

## Lecture 28

The  $H_{DR}^k$  are finite-dimensional.

### Poincare Duality

Make a pairing  $P : \Omega^k \times \Omega^{n-k} \rightarrow \mathbb{C}$  given by

$$P(\alpha, \beta) = \int_X \alpha \wedge \beta$$

If  $\alpha$  is exact and  $\beta$  closed then  $P(\alpha, \beta) = 0$ , since  $\alpha = d\omega$ ,  $d\beta = 0$  and  $\alpha \wedge \beta = d\omega \wedge \beta = d(\omega \wedge \beta)$ . By Stokes  $\int \alpha \wedge \beta$  is thus 0.  $P$  induces a pairing in cohomology,  $P^\sharp : H_{DR}^k \times H_{DR}^{n-k} \rightarrow \mathbb{C}$ .

**Theorem (Poincare).** *This is a non-degenerate pairing.*

We give a Hodge Theoretic Proof. First,

**Lemma.**  $\delta : \Omega^k \rightarrow \Omega^{k-1}$  is given by  $\delta = (-1)^k *^{-1} d*$

*Proof.* Let  $\delta_1 = (-1)^k *^{-1} d*$ , we want to show that  $\delta = \delta_1$ . Let  $\alpha \in \Omega^{k-1}$  and  $\beta \in \Omega^{n-k}$  then

$$\begin{aligned} d(\alpha \wedge \bar{\beta}) &= d\alpha \wedge \bar{\beta} + (-1)^{k-1} \alpha \wedge d*\bar{\beta} \\ &= d\alpha \wedge *\bar{\beta} + (-1)^{k-1} \alpha \wedge *( *^{-1} d*\bar{\beta}) \\ &= d\alpha \wedge *\bar{\beta} - \alpha \wedge *(\bar{\delta}_1 \bar{\beta}) \end{aligned}$$

Now integrate and apply Stokes

$$\int d\alpha \wedge *\bar{\beta} = \int \alpha \wedge *\delta_1 \bar{\beta}$$

so  $\langle d\alpha, \beta \rangle = \langle \alpha, \delta_1 \bar{\beta} \rangle$  and  $\delta_1 = d^t = \delta$ . □

**Corollary.**  $*\mathcal{H}^k = \mathcal{H}^{n-k}$

*Proof.* Take  $\alpha \in \mathcal{H}^k$ . We'll show that  $d*\alpha = 0$ . This happens iff  $*^{-1}d*\alpha = \pm\delta\alpha$ . Since  $\delta\alpha = 0$ ,  $d*\alpha = 0$ . It is similarly easy to check that  $\delta*\alpha = 0$ . □

*Proof of Poincare Duality.* It suffices to check that the pairing  $P : \mathcal{H}^k \times \mathcal{H}^{n-k} \rightarrow \mathbb{C}$  given by  $\alpha, \beta \mapsto \int_X \alpha \wedge \beta$  is non-degenerate.

Suppose  $P(\alpha, \beta) = 0$  for all  $\beta$ . Take  $\beta = *\bar{\alpha}$ . Then

$$P(\alpha, \beta) = \int_X \alpha \wedge *\bar{\alpha} = \langle \alpha, \alpha \rangle = 0$$

so this would imply that  $\alpha = 0$ . □

## A Review of Kaehlerian Linear Algebra

**Definition.**  $V = V^{2n}$  a vector space over  $\mathbb{R}$ ,  $B_s$  a non-degenerate alternating bilinear form on  $V$ ,  $J : V \rightarrow V$  a linear map such that  $J^2 = -I$ .  $B_s$  and  $J$  are compatible if  $B_s(Jv, Jw) = B_s(v, w)$ .

**Lemma.** *If  $B_s$  and  $J$  are compatible if and only if the bilinear form  $B_r(v, w) = B_s(v, Jw)$  is symmetric. (Here  $B_r$  is a Riemannian metric)*

$J, B_s$  Kaehler implies that  $B_r$  is positive definite.

Notice that  $B_r(Jv, Jw) = B_s(Jv, J^2w) = B_s(v, Jw) = B_r(v, w)$  so that  $B_r$  and  $J$  are compatible. And also notice that  $B_r(Jv, w) = B_s(Jv, Jw) = B_s(v, w)$ . Let  $J^t$  be the transpose of  $J$  with respect to  $B_r$ . Then

$$B_r(Jv, Jw) = B_r(v, J^t Jw) = B_r(v, w)$$

so  $J^t J = I$  and  $J^t = -J$ .

## $B_r, B_s, J$ in Coordinates

Let  $e \in V$  such that  $B_r(e, e) = 1$ , and set  $f = Je$ , and  $e = -Jf$ . Then

$$B_r(e, e) = 1 \quad B_s(e, f) = 1$$

Take  $V_1 = \text{span}\{e, f\}$ . This is a  $J$ -invariant subspace. If we then take

$$V_1^\perp = \text{orthocomplement of } V_1 \text{ w.r.t } B_r$$

then for  $v \in V_1, w \in V_1^\perp$ ,  $0 = B_r(Jv, w) = B_s(v, w)$ , so  $V_1^\perp$  is the symplectic orthocomplement of  $V_1$  with respect to  $B_s$ .

Applying induction we get a decomposition

$$V = V_1 \oplus V_2 \oplus \cdots \oplus V_n$$

where  $V_i = \text{span}\{e_i, f_i\}$  such that  $e_1, f_1, \dots, e_n, f_n$  is an oriented orthonormal basis of  $V$  with respect to  $B_r$  and a Darboux basis with respect to  $B_s$ . Note that  $Je_i = f_i$  and  $Jf_i = -e_i$

### 5.0.3 $B_r, B_s$ and $J$ on $\Lambda^k(V)$

$\omega = \sum e_i \wedge f_i$  is the symplectic element in  $\Lambda^2(V)$  and  $\Omega = \omega^n/n! = e_1 \wedge f_1 \wedge \cdots \wedge e_n \wedge f_n$  is the symplectic volume for and Riemannian volume form.

On decomposable elements,  $\alpha = v_1 \wedge \cdots \wedge v_k$  and  $\beta = w_1 \wedge \cdots \wedge w_k$  and

$$B_r(\alpha, \beta) = \det(B_r(v_i, w_j)) \quad B_s(\alpha, \beta) = \det(B_s(v_i, w_j))$$

and we can define

$$J\alpha = Jv_1 \wedge \cdots \wedge Jv_k$$

Notice that

$$B_r(\alpha, \beta) = \det(B_r(v_i, w_j)) = \det B_s(v_i, Jw_j) = B_s(\alpha, J\beta)$$

and furthermore, it is easy to check that  $B_r(J\alpha, J\beta) = B_r(\alpha, \beta)$ ,  $B_s(J\alpha, J\beta) = B_s(\alpha, \beta)$ ,  $J^2 = (-1)^k Id$  and if  $J^t : \Lambda^k \rightarrow \Lambda^k$  is the  $B_r$ -transpose of  $J$ , then  $J^t = (-1)^k J$ .

## The Star Operators

These are  $*_r$  and  $*_s$ , the Riemannian and symplectic star operators, respectively. Let  $\Omega$  be the symplectic (and Riemannian) volume form. For  $\alpha, \beta \in \Lambda^k$  we have

$$\alpha \wedge *_r \beta = B_r(\alpha, \beta)\Omega = B_s(\alpha, J\beta) = \alpha \wedge *_s J\beta$$

so

$$*_r = *_s J$$

Also, notice that

$$J\alpha \wedge *_r J\beta = B_r(J\alpha, J\beta)\Omega = B_r(\alpha, \beta)\Omega = \alpha \wedge *_r \beta$$

on the other hand  $J\Omega = \Omega$ , so

$$\alpha \wedge *_r \beta = B_r(\alpha, \beta)\Omega = J\alpha \wedge *_r J *_r \beta$$

so  $*_r J = J *_r$  and since  $*_r = *_s J$  we have  $J *_s = *_s J$ .

## Structure of $\Lambda(V)$

We have a symplectic element  $\omega = \sum e_i \wedge f_i \in \Omega^2$ . From this, we can define a mapping  $L : \Lambda^k \rightarrow \Lambda^{k+2}$  given by  $\alpha \mapsto \omega \wedge \alpha$ . Note that

$$LJ\alpha = \omega \wedge J\alpha = J(\omega \wedge \alpha) = JL\alpha$$

so that  $[J, L] = 0$ .

Similarly for  $L^t : \Lambda^{k+2} \rightarrow \Lambda^k$ , the symplectic transpose given by  $L^t = *_s L *_s$ . Since  $*_s, L$  commute with the  $J$  map, so does  $L^t$ , so  $[J, L^t] = 0$ .

Notice that

$$B_r(L\alpha, \beta) = B_s(L\alpha, J\beta) = B_s(\alpha, L^t J\beta) = B_s(\alpha, JL^t \beta) = B_r(\alpha, L^t \beta)$$

so  $L^t$  is also the Riemannian transpose.

From  $L, L^t$  we get a representation of  $SL(2, \mathbb{R})$  on  $\Lambda(V)$  and this representation is  $J$ -invariant.