

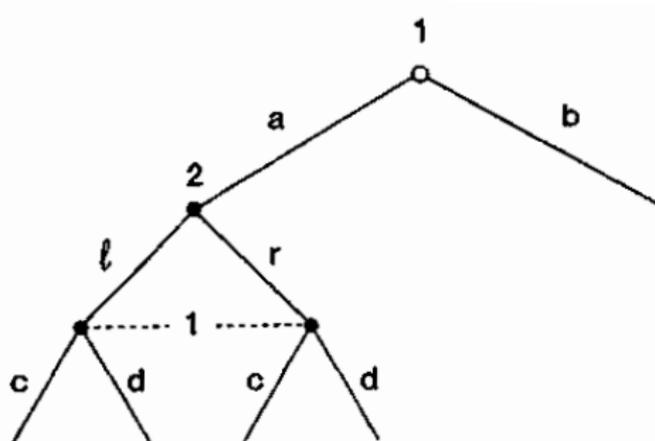
Extensive Form Games

Mihai Manea

MIT

Extensive-Form Games

- ▶ N : finite set of **players**; nature is player $0 \in N$
- ▶ **tree**: order of moves
- ▶ **payoffs** for every player at the terminal nodes
- ▶ **information partition**
- ▶ **actions** available at every information set
- ▶ description of how actions lead to progress in the tree
- ▶ random moves by nature



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Game Tree

- ▶ $(X, >)$: **tree**
- ▶ X : set of nodes
- ▶ $x > y$: node x precedes node y
- ▶ $\phi \in X$: **initial** node, $\phi > x, \forall x \in X \setminus \{\phi\}$
- ▶ $>$ transitive ($x > y, y > z \Rightarrow x > z$) and asymmetric ($x > y \Rightarrow y \not> x$)
- ▶ every node $x \in X \setminus \{\phi\}$ has one immediate predecessor: $\exists x' > x$ s.t. $x'' > x \ \& \ x'' \neq x' \Rightarrow x'' > x'$
- ▶ $Z = \{z \mid \nexists x, z > x\}$: set of **terminal** nodes
- ▶ $z \in Z$ determines a unique path of moves through the tree, payoff $u_i(z)$ for player i

Information Partition

- ▶ **information partition**: a partition of $X \setminus Z$
- ▶ node x belongs to **information set** $h(x)$
- ▶ player $i(h) \in N$ moves at every node x in information set h
- ▶ $i(h)$ knows that he is at some node of h but does not know which one
- ▶ same player moves at all $x \in h$, otherwise players might disagree on whose turn it is
- ▶ $i(x) := i(h(x))$

Actions

- ▶ $A(x)$: set of available **actions** at $x \in X \setminus Z$ for player $i(x)$
- ▶ $A(x) = A(x') =: A(h), \forall x' \in h(x)$ (otherwise $i(h)$ might play an infeasible action)
- ▶ each node $x \neq \phi$ associated with the last action taken to reach it
- ▶ every immediate successor of x labeled with a different $a \in A(x)$ and vice versa
- ▶ move by nature at node x : probability distribution over $A(x)$

Strategies

- ▶ $H_i = \{h | i(h) = i\}$
- ▶ $S_i = \prod_{h \in H_i} A(h)$: set of **pure strategies** for player i
- ▶ $s_i(h)$: action taken by player i at information set $h \in H_i$ under $s_i \in S_i$
- ▶ $S = \prod_{i \in N} S_i$: **strategy profiles**
- ▶ A strategy is a complete **contingent plan** specifying the action to be taken at each information set.
- ▶ **Mixed strategies**: $\sigma_i \in \Delta(S_i)$
- ▶ mixed strategy profile $\sigma \in \prod_{i \in N} \Delta(S_i) \rightarrow$ probability distribution $O(\sigma) \in \Delta(Z)$
- ▶ $u_i(\sigma) = \mathbb{E}_{O(\sigma)}(u_i(z))$

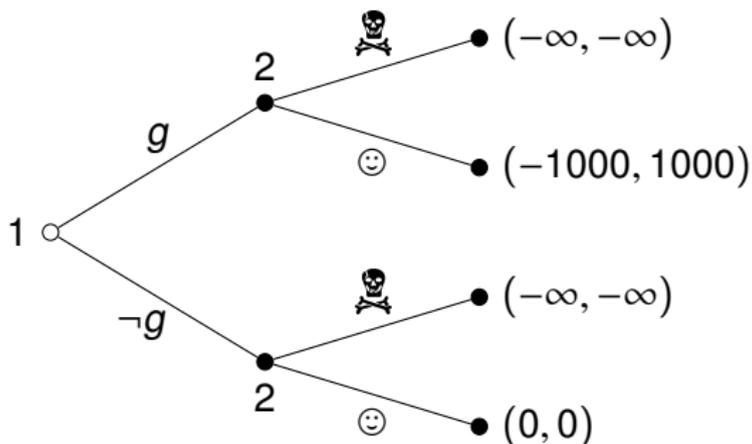
Strategic Form

- ▶ The **strategic form representation** of the extensive form game is the normal form game defined by (N, S, u)
- ▶ A mixed strategy profile is a **Nash equilibrium** of the extensive form game if it constitutes a Nash equilibrium of its strategic form.

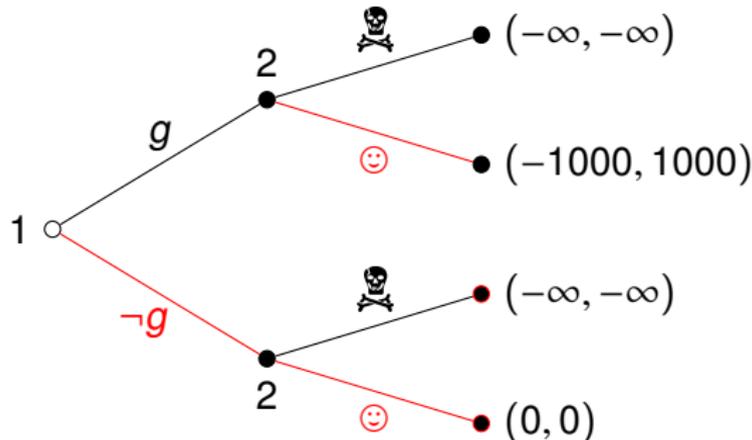
Grenade Threat Game

Player 2 threatens to explode a grenade if player 1 doesn't give him \$1000.

- ▶ Player 1 chooses between g and $\neg g$.
- ▶ Player 2 observes player 1's choice, then decides whether to explode a grenade that would kill both.



Strategic Form Representation



g	$-\infty, -\infty$	$-\infty, -\infty$	$-1000, 1000^*$	$-1000, 1000$
$-g$	$-\infty, -\infty$	$0, 0^*$	$-\infty, -\infty$	$0, 0^*$

Three pure strategy Nash equilibria. Only $(-g, \text{smiley}, \text{smiley})$ is **subgame perfect**.

is not a **credible** threat.

Behavior Strategies

- ▶ $b_i(h) \in \Delta(A(h))$: **behavior strategy** for player $i(h)$ at information set h
- ▶ $b_i(a|h)$: probability of action a at information set h
- ▶ behavior strategy $b_i \in \prod_{h \in H_i} \Delta(A(h))$
- ▶ **independent mixing** at each information set
- ▶ b_i outcome equivalent to the mixed strategy

$$\sigma_i(s_i) = \prod_{h \in H_i} b_i(s_i(h)|h) \quad (1)$$

- ▶ Is every mixed strategy equivalent to a behavior strategy?
- ▶ Yes, under **perfect recall**.

Perfect Recall

No player forgets any information he once had or actions he previously chose.

- ▶ If $x'' \in h(x')$, $x > x'$, and the same player i moves at both x and x' (and thus at x''), then there exists $\hat{x} \in h(x)$ (possibly $\hat{x} = x$) s.t. $\hat{x} > x''$ and the action taken at x along the path to x' is the same as the action taken at \hat{x} along the path to x'' .
- ▶ x' and x'' distinguished by information i does not have, so he cannot have had it at $h(x)$
- ▶ x' and x'' consistent with the same action at $h(x)$ since i must remember his action there
- ▶ Equivalently, every node in $h \in H_i$ must be reached via the same sequence of i 's actions.

Equivalent Behavior Strategies

- ▶ $R_i(h) = \{s_i | h \text{ is on the path of } (s_i, s_{-i}) \text{ for some } s_{-i}\}$: set of i 's pure strategies that do not preclude reaching information set $h \in H_i$
- ▶ Under perfect recall, a mixed strategy σ_i is equivalent to a behavior strategy b_i defined by

$$b_i(a|h) = \frac{\sum_{\{s_i \in R_i(h) | s_i(h)=a\}} \sigma_i(s_i)}{\sum_{s_i \in R_i(h)} \sigma_i(s_i)} \quad (2)$$

when the denominator is positive.

Theorem 1 (Kuhn 1953)

In extensive form games with perfect recall, mixed and behavior strategies are outcome equivalent under the formulae (1) & (2).

Proof

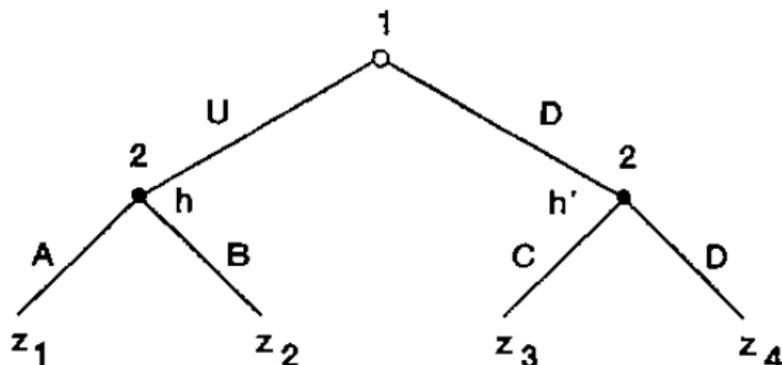
- ▶ $h_1, \dots, h_{\bar{k}}$: player i 's information sets preceding h in the tree
- ▶ Under perfect recall, reaching any node in h requires i to take the same action a_k at each h_k ,

$$R_i(h) = \{s_i | s_i(h_k) = a_k, \forall k = \overline{1, \bar{k}}\}.$$

- ▶ Conditional on getting to h , the distribution of continuation play at h is given by the relative probabilities of the actions available at h under the restriction of σ_i to $R_i(h)$,

$$b_i(a|h) = \frac{\sum_{\{s_i | s_i(h_k) = a_k, \forall k = \overline{1, \bar{k}} \ \& \ s_i(h) = a\}} \sigma_i(s_i)}{\sum_{\{s_i | s_i(h_k) = a_k, \forall k = \overline{1, \bar{k}}\}} \sigma_i(s_i)}.$$

Example

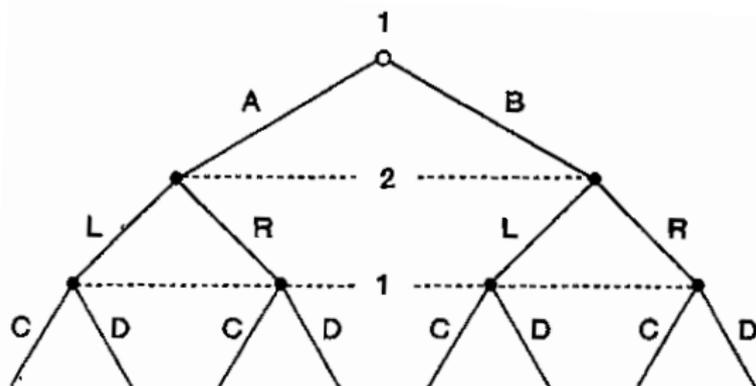


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Figure: Different mixed strategies can generate the same behavior strategy.

- ▶ $S_2 = \{(A, C), (A, D), (B, C), (B, D)\}$
- ▶ Both $\sigma_2 = 1/4(A, C) + 1/4(A, D) + 1/4(B, C) + 1/4(B, D)$ and $\sigma_2 = 1/2(A, C) + 1/2(B, D)$ generate—and are equivalent to—the behavior strategy b_2 with $b_2(A|h) = b_2(B|h) = 1/2$ and $b_2(C|h') = b_2(D|h') = 1/2$.

Example with Imperfect Recall

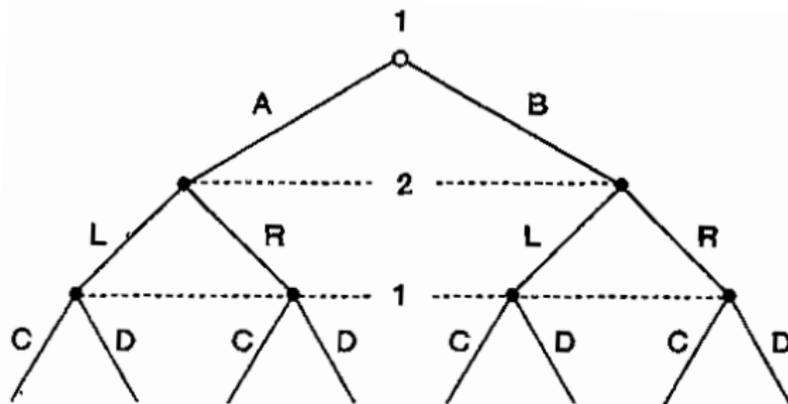


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Figure: Player 1 forgets what he did at the initial node.

- ▶ $S_1 = \{(A, C), (A, D), (B, C), (B, D)\}$
- ▶ $\sigma_1 = 1/2(A, C) + 1/2(B, D) \rightarrow b_1 = (1/2A + 1/2B, 1/2C + 1/2D)$
- ▶ b_1 **not** equivalent to σ_1
- ▶ (σ_1, L) : prob. 1/2 for paths (A, L, C) and (B, L, D)
- ▶ (b_1, L) : prob. 1/4 to paths $(A, L, C), (A, L, D), (B, L, C), (B, L, D)$

Imperfect Recall and Correlations



7 cl fhYgmicZH\Y 'A -H DFYgg" l gYX'k]h' dYfa]gg]cb"

- ▶ Since both A vs. B and C vs. D are choices made by player 1, the strategy σ_1 under which player 1 makes all his decisions at once allows choices at different information sets to be correlated
- ▶ Behavior strategies cannot produce this correlation, because when it comes time to choose between C and D , player 1 has forgotten whether he chose A or B .

Absent Minded Driver

Piccione and Rubinstein (1997)

- ▶ A drunk driver has to take the third out of five exits on the highway (exit 3 has payoff 1, other exits payoff 0).
- ▶ The driver cannot read the signs and forgets how many exits he has already passed.
- ▶ At each of the first four exits, he can choose C (continue) or E (exit). . . imperfect recall: choose same action.
- ▶ C leads to exit 5, while E leads to exit 1.
- ▶ Optimal solution involves randomizing: probability p of choosing C maximizes $p^2(1 - p)$, so $p = 2/3$.
- ▶ “Beliefs” given $p = 2/3$: $(27/65, 18/65, 12/65, 8/65)$
- ▶ E has conditional “expected” payoff of $12/65$, C has 0. Optimal strategy: E with probability 1, inconsistent.

Conventions

- ▶ Restrict attention to games with perfect recall, so we can use mixed and behavior strategies interchangeably.
- ▶ Behavior strategies are more convenient.
- ▶ Drop notation b for behavior strategies and denote by $\sigma_i(a|h)$ the probability with which player i chooses action a at information set h .

Survivor

THAI 21

- ▶ Two players face off in front of 21 flags.
- ▶ Players alternate in picking 1, 2, or 3 flags at a time.
- ▶ The player who successfully grabs the last flag wins.

Game of luck?

Backward Induction

- ▶ An extensive form game has **perfect information** if all information sets are singletons.
- ▶ Can solve games with perfect information using **backward induction**.
- ▶ Finite game $\rightarrow \exists$ penultimate nodes (successors are terminal nodes).
- ▶ The player moving at each penultimate node chooses an action that maximizes his payoff.
- ▶ Players at nodes whose successors are penultimate/terminal choose an optimal action given play at penultimate nodes.
- ▶ Work backwards to initial node. . .

Theorem 2 (Zermelo 1913; Kuhn 1953)

In a finite extensive form game of perfect information, the outcome(s) of backward induction constitutes a pure-strategy Nash equilibrium.

Market Entrance

- ▶ **Incumbent** firm 1 chooses a level of capital K_1 (which is then fixed).
- ▶ A potential **entrant**, firm 2, observes K_1 and chooses its capital K_2 .
- ▶ The profit for firm $i = 1, 2$ is $K_i(1 - K_1 - K_2)$ (firm i produces output K_i , we use earlier demand function).
- ▶ Each firm dislikes capital accumulation by the other.
- ▶ A firm's *marginal* value of capital decreases with the other's.
- ▶ Capital levels are **strategic substitutes**.

Stackelberg Competition

- ▶ Profit maximization by firm 2 requires

$$K_2 = \frac{1 - K_1}{2}.$$

- ▶ Firm 1 **anticipates** that firm 2 will act optimally, and therefore solves

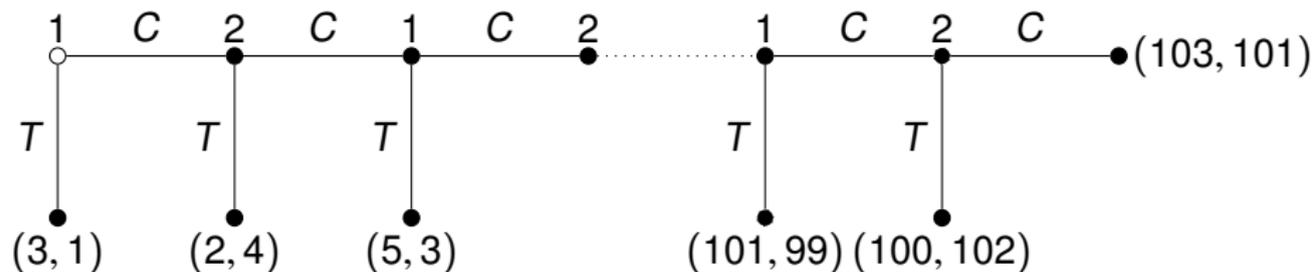
$$\max_{K_1} \left\{ K_1 \left(1 - K_1 - \frac{1 - K_1}{2} \right) \right\}.$$

- ▶ Solution involves $K_1 = 1/2$, $K_2 = 1/4$, $\pi_1 = 1/8$, and $\pi_2 = 1/16$.
- ▶ Firm 1 has **first mover advantage**.
- ▶ In contrast, in the simultaneous move game, $K_1 = 1/3$, $K_2 = 1/3$, $\pi_1 = 1/9$, and $\pi_2 = 1/9$.

Centipede Game

- ▶ Player 1 has two piles in front of her: one contains 3 coins, the other 1.
- ▶ Player 1 can either take the larger pile and give the smaller one to player 2 (T) or push both piles across the table to player 2 (C).
- ▶ Every time the piles pass across the table, one coin is added to each.
- ▶ Players alternate in choosing whether to take the larger pile (T) or trust opponent with bigger piles (C).
- ▶ The game lasts 100 rounds.

What's the backward induction solution?



Chess Players and Backward Induction

Palacios-Huerta and Volij (2009)

- ▶ chess players and college students behave differently in the centipede game.
- ▶ Higher-ranked chess players end the game earlier.
- ▶ All Grandmasters in the experiment stopped at the first opportunity.
- ▶ Chess players are familiar with backward induction reasoning and need less learning to reach the equilibrium.
- ▶ Playing against non-chess-players, even chess players continue in the game longer.
- ▶ In long games, common knowledge of the ability to do complicated inductive reasoning becomes important for the prediction.

Subgame Perfection

- ▶ Backward induction solution is more than a Nash equilibrium.
- ▶ Actions are optimal given others' play—and form an equilibrium—starting at *any* intermediate node: **subgame perfection**. . . rules out non-credible threats.
- ▶ Subgame perfection extends backward induction to imperfect information games.
- ▶ Replace “smallest” subgames with a Nash equilibrium and iterate on the reduced tree (if there are multiple Nash equilibria in a subgame, all players expect same play).

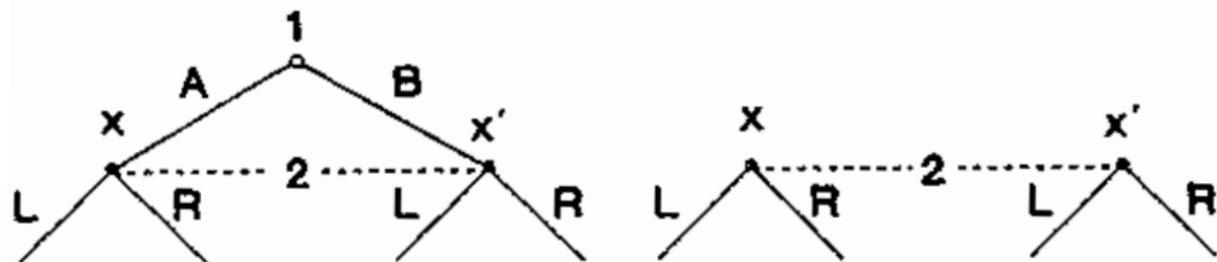
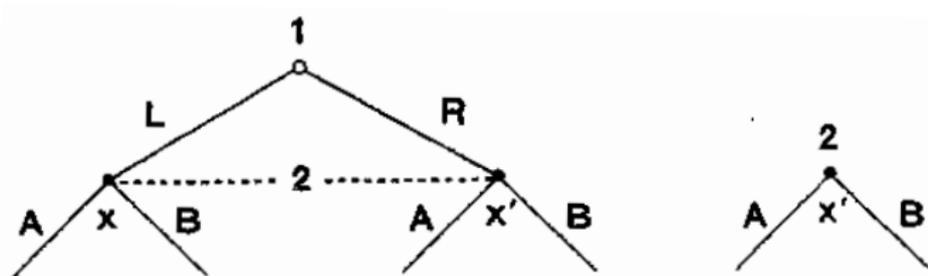
Subgames

Subgame: part of a game that can be analyzed separately; strategically and informationally independent. . . information sets not “chopped up.”

Definition 1

A **subgame** G of an extensive form game T consists of a single node x and *all* its successors in T , with the property that if $x' \in G$ and $x'' \in h(x')$ then $x'' \in G$. The information sets, actions and payoffs in the subgame are inherited from T .

False Subgames



7ci ftYgmcZHYY A +HDYgg"l gYX k Jh dYfa Jggjcb"

Subgame Perfect Equilibrium

σ : behavior strategy in T

- ▶ $\sigma|G$: the strategy profile induced by σ in subgame G of T (start play at the initial node of G , follow actions specified by σ , obtain payoffs from T at terminal nodes)
- ▶ Is $\sigma|G$ a Nash equilibrium of G for any subgame G ?

Definition 2

A strategy profile σ in an extensive form game T is a **subgame perfect equilibrium** if $\sigma|G$ is a Nash equilibrium of G for every subgame G of T .

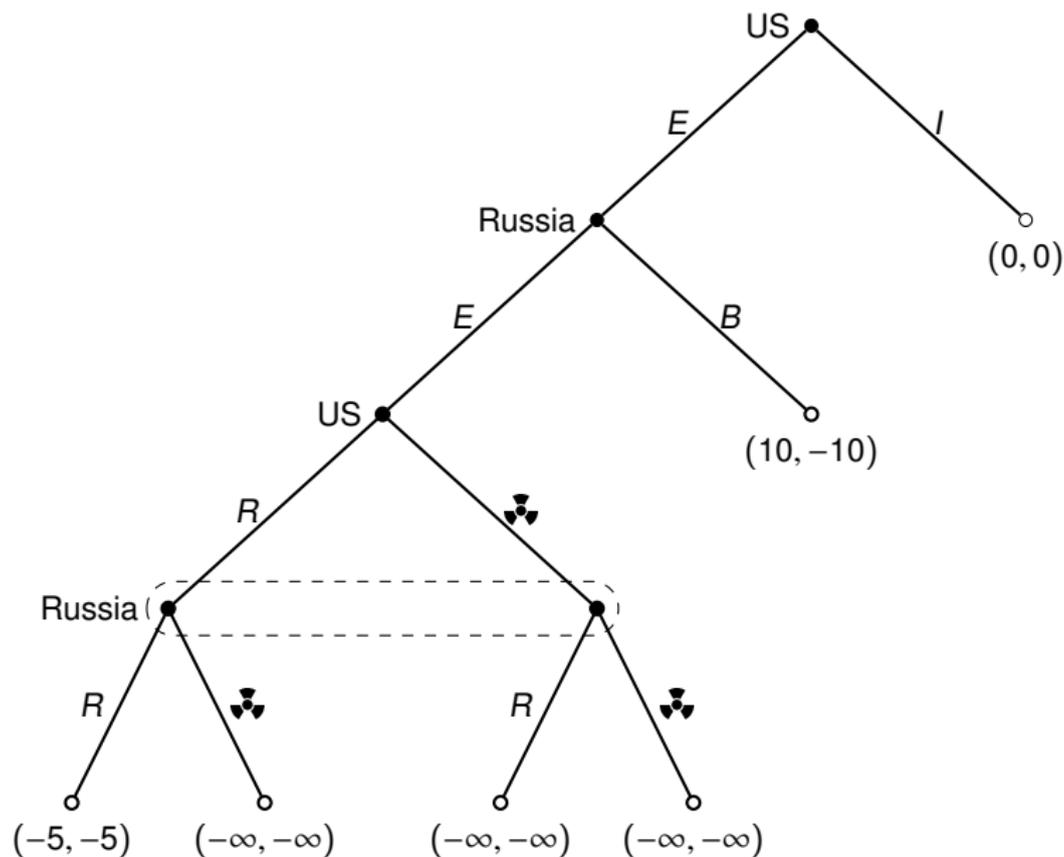
- ▶ Any game is a subgame of itself \rightarrow a subgame perfect equilibrium is a Nash equilibrium.
- ▶ Subgame perfection coincides with backward induction in games of perfect information.

Nuclear Crisis

Russia provokes the US...

- ▶ The U.S. can choose to escalate (E) or end the game by ignoring the provocation (I).
- ▶ If the game escalates, Russia faces a similar choice: to back down (B), but lose face, or escalate (E).
- ▶ Escalation leads to nuclear crisis: a simultaneous move game where each nation chooses to either retreat (R) and lose credibility or detonate (\blacklozenge). Unless both countries retreat, retaliation to the first nuclear strike culminates in nuclear disaster, which is infinitely costly.

The Extensive Form

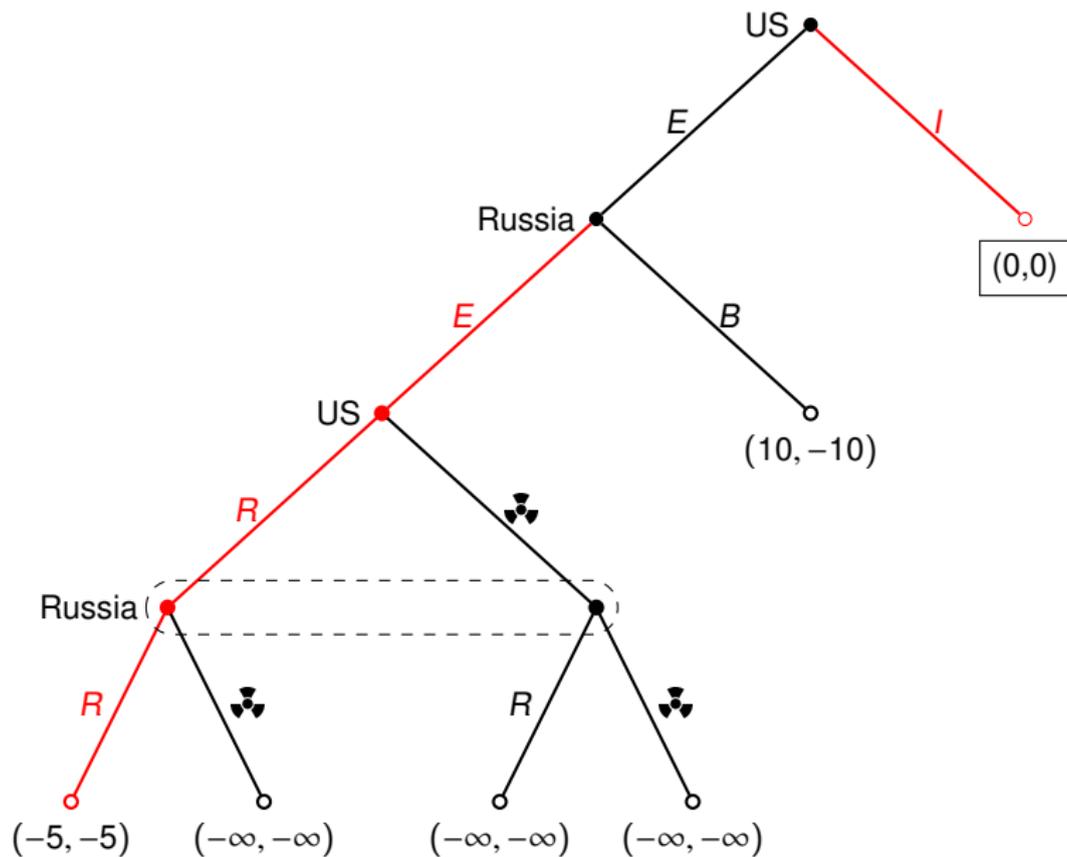


Last Stage

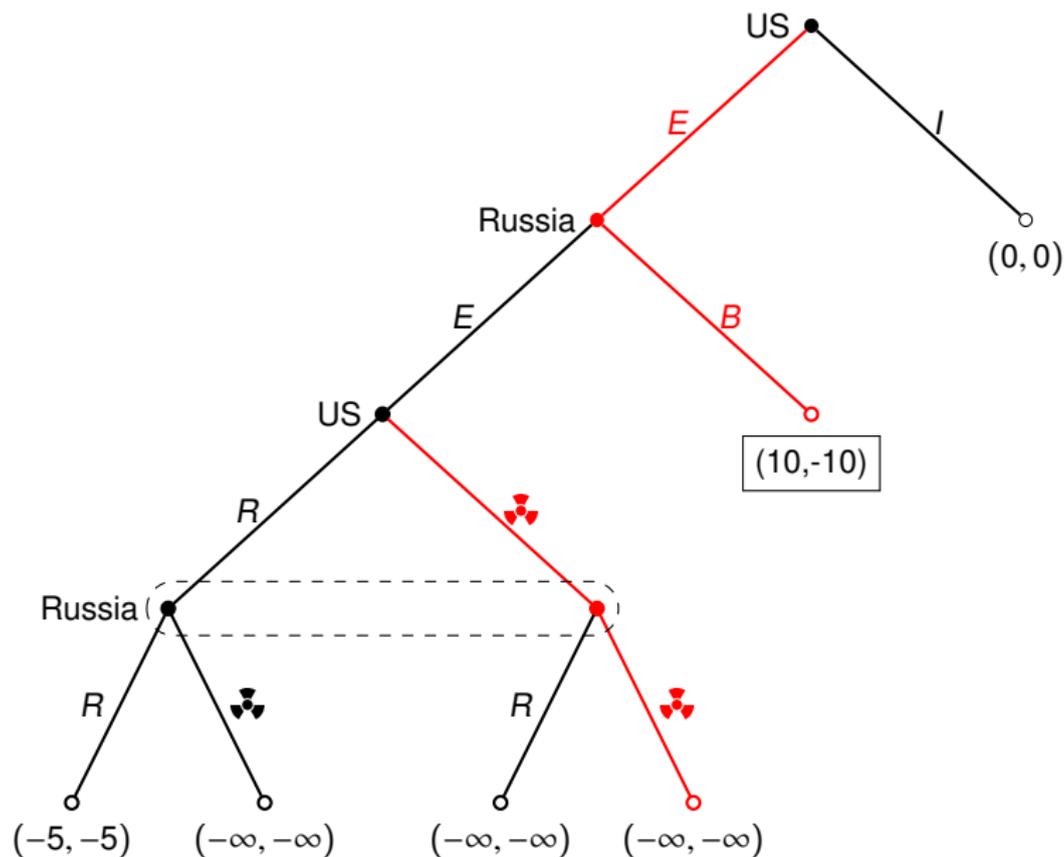
The simultaneous-move game at the last stage has two Nash equilibria.

	R	
R	$-5, 5^*$	$-\infty, -\infty$
	$-\infty, -\infty$	$-\infty, -\infty^*$

One Subgame Perfect Equilibrium



Another Subgame Perfect Equilibrium



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14.16 Strategy and Information

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