

Chapter 10

10.3 Simultaneous Iterations

$$V = [v_1, \dots, v_n] \tag{10.1}$$

$$V^{(i)} = AV^{(i-1)} \tag{10.2}$$

Instead take

$Q^{(0)} = [q_1, \dots, q_n]$ -orthogonal
for $k = 1, 2, \dots$

$$Z = AQ^{(k-1)}$$

$$Q^{(k)}R^{(k)} = Z$$

$$A^{(k)} = (Q^{(k)})^T A Q^{(k)}$$

Chapter 11

11.1 Simultaneous Iteration

$A^{(k)}V \rightarrow$ problematic, all columns of V converge to same v_1 . Orthogonalized V :

Pick $Q^{(0)}$ --orthogonal

For $k = 1, 2, \dots$

$$Z = AQ^{(k-1)}$$

$$\underline{Q^{(k)}} R^{(k)} = Z$$

Define $A^{(k)} = (\underline{Q^{(k)}})^T A \underline{Q^{(k)}}$

11.2 QR Iteration

$$A^{(0)} = A \tag{11.1}$$

$$A^{(k-1)} = Q^{(k)} R^{(k)} \tag{11.2}$$

$$A^{(k)} = R^{(k)} Q^{(k)} \tag{11.3}$$

$$\underline{Q^{(k)}} = Q^{(1)} \dots Q^{(k)} \tag{11.4}$$

Define

$$\underline{R^{(k)}} = R^{(k)} \dots R^{(1)} \tag{11.5}$$

Therefore, $A^{(k)}$ are the same.

$$A^{(k)} = \underline{Q^{(k)}} \underline{R^{(k)}} \tag{11.6}$$

Proof: Induction.

$$\begin{aligned}
A^{(k)} &= \underline{AQ^{(k-1)}R^{(k-1)}} \\
&= \underline{Q^{(k)}R^{(k)}R^{(k-1)}} \\
&= \underline{Q^{(k)}R^{(k)}}.
\end{aligned} \tag{11.7}$$

Because of independent assumption on

$$A^{(k-1)} = (Q^{(k-1)})^T A Q^{(k-1)}. \tag{11.8}$$

Formally:

$$\begin{aligned}
A^{(k)} &= (Q^{(k)})^T A^{(k-1)} Q^{(k)} \\
&= \underline{(Q^{(k)})^T A^{(k)} Q^{(k)}}.
\end{aligned} \tag{11.9}$$

From QR:

$$\begin{aligned}
A^{(k)} &= \underline{AQ^{(k-1)}R^{(k-1)}} \\
&= \underline{Q^{(k-1)}A^{(k-1)}R^{(k-1)}} \\
&= \underline{Q^{(k)}R^{(k)}}.
\end{aligned} \tag{11.10}$$

11.3 Connection with Inverse Iteration

Let A be real and symmetric.

$$A^{(k)} = \underline{Q^{(k)}R^{(k)}} \tag{11.11}$$

$$\begin{aligned}
(A^{(k)})^{-1} &= (R^{(k)})^{-1}(Q^{(k)})^T \\
&= \underline{Q^{(k)}(R^{(k)})^{-T}}.
\end{aligned} \tag{11.12}$$

Let P be the reverse identity

$$P_{ij} = (\delta_{n+1-i,j})_{i,j=1}^n \tag{11.13}$$

$$P = \begin{bmatrix} & & & & 1 \\ & & & & \\ & & & 1 & \\ & & \ddots & & \\ & & & & \\ 1 & & & & \end{bmatrix} \tag{11.14}$$

$$A^{-1}P = \underline{(Q^{(k)}P)[P(R^{(k)})^{-T}P]} \tag{11.15}$$

Simultaneous iteration on P . Simultaneous inverse iteration on A .

11.4 Shifts in QR

$$A^{(k-1)} - \mu^{(k)}I = Q^{(k)}R^{(k)} \quad (11.16)$$

$$\begin{aligned} A^{(k)} &= R^{(k)}Q^{(k)} + \mu^{(k)}I \\ &= (Q^{(k)})^T A^{(k-1)} Q^{(k)} \end{aligned}$$

$$= \dots$$

$$= \frac{(Q^{(k)})^T A Q^{(k)}}{\quad} \quad (11.17)$$

$$(A - \mu^{(k)}I)(A - \mu^{(k-1)}I) \dots (A - \mu^{(1)}I) = Q^{(k)}R^{(k)} \quad (11.18)$$

$$\underline{Q^{(k)}} = \prod_{j=1}^k Q^{(j)} \quad (11.19)$$

is an orthogonalization of A .

11.5 Choice of Shifts

Converge to the last column of $Q^{(k)}$.

Shift:

$$\begin{aligned} \mu^{(k)} &= \frac{(q_n^{(k)})^T A q_n^{(k)}}{(q_n^{(k)})^T q_n^{(k)}} \\ &= (q_n^{(k)})^T A q_n^{(k)} \\ &= (Q^{(k)} e_n)^T A (Q^{(k)} e_n) \\ &= e_n^T (Q^{(k)})^T A (Q^{(k)}) e_n \\ &= e_n^T A e_n \\ &= A_{nn} \end{aligned} \quad (11.20)$$

Rayleigh quotient shift with starting vector e_n .

Rayleigh quotient shift does not break this matrix $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$.

Need Wilkinson shift \rightarrow eigenvalue of $\begin{bmatrix} a_{m-1} & b_{m-1} \\ b_{m-1} & a_m \end{bmatrix}$ closer to a_m .

11.6 Stability

QR iteration is backward stable.

$$\tilde{Q}\tilde{\Lambda}\tilde{Q} = A + \delta A \quad (11.21)$$

$$\frac{\|\delta A\|}{\|A\|} = O(\epsilon) \quad (11.22)$$

$$|\tilde{\lambda}_j - \lambda_j| = O(\epsilon) \|A\| \quad (11.23)$$

11.7 Jacobi Method

Algorithm for finding eigenvalues of symmetric matrices.

Idea: Form $J^T A J$, J -orthogonal, in such a way that $\|\cdot\|_F$ is preserved, but $\text{off}(A)$ is reduced the off diagonal, where $\text{off}(A) = \sum_{i \neq j} |a_{ij}|^2$ is the sum of the squares of the off diagonal elements.

$$J^T \begin{bmatrix} a & d \\ d & b \end{bmatrix} J = \begin{bmatrix} * & 0 \\ 0 & * \end{bmatrix} \quad (11.24)$$

$$J = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \quad (11.25)$$

$$\tan 2\theta = \frac{2d}{b-a} \quad (11.26)$$

Which a_{ij} do we pick at every step? Pick largest, therefore $\text{off}(A)$ decreases by a factor of $1 - \frac{2}{m^2 - m}$. Therefore, $O(m^2)$ steps ($O(m)$ operations per step) are needed for convergence.