

# 14.127 Behavioral Economics. Lecture 9

Xavier Gabaix

April 8, 2004

# 1 Self Control Problems

## 1.1 Hyperbolic discounting

- Do you want a small cookie  $u_s$  now ( $t_0 = 0$ ) or a big cookie  $u_b$  later ( $t_1 = 1$  week)?
- Many people prefer  $(u_s, 0)$  to  $(u_b, t_1)$

- Denote by  $\Delta(t)$  the discount factor applied to time  $t$

- Then

$$\Delta(0) u_s > \Delta(t_1) u_b.$$

- At the same time many people prefer  $(u_s, t)$  to  $(u_b, t + t_1)$  where  $t = 1$  year, and  $t_1 = 1$  day.

$$\Delta(t) u_s < \Delta(t + t_1) u_b.$$

- Thus,

$$\frac{\Delta(t + t_1)}{\Delta(t)} > \frac{u_s}{u_b} > \frac{\Delta(t_1)}{\Delta(0)}$$

- Denote

$$\psi(t) = \frac{\Delta(t + t_1)}{\Delta(t)}$$

and note

$$\psi(t) > \psi(0)$$

- 

$$\frac{\psi(t) - 1}{t_1} = \frac{1}{\Delta(t)} \frac{\Delta(t + t_1) - \Delta(t)}{t_1} \simeq \frac{1}{\Delta(t)} \Delta'(t)$$

- Thus  $\frac{\Delta'(t)}{\Delta(t)}$  is increasing.

- Let us write  $\Delta(t) = e^{-\int_0^t \rho(s) ds}$
- Then  $\frac{\Delta'(t)}{\Delta(t)} = \frac{d}{dt} \ln \Delta(t) = \frac{d}{dt} \left( -\int_0^t \rho(s) ds \right) = -\rho(t)$
- Standard exponential model  $\Delta(t) = e^{-\rho t}$ ,  $\rho(s) = \bar{\rho}$
- Empirical evidence points to  $\rho(t)$  decreasing
- In comparison of today and tomorrow emotions are silent, in comparison of 1000 days from now and 1001 days cognition takes over.

- Maybe people compare ratios: 1 in  $t = 1000$  days vs  $X_t$  in  $t + 1 = 1001$  days. For indifference something like  $X_t \simeq \frac{1001}{1000}$  is plausible.

$$X_t \simeq 1 + \frac{a}{t}$$

for large  $t$ . Clearly  $X_t \rightarrow 1$  as  $t \rightarrow \infty$ .

- But,  $X_t = \frac{\Delta(t)}{\Delta(t+h)} = e^{\int_t^{t+h} \rho(s) ds}$ . Thus  $X_t \rightarrow 1$  iff  $\rho(t) \rightarrow 0$ .
- If  $X(t) = 1 + \frac{a}{t}$ , then  $1 + \frac{a}{t} = X(t) = e^{\int_t^{t+h} \rho(s) ds} \simeq 1 + \int_t^{t+h} \rho(s) ds$ .
- Thus  $\rho(t) \simeq \frac{ah}{t}$  for large  $t$ .

- Thus  $\int_1^t \rho(s) ds \simeq ah \int_1^t \frac{1}{s} ds = ah \ln t = a' \ln t$

- Postulate  $\Delta(t) = e^{-a' \ln(t+1)} = \frac{1}{(1+t)^{a'}}$ .

- That's why this is called hyperbolic discounting

- Quasi-hyperbolic approximation (Phelps and Pollack 1968, Laibson 1997)

$$\Delta(t) = \begin{cases} 1 & \text{for } t = 0 \\ \beta\delta^t & \text{for } t \geq 1 \end{cases}$$

- Typically,  $\beta \leq 1$ .

- Now,

$$\frac{\Delta(1)}{\Delta(0)} = \beta\delta < \delta = \frac{\Delta(2)}{\Delta(1)}$$

- This function is tractable. It does not get  $X_t \rightarrow 1$  though.

## 1.2 Open question

- What is  $t = 1$ ? For cookie it might be 1 hour. For small money it might be 1 week. For macro consumption it is one quarter. Empirically,  $\delta \simeq .98$  in yearly units, and  $\beta \simeq .6$  is usually found for all time units.
- What determines  $\beta$ ? Clearly, the appeal of the good seems to matter. A nice, moist cookie may have a lower  $\beta$ , while a fairly stale plain bagel may have a  $\beta$  close to 1.

## 1.3 Dynamic inconsistency

- Example. Do the task (taxes) at  $t \in \{0, 1, 2\}$  at a cost  $c_0 = 1$ ,  $c_1 = 1.5$ ,  $c_2 = 2.5$ . Take  $\beta = \frac{1}{2}$  and  $\delta = 1$ .
  - Take Self 0 (the decision maker at time 0). Disutility of doing the task at 0 is 1, at 1 is  $\frac{3}{4}$ , at time 2 is 1.25. So, Self 0 would to the task to be done at  $t = 1$ .
  - Self 1 compares time 1 cost of 1.5 with time 2 cost of 1.25 and prefers the task to be done at time 2.
  - Self 2 does the task at the cost 2.5.

- Proposition. If the decision criterion at  $t$  is  $\max \sum_{s \geq 0} \Delta(s) u(c_{t+s})$  then there is dynamic inconsistency unless there exists a constant  $\eta$  such that  $\Delta(s) = \Delta(0) \eta^s$ .
  
- Proof (sketch). Take  $t = 0$  and choose  $c_0$ .
  - Self 0 planned  $c_1, c_2, \dots$  maximizes  $\max \sum_{s \geq 1} \Delta(s) u(c_s)$  over  $c_1, c_2, \dots$  satisfying a budget constraint.
  
  - Self 1 maximizes  $\max \sum_{s \geq 1} \Delta(s-1) u(c_s)$  subject to the same budget constraint
  
  - For the choices to be the same, there must be a constant  $\eta$  s.t.  $(\Delta(s))_{s \geq 1} = \eta (\Delta(s-1))_{s \geq 1}$ , i.e.  $\forall s, \Delta(s) = \eta \Delta(s-1)$ , which implies  $\Delta(s) = \Delta(0) \eta^s$ .

## 1.4 Naives vs sophisticates.

- Sophisticates understand the structure of the game and use backward induction.
  - In the example above a sophisticate understands that time 1 Self is not going to do the taxes and time 2 Self is going to do them, unless Self 0 does. So Self 0 chooses to do his taxes.
  - But the first best would be to force Self 1 to do the taxes.
  - You don't see too much commitment schemes in practice.
  - Maybe they will be developed by the market, or maybe all consumers are naives.

- Naive thinks that future selves will act according to his wishes.
  - Naives don't want commitment devices.
  
- Are people naives or sophisticates?
  - We see some commitment devices, e.g. mortgage is forced savings.
  
- Partial naives (O'Donoghue and Rabin, Doing it now or later, AER 1999)
  - Self  $t$ 's preferences are  $(1, \beta\delta, \beta\delta^2, \dots)$  but Self  $t$  thinks that future selves have  $(1, \hat{\beta}\delta, \hat{\beta}\delta^2, \dots)$ .
  - If  $\hat{\beta} = \beta$  then the agent is sophisticated. If  $\hat{\beta} = 1$  then the agent is naive.

## 1.5 Paradoxes with sophisticated hyperbolics

- Sophisticated hyperbolics have consumption that is a non-monotonic function of their wealth if there are borrowing constraints (Harris and Laibson, “Dynamic Choices of Hyperbolic Consumers”, *Econometrica* 2004)
- This pushes very far the assumption of sophistication.
- That disappears if the environment is noisy enough (that smoothes out the ups and downs)

## 1.6 Continuous time hyperbolics

- Harris and Laibson: “Instantaneous gratification”.

– Agents maximize

$$\max \int_0^{\infty} \Delta(t) u(c_t) dt$$

where  $\Delta(t)$  equals  $\Delta(t - dt)(1 - \rho dt)$  with probability  $1 - \lambda dt$  and equals  $\beta \Delta(t - dt)$  with probability  $\lambda dt$ .

– They have only one shock in a lifetime.

- So:

$$V = E \left[ \int_t^{t+T} e^{-\rho(s-t)} u(c_s) ds + \beta \int_{t+T}^{\infty} e^{-\rho(s-t)} u(c_s) ds \right]$$

where  $T$  is a Poisson( $\lambda$ ) arrival time.

- One can do continuous time Bellman Equations.
- Nice paper by Luttmer and Mariotti (JPE 2003).