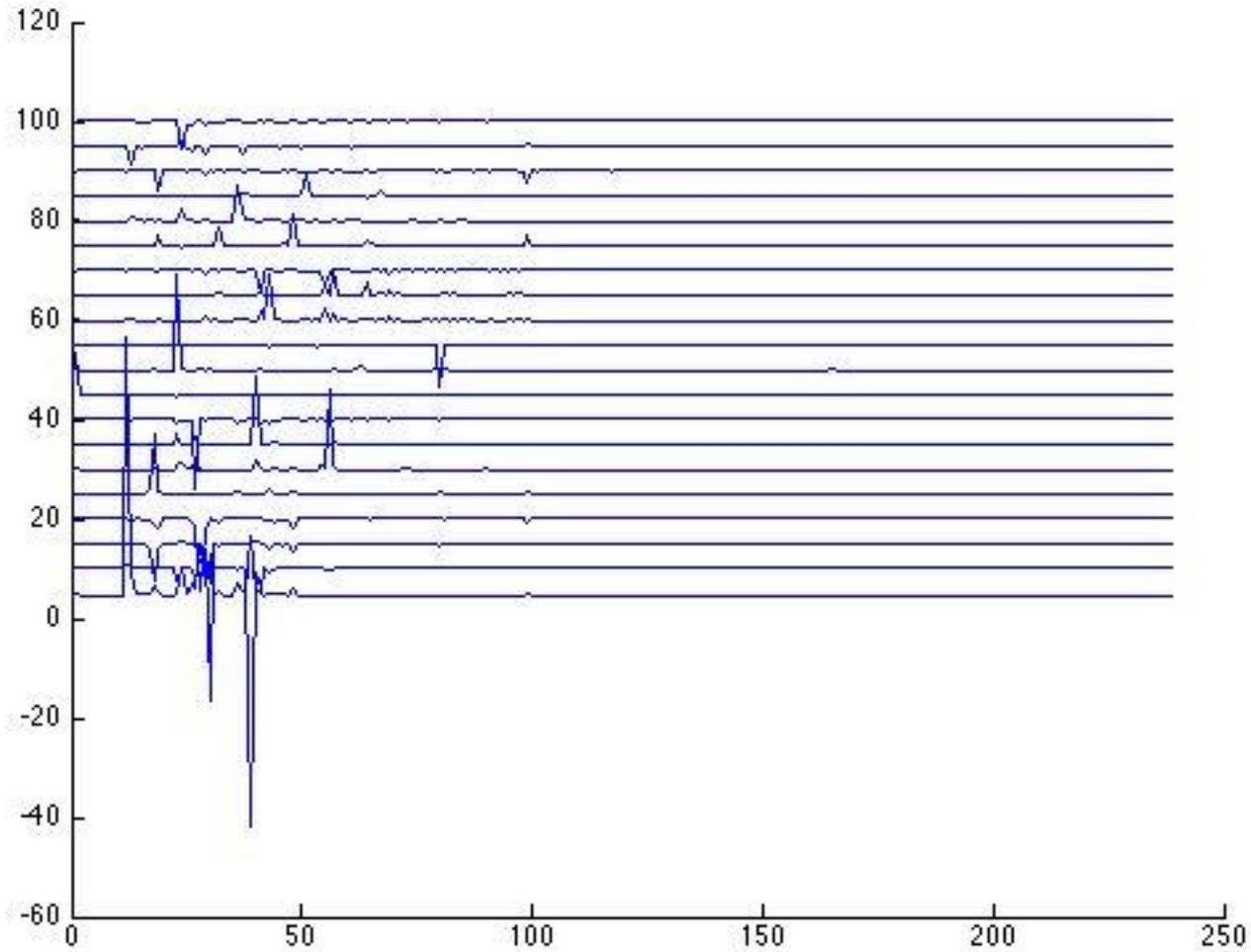
1. Assumes non-Gaussian distributions, maximizes the kurtosis for randomly-generated weighing factors.

2. Decorrelates and re-normalizes factors after every iteration:

$$W_{p+1} = W_{p+1} - \sum_{j=1}^p W_{p+1}^T W_j W_j$$

$$W_{p+1} = W_{p+1} / \sqrt{W_{p+1}^T W_{p+1}}$$

# Independent component analysis



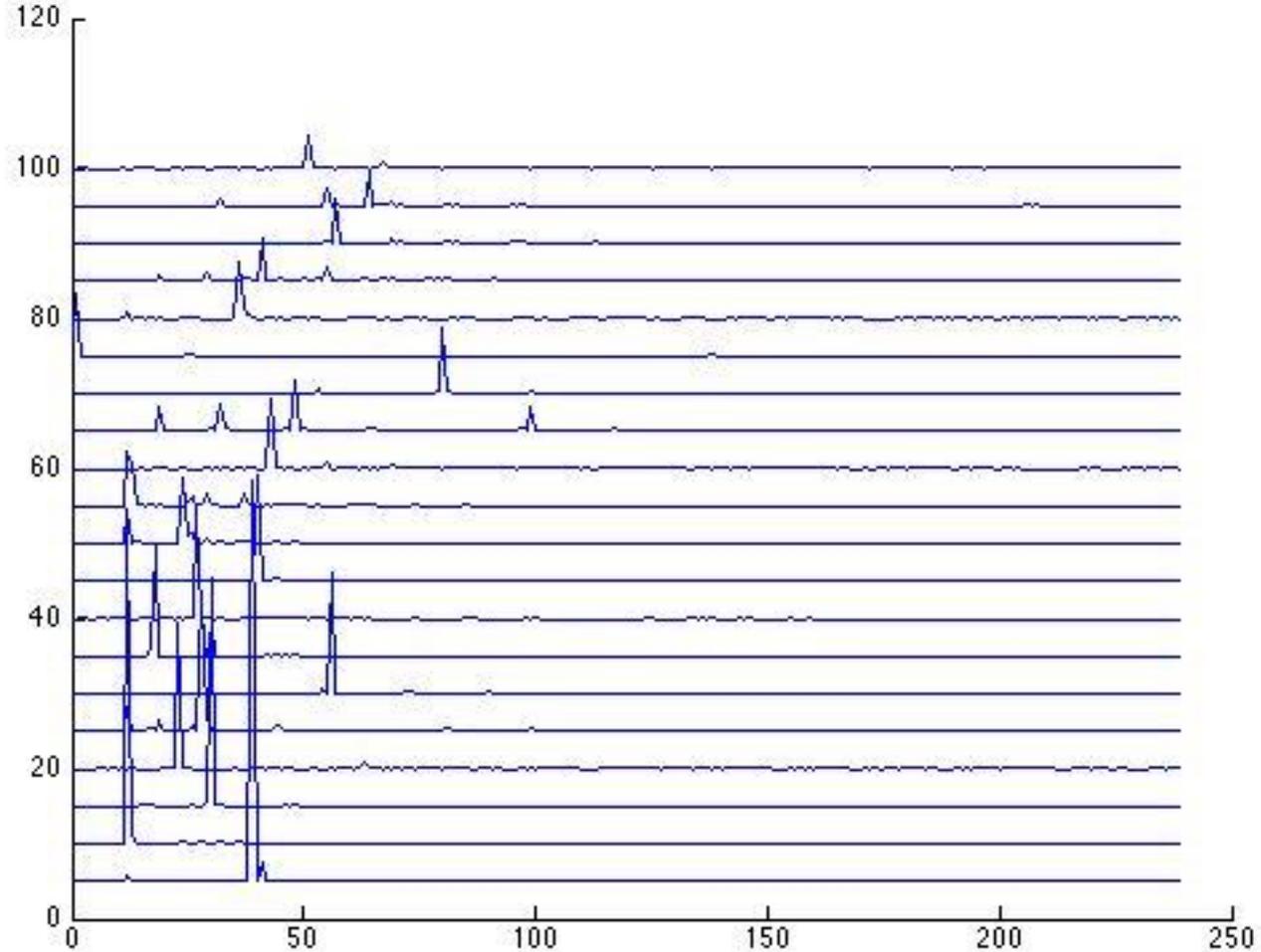
# Non-negative matrix factorization

1. Factors an  $n$ -by- $m$  matrix  $A$  into nonnegative factors  $W$  ( $n$ -by- $k$ ) and  $H$  ( $k$ -by- $m$ ).
2. Starting with random  $W$  and  $H$ , iteratively minimize the residual:

$$D = \sqrt{\frac{\|A - WH\|_F}{nm}}$$

3. Re-normalize  $W$  and  $H$ .

# Non-negative matrix factorization



# Future work

1. Try a different way of measuring non-gaussianity in the ICA algorithm (negentropy)
2. Combine ICA and NNMF?
3. Validate results with laboratory data and analyze multiple aircraft flights
4. Clustering algorithms?

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