

MATH 18.152 - PROBLEM SET 8

18.152 Introduction to PDEs, Fall 2011

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Problem Set 8, Due: at the start of class on 11-10-11

I. Consider the energy-momentum tensor corresponding to the linear wave equation:  $T_{\mu\nu} \stackrel{\text{def}}{=} \partial_\mu\phi\partial_\nu\phi - \frac{1}{2}m_{\mu\nu}(m^{-1})^{\alpha\beta}\partial_\alpha\phi\partial_\beta\phi$ , and assume that  $|\nabla_{t,x}\phi| \stackrel{\text{def}}{=} \sqrt{(\partial_t\phi)^2 + \sum_{i=1}^n(\partial_i\phi)^2} \neq 0$ . Here,  $(m^{-1})^{\mu\nu} = \text{diag}(-1, 1, 1, \dots, 1)$  is the standard Minkowski metric on  $\mathbb{R}^{1+n}$ . Let  $X, Y$  be future-directed timelike vectors (i.e.,  $m(X, X) < 0, m(Y, Y) < 0, X^0 > 0$ , and  $Y^0 > 0$ ). Show that

$$(0.0.1) \quad T(X, Y) \stackrel{\text{def}}{=} T_{\alpha\beta}X^\alpha Y^\beta > 0.$$

**Hint:** First show that if  $L$  and  $\underline{L}$  are any pair of null vectors normalized by  $m(L, \underline{L}) = -2$ , then  $T(L, L) \geq 0, T(\underline{L}, \underline{L}) \geq 0, T(L, \underline{L}) \geq 0$ , and that at least one of these three must be non-zero. To prove these facts, it might be helpful to supplement the vectors  $L$  and  $\underline{L}$  with some vectors  $e_{(1)}, \dots, e_{(n-1)}$  in order to form a null frame  $\mathcal{N} \stackrel{\text{def}}{=} \{L, \underline{L}, e_{(1)}, \dots, e_{(n-1)}\}$ ; the calculations will be much easier to do relative to the basis  $\mathcal{N}$  compared to the standard basis for  $\mathbb{R}^{1+n}$ . Recall that  $\mathcal{N} \stackrel{\text{def}}{=} \{L, \underline{L}, e_{(1)}, \dots, e_{(n-1)}\}$  is any basis for  $\mathbb{R}^{1+n}$  such that  $0 = m(L, L) = m(\underline{L}, \underline{L}) = m(L, e_{(i)}) = m(\underline{L}, e_{(i)})$  for  $1 \leq i \leq n-1$ , such that  $m(L, \underline{L}) = -2$ , such that  $m(e_{(i)}, e_{(j)}) = 1$  if  $i = j$ , and such that  $m(e_{(i)}, e_{(j)}) = 0$  if  $i \neq j$ ; as we discussed in class, given any null pair  $L, \underline{L}$  normalized by  $m(L, \underline{L}) = -2$ , there exists such a null frame  $\mathcal{N}$  containing  $L$  and  $\underline{L}$ . Recall also that  $(m^{-1})^{\mu\nu} = -\frac{1}{2}L^\mu\underline{L}^\nu - \frac{1}{2}\underline{L}^\mu L^\nu + \not{m}^{\mu\nu}$ , where  $\not{m}^{\mu\nu}$  is positive definite on  $\text{span}\{e_{(1)}, \dots, e_{(n-1)}\}$ ,  $\not{m}^{\mu\nu}$  vanishes on  $\text{span}\{L, \underline{L}\}$ , and  $\not{m}(L, e_{(i)}) = \not{m}(\underline{L}, e_{(i)}) = 0$  for  $1 \leq i \leq n-1$ .

To tackle the case of general  $X$  and  $Y$ , use Problem V from last week.

**Remark 0.0.1.** Inequality (0.0.1) also holds if  $X, Y$  are past-directed timelike vectors (i.e.,  $m(X, X) < 0, m(Y, Y) < 0, X^0 < 0$ , and  $Y^0 < 0$ ).

II. Consider the Morawetz vectorfield  $\overline{K}^\mu$  on  $R^{1+3}$  defined by

$$(0.0.2) \quad \overline{K}^0 = 1 + t^2 + (x^1)^2 + (x^2)^2 + (x^3)^2,$$

$$(0.0.3) \quad \overline{K}^j = 2tx^j, \quad (j = 1, 2, 3).$$

a) Show that  $\overline{K}$  is future-directed and timelike. Above,  $(t, x^1, x^2, x^3)$  are the standard coordinates on  $R^{1+3}$ .

b) Show that

$$(0.0.4) \quad \partial_\mu\overline{K}_\nu + \partial_\nu\overline{K}_\mu = 4tm_{\mu\nu}, \quad (\mu, \nu = 0, 1, 2, 3),$$

where  $m_{\mu\nu}$  denotes the Minkowski metric.

**Remark 0.0.2.**  $\bar{K}$  is said to be a *conformal Killing field* of the Minkowski metric because the right-hand side of (0.0.4) is proportional to  $m_{\mu\nu}$ .

c) Show that

$$(0.0.5) \quad m_{\mu\nu}T^{\mu\nu} = 0,$$

where  $T^{\mu\nu} \stackrel{\text{def}}{=} (m^{-1})^{\mu\alpha}(m^{-1})^{\nu\beta}T_{\alpha\beta}$  is the energy-momentum tensor from Problem I with its indices raised. Note that the formula (0.0.5) only holds in 1 + 3 spacetime dimensions.

d) Show that  $\partial_\mu(\bar{K})J^\mu = 0$  whenever  $\phi$  is a solution to the linear wave equation  $(m^{-1})^{\mu\nu}\partial_\mu\phi\partial_\nu\phi = 0$ , where

$$(0.0.6) \quad (\bar{K})J^\mu \stackrel{\text{def}}{=} -T^{\mu\nu}\bar{K}_\nu.$$

e) Show that

$$(0.0.7) \quad (\bar{K})J^0 = \frac{1}{4}\left\{[1 + (t + r)^2](\nabla_L\phi)^2 + [1 + (t - r)^2](\nabla_{\underline{L}}\phi)^2 + 2[1 + t^2 + r^2] \not{m}^{\mu\nu}\partial_\mu\phi\partial_\nu\phi\right\}.$$

Above,  $(m^{-1})^{\mu\nu} = -\frac{1}{2}L^\mu\underline{L}^\nu - \frac{1}{2}\underline{L}^\mu L^\nu + \not{m}^{\mu\nu}$  is the standard null decomposition of  $(m^{-1})^{\mu\nu}$  from class. In particular,  $L^\mu = (1, \frac{x^1}{r}, \frac{x^2}{r}, \frac{x^3}{r})$ ,  $\underline{L}^\mu = (1, -\frac{x^1}{r}, -\frac{x^2}{r}, -\frac{x^3}{r})$ ,  $\nabla_L\phi = \partial_t\phi + \partial_r\phi$ ,  $\nabla_{\underline{L}}\phi = \partial_t\phi - \partial_r\phi$ , and  $\not{m}^{\mu\nu}\partial_\mu\phi\partial_\nu\phi$  is the square of the Euclidean norm of the *angular* derivatives of  $\phi$ . Here,  $r \stackrel{\text{def}}{=} \sqrt{(x^1)^2 + (x^2)^2 + (x^3)^2}$  denotes the standard spherical coordinate on  $\mathbb{R}^3$ , and  $\partial_r$  denotes the standard radial derivative.

**Hint:** The following expansions in terms of  $L$  and  $\underline{L}$  may be very helpful:

$$(0.0.8) \quad \bar{K}^\mu = \frac{1}{2}\left\{[1 + (r + t)^2]L^\mu + [1 + (r - t)^2]\underline{L}^\mu\right\},$$

$$(0.0.9) \quad (1, 0, 0, 0) = \frac{1}{2}(L^\mu + \underline{L}^\nu),$$

$$(0.0.10) \quad \begin{aligned} (\bar{K})J^0 &= T(\bar{K}, \frac{1}{2}(L + \underline{L})) \\ &= \frac{1}{4}\left\{[1 + (r + t)^2]T(L, L) + [1 + (r - t)^2]T(\underline{L}, \underline{L}) + ([1 + (r + t)^2] + [1 + (r - t)^2])T(L, \underline{L})\right\}. \end{aligned}$$

f) Finally, with the help of the vectorfield  $(\bar{K})J^\mu$ , apply the divergence theorem on an appropriately chosen spacetime region and use the previous results to derive the following conservation law for smooth solutions to the linear wave equation  $(m^{-1})^{\mu\nu}\partial_\mu\phi\partial_\nu\phi = 0$  :

(0.0.11)

$$\int_{\mathbb{R}^3} \frac{1}{4} \left\{ [1 + (t+r)^2] (\nabla_L \phi(t, x))^2 + [1 + (t-r)^2] (\nabla_{\underline{L}} \phi(t, x))^2 + 2[1 + t^2 + r^2] \not{m}^{\mu\nu} \partial_\mu \phi(t, x) \partial_\nu \phi(t, x) \right\} d^3x$$

$$= \int_{\mathbb{R}^3} \frac{1}{4} \left\{ [1 + r^2] (\nabla_L \phi(0, x))^2 + [1 + r^2] (\nabla_{\underline{L}} \phi(0, x))^2 + 2[1 + r^2] \not{m}^{\mu\nu} \partial_\mu \phi(0, x) \partial_\nu \phi(0, x) \right\} d^3x.$$

For simplicity, at each fixed  $t$ , you may assume that there exists an  $R > 0$  such that  $\phi(t, x)$  vanishes whenever  $|x| \geq R$ .

**Remark 0.0.3.** Note that the right-hand side of (0.0.11) can be computed in terms of the initial data alone. Note also that the different *null derivatives* of  $\phi$  appearing on the left-hand side of (0.0.11) carry different weights. In particular,  $\nabla_L \phi$  and the angular derivatives of  $\phi$  have larger weights than  $\nabla_{\underline{L}} \phi$ . These larger weights are strongly connected to the following fact, whose full proof requires additional methods going beyond this course:  $\nabla_L \phi$  and the angular derivatives of  $\phi$  decay faster in  $t$  compared to  $\nabla_{\underline{L}} \phi$ .

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