

A few important PDEs

constant coefficients = 1 (one of several possible examples of)
variable coefficients = $c(\mathbf{x})$

Poisson's equation:

$$\nabla^2 u = f$$

example: f = charge density,
 u = -electric potential
 example: f = heat source/sink rate
 u = steady-state temperature
 example: f = solute source/sink rate,
 u = steady-state concentration
 example: $f \sim$ force on stretched string/drum
 u = steady-state displacement

$$\nabla \cdot (c \nabla u) = f$$

c = permittivity ϵ
 c = thermal conductivity
 c = diffusion coefficient
 $c \sim$ "springy-ness"

Laplace's equation:

$$\nabla^2 u = 0$$

examples: as for Poisson, but no sources

$$\nabla \cdot (c \nabla u) = 0$$

Heat/diffusion equation:

$$\frac{\partial u}{\partial t} = \nabla^2 u$$

examples: u = temperature
 u = solute concentration

$$\frac{\partial u}{\partial t} = \nabla \cdot (c \nabla u)$$

c = thermal conductivity
 c = diffusion coefficient

Scalar wave equation:

$$\frac{\partial^2 u}{\partial t^2} = \nabla^2 u$$

examples: u = displacement of stretched string/drum
 u = density of gas/fluid

$$\frac{\partial^2 u}{\partial t^2} = \nabla \cdot (c \nabla u)$$

$c^2 = 1$ / wave speed

+ many, many others...

Maxwell (electromagnetism)

Schrödinger (quantum mechanics)

Navier–Stokes / Stokes / Euler (fluids)

Black-Scholes (options pricing)

Lamé–Navier (linear elastic solids)

beam equation (bending thin solid strips)

advection-diffusion (diffusion in flows)

reaction-diffusion (diffusion+chemistry)

minimal-surface equation (soap films)

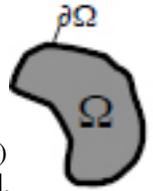
nonlinear wave equation (e.g. solitary ocean waves)

18.06

finite-dimensional linear algebra

18.303

linear algebra w/ functions & derivatives



unknowns:	vector space of column vectors \mathbf{x} (or $\bar{\mathbf{x}}$) in \mathbb{R}^n (or \mathbb{C}^n), or possibly $\mathbf{x}(t)$ [time-dependent]	vector space: we can add, subtract, & multiply by constants without leaving the space	vector space of real-valued (or complex) functions $u(\mathbf{x})$ [for \mathbf{x} in some domain Ω], or possibly $u(\mathbf{x},t)$ [time-dependent], ... possibly restricted by some boundary conditions at the boundary $\partial\Omega$ [e.g. $u(\mathbf{x}) = 0$ on $\partial\Omega$] ... possibly with vector-valued $\mathbf{u}(\mathbf{x})$ [vector fields]
linear operators:	matrices A	linearity: $A(\alpha\mathbf{x} + \beta\mathbf{y}) = \alpha A\mathbf{x} + \beta A\mathbf{y}$ $A(c\mathbf{u} + \beta\mathbf{v}) = \alpha A\mathbf{u} + \beta A\mathbf{v}$	linear operators on functions \hat{A} , [$\hat{A}u = \text{function}$] using partial derivatives. examples: $\hat{A}_1 u = \nabla^2 u$ [Laplacian operator] $\hat{A}_2 u = 3u$ [mult. by constant] $\hat{A}_3 u _{\mathbf{x}} = a(\mathbf{x}) u(\mathbf{x})$ [mult. by function] $\hat{A} = 4\hat{A}_1 + \hat{A}_2 + 7\hat{A}_3$ [linear comb. of ops.]
dot product and transpose:	$\mathbf{x} \cdot \mathbf{y} = \mathbf{x}^* \mathbf{y} = \sum_i x_i y_i$ $\mathbf{x} \cdot A\mathbf{y} = \mathbf{x}^* A\mathbf{y} = (A\mathbf{x})^* \mathbf{y}$ $\Leftrightarrow (A^*)_{ij} = A_{ji}$ [conjugate & swap rows/cols]	complex \mathbf{x} : $\mathbf{x}^T \rightarrow \mathbf{x}^T = \mathbf{x}^*$ $(\frac{\partial}{\partial \mathbf{x}})^* = ???$	$u(\mathbf{x}) \cdot v(\mathbf{x}) = \langle u, v \rangle = \text{???}$ [inner product] [= some integral] $\langle u, \hat{A}v \rangle = \langle \hat{A}^* u, v \rangle$ $\Rightarrow \hat{A}^* = \text{???}$ (= \hat{A}^\dagger in physics) [adjoint]
basis:	set of vectors \mathbf{b}_i with span = whole space \Leftrightarrow any $\mathbf{x} = \sum_i c_i \mathbf{b}_i$ for some coefficients c_i ... if orthonormal basis, then $c_i = \mathbf{b}_i^* \mathbf{x}$	[e.g. Fourier series!]	∞ set of functions $b_i(\mathbf{x})$ with span = whole space \Leftrightarrow any $u(\mathbf{x}) = \sum_i c_i b_i(\mathbf{x})$ for some coefficients c_i ... if orthonormal basis, then $c_i = \langle b_i, u \rangle$
linear equations:	solve $A\mathbf{x} = \mathbf{b}$ for \mathbf{x}		solve $\hat{A}u = f$ for $u(\mathbf{x})$
existence & uniqueness:	$A\mathbf{x} = \mathbf{b}$ solvable if \mathbf{b} in column space of A . Solution unique if null space of $A = \{\mathbf{0}\}$, or equivalently if eigenvalues of A are $\neq 0$.		$\hat{A}u = f$ solvable if $f(\mathbf{x})$ in col. space (image) of \hat{A} . Solution unique if null space (kernel) of $\hat{A} = \{0\}$, or equivalently if eigenvalues of \hat{A} are $\neq 0$.
eigenvalues/vectors:	solve $A\mathbf{x} = \lambda\mathbf{x}$ for \mathbf{x} and λ . For this \mathbf{x} , A acts just like a number (λ). [e.g. $A^n \mathbf{x} = \lambda^n \mathbf{x}$, $e^A \mathbf{x} = e^\lambda \mathbf{x}$.]		solve $\hat{A}u = \lambda u$ for $u(\mathbf{x})$ [eigenfunction] and λ . For this u , \hat{A} acts just like a number (λ). [e.g. $\hat{A}^n u = \lambda^n u$, $e^{\hat{A}} u = e^\lambda u$.] example: $\frac{\partial^2}{\partial x^2} \sin(kx) = (-k^2) \sin(kx)$
time-evolution initial-value problem:	solve $d\mathbf{x}/dt = A\mathbf{x}$ for $\mathbf{x}(0) = \mathbf{b}$ [system of ODEs] $\Rightarrow \mathbf{x} = e^{At} \mathbf{b}$ [if A constant] ... expand \mathbf{b} in eigenvectors, mult. each by $e^{\lambda t}$		solve $\partial u / \partial t = \hat{A}u$ for $u(\mathbf{x}, 0) = f(\mathbf{x})$ $\Rightarrow u(\mathbf{x}, t) = e^{\hat{A}t} f(\mathbf{x})$ [if \hat{A} constant] ... expand f in eigenfunctions, mult. each by $e^{\lambda t}$
real-symmetric or Hermitian:	$A = A^*$ \Rightarrow real λ , orthogonal eigenvectors, diagonalizable		$\hat{A} = \hat{A}^*$ [?????] \Rightarrow real λ , orthogonal eigenvectors (???) diagonalizable (???)
positive definite / semi-definite:	$A = A^*$, $\mathbf{x}^* A \mathbf{x} > 0$ for any $\mathbf{x} \neq \mathbf{0}$ / $\mathbf{x}^* A \mathbf{x} \geq 0$ \Leftrightarrow real $\lambda > 0 / \geq 0$, $A = B^* B$ for some B important fact: $-\nabla^2$ is symmetric positive definite or semi-definite!		$\hat{A} = \hat{A}^*$, $\langle u, \hat{A}u \rangle > 0 / \geq 0$ for $u \neq 0$ (???) \Leftrightarrow real $\lambda > 0 / \geq 0$, $\hat{A} = \hat{B}^* \hat{B}$ for some \hat{B} (???)
inverses:	$A^{-1} A = A A^{-1} = 1$ [if it exists] $\Rightarrow A\mathbf{x} = \mathbf{b}$ solved by $\mathbf{x} = A^{-1} \mathbf{b}$	$(\frac{\partial}{\partial \mathbf{x}})^{-1} = ???$... some kind of integral?	$\hat{A}^{-1} = \text{???}$ $\Rightarrow \hat{A}u = f$ solved by $f = \hat{A}^{-1} u$???
(real) orthogonal or unitary:	$A^{-1} = A^* \Leftrightarrow (A\mathbf{x}) \cdot (A\mathbf{x}) = \mathbf{x} \cdot \mathbf{x}$ for any \mathbf{x} $\Rightarrow \lambda = 1$, orthogonal eigenvectors, diagonalizable		$\hat{A}^{-1} = \hat{A}^* \Leftrightarrow \langle \hat{A}u, \hat{A}u \rangle = \langle u, u \rangle$ for any u $\Rightarrow \lambda = 1$, orthogonal eigenvectors (???) diagonalizable (???)

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