

32. STOKES' THEOREM

Definition 32.1. We say that a vector field

$$\vec{F}: A \longrightarrow \mathbb{R}^m,$$

has **compact support** if there is a compact subset $K \subset A$ such that

$$\vec{F}(\vec{x}) = \vec{0},$$

for every $\vec{x} \in A - K$.

If $S \subset \mathbb{R}^3$ is a smooth manifold (possibly with boundary) then we will call S a *surface*. An *orientation* is a “continuous” choice of unit normal vector. Not every surface can be oriented. Consider for example the Möbius band, which is obtained by taking a piece of paper and attaching it to itself, except that we add a twist.

Theorem 32.2 (Stokes’ Theorem). *Let $S \subset \mathbb{R}^3$ be a smooth oriented surface with boundary and let $\vec{F}: S \longrightarrow \mathbb{R}^3$ be a smooth vector field with compact support.*

Then

$$\iint_S \operatorname{curl} \vec{F} \cdot d\vec{S} = \int_{\partial S} \vec{F} \cdot d\vec{s},$$

where ∂S is oriented compatibly with the orientation on S .

Example 32.3. *Let S be a smooth 2-manifold that looks like a pair of pants. Choose the orientation of S such that the normal vector is pointing outwards. There are three oriented curves C_1 , C_2 and C_3 (the two legs and the waist). Suppose that we are given a vector field \vec{B} with zero curvature. Then (32.2) says that*

$$\int_{C_3} \vec{B} \cdot d\vec{s} + \int_{C'_1} \vec{B} \cdot d\vec{s} + \int_{C'_2} \vec{B} \cdot d\vec{s} = \iint_S \operatorname{curl} \vec{B} \cdot d\vec{S} = 0.$$

Here C'_1 and C'_2 denote the curves C_1 and C_2 with the opposite orientation. In other words,

$$\int_{C_3} \vec{B} \cdot d\vec{s} = \int_{C_1} \vec{B} \cdot d\vec{s} + \int_{C_2} \vec{B} \cdot d\vec{s}.$$

Proof of (32.2). We prove this in three steps, in very much the same way as we proved Green’s Theorem.

Step 1: We suppose that $M = \mathbb{H}^2 \subset \mathbb{R}^2 \subset \mathbb{R}^3$, where the plane is the xy -plane. In this case, we can take $\hat{n} = \hat{k}$, and this induces the standard orientation of the boundary. Note that

$$\operatorname{curl} \vec{F} \cdot \hat{n} = \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y},$$

and so the result reduces to Green's Theorem. This completes step 1.

Step 2: We suppose that there is a compact subset $K \subset S$ and a parametrisation

$$\vec{g}: \mathbb{H}^2 \cap U \longrightarrow S \cap W,$$

which is compatible with the orientation, such that

- (1) $\vec{F}(\vec{x}) = \vec{0}$ if $\vec{x} \in S - K$, and
- (2) $K \subset S \cap W$.

Define a vector field $\vec{G}: \mathbb{H}^2 \longrightarrow \mathbb{R}^2$ by the rule

$$\vec{G}(u, v) = \begin{cases} \vec{F}(\vec{g}(u, v)) \cdot D\vec{g}(u, v) & (u, v) \in U \\ \vec{0} & (u, v) \notin U. \end{cases}$$

Note that

$$\begin{aligned} G_1(u, v) &= F_1 \frac{\partial x}{\partial u} + F_2 \frac{\partial y}{\partial u} + F_3 \frac{\partial z}{\partial u} \\ G_2(u, v) &= F_1 \frac{\partial x}{\partial v} + F_2 \frac{\partial y}{\partial v} + F_3 \frac{\partial z}{\partial v}. \end{aligned}$$

Using step 1, it is enough to prove:

Claim 32.4.

- (1)

$$\iint_S \text{curl } \vec{F} \cdot d\vec{S} = \iint_{\mathbb{H}^2} \left(\frac{\partial G_2}{\partial u} - \frac{\partial G_1}{\partial v} \right) du dv.$$

- (2)

$$\iint_{\partial S} \vec{F} \cdot d\vec{s} = \iint_{\partial \mathbb{H}^2} \vec{G} \cdot ds.$$

Proof of (32.4). Note that

$$\begin{aligned} \text{curl } \vec{F} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} \\ &= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} - \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \hat{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}. \end{aligned}$$

On the other hand,

$$\begin{aligned} \frac{\partial \vec{g}}{\partial u} &= \frac{\partial x}{\partial u} \hat{i} + \frac{\partial y}{\partial u} \hat{j} + \frac{\partial z}{\partial u} \hat{k} \\ \frac{\partial \vec{g}}{\partial v} &= \frac{\partial x}{\partial v} \hat{i} + \frac{\partial y}{\partial v} \hat{j} + \frac{\partial z}{\partial v} \hat{k}. \end{aligned}$$

It follows that

$$\begin{aligned} \frac{\partial \vec{g}}{\partial u} \times \frac{\partial \vec{g}}{\partial v} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix} \\ &= \frac{\partial(y, z)}{\partial(u, v)} \hat{i} - \frac{\partial(x, z)}{\partial(u, v)} \hat{j} + \frac{\partial(x, y)}{\partial(u, v)} \hat{k}. \end{aligned}$$

So,

$$\text{curl } \vec{F} \cdot \frac{\partial \vec{g}}{\partial u} \times \frac{\partial \vec{g}}{\partial v} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \frac{\partial(y, z)}{\partial(u, v)} + \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \frac{\partial(x, z)}{\partial(u, v)} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \frac{\partial(x, y)}{\partial(u, v)}.$$

On the other hand, if one looks at the proof of the second step of Green's theorem, we see that

$$\frac{\partial G_2}{\partial u} - \frac{\partial G_1}{\partial v},$$

is also equal to the RHS (in fact, what we calculated in the proof of Green's theorem was the third term of the RHS; by symmetry the other two terms have the same form). This is (1).

For (2), let's parametrise $\partial\mathbb{H}^2 \cap U$ by $\vec{x}(u) = (u, 0)$ and $\partial S \cap W$ by $\vec{s}(u) = \vec{g}(\vec{x}(u))$. Then

$$\begin{aligned} \int_{\partial S} \vec{F} \cdot d\vec{s} &= \int_{\partial S \cap W} \vec{F} \cdot d\vec{s} \\ &= \int_a^b \vec{F}(\vec{s}(u)) \cdot \vec{s}'(u) du \\ &= \int_a^b \vec{F}(\vec{g}(\vec{x}(u))) \cdot D\vec{g}(\vec{x}(u))\vec{x}'(u) du \\ &= \int_a^b \vec{G}(\vec{x}(u)) \cdot \vec{x}'(u) du \\ &= \int_{\partial\mathbb{H}^2 \cap U} \vec{G} \cdot d\vec{s} \\ &= \int_{\partial\mathbb{H}^2} \vec{G} \cdot d\vec{s}, \end{aligned}$$

and this is (2). □

This completes step 2.

Step 3: We again use partitions of unity. It is straightforward to cover the bounded set K by finitely many compact subsets K_1, K_2, \dots, K_k , such that given any smooth vector field which is zero outside K_i , then

the conditions of step 2 hold. By using a partition of unity, we can find smooth functions $\rho_1, \rho_2, \dots, \rho_k$ such that ρ_i is zero outside K_i and

$$1 = \sum_{i=1}^k \rho_i.$$

Multiplying both sides of this equation by \vec{F} , we have

$$\vec{F} = \sum_{i=1}^k \vec{F}_i,$$

where $\vec{F}_i = \rho_i \vec{F}$ is a smooth vector field, which is zero outside K_i . In this case

$$\begin{aligned} \iint_S \operatorname{curl} \vec{F} \cdot d\vec{S} &= \sum_{i=1}^k \iint_S \operatorname{curl} \vec{F}_i \cdot d\vec{S} \\ &= \sum_{i=1}^k \int_{\partial M} \vec{F}_i \cdot d\vec{s} \\ &= \int_{\partial M} \vec{F} \cdot d\vec{s}. \end{aligned}$$

□

MIT OpenCourseWare
<http://ocw.mit.edu>

18.022 Calculus of Several Variables
Fall 2010

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.