

## Navier-Stokes Equations

$$\begin{cases} \underline{u}_t + (\underline{u} \cdot \nabla) \underline{u} = -\nabla p + \frac{1}{Re} \nabla^2 \underline{u} [+g] & \text{Momentum equation} \\ \nabla \cdot \underline{u} = 0 & \text{Incompressibility} \end{cases}$$

Incompressible flow, i.e. density  $\rho = \text{constant}$ .

Reynolds number:

$$Re = \frac{U \cdot L}{\nu} = \frac{\text{inertial forces}}{\text{viscous forces}}$$

$U$  = Characteristic velocity

$L$  = Characteristic length scale

$\nu$  = Kinetic viscosity

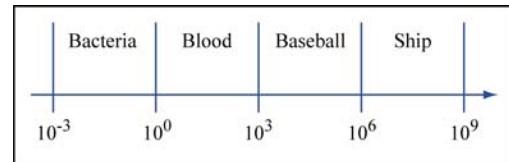


Image by MIT OpenCourseWare.

in 2D:  $\underline{u} = \begin{pmatrix} u \\ v \end{pmatrix}$

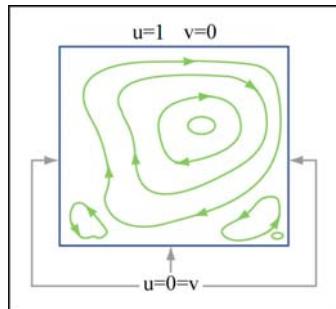
$$(1) \quad u_t + uu_x + vu_y = -p_x + \frac{1}{Re}(u_{xx} + u_{yy})$$

$$(2) \quad v_t + uv_x + vv_y = -p_y + \frac{1}{Re}(v_{xx} + v_{yy})$$

$$(3) \quad u_x + v_y = 0$$

### Famous Problems:

Lid driven cavity



Flow around cylinder

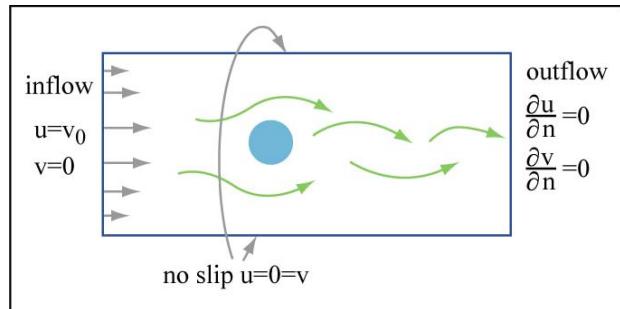


Image by MIT OpenCourseWare.

3 unknowns, 3 equations

DAE (Differential Algebraic System), (3) is a constraint

Solve by projection approach:

In each time step

I. Solve  $\underline{u}_t + (\underline{u} \cdot \nabla) \underline{u} = \frac{1}{\text{Re}} \nabla^2 \underline{u}$

$$\frac{U^* - U^n}{\Delta t} = -(U^n \cdot \nabla) U^n + \frac{1}{\text{Re}} \nabla^2 U^n$$

Note:  $\nabla \cdot U^* \neq 0$

II. Project on divergence-free velocity field

$$\frac{U^{n+1} - U^*}{\Delta t} = -\nabla p$$

What is  $p : 0 \stackrel{!}{=} \nabla \cdot U^{n+1} = \nabla \cdot U^* - \Delta t \nabla^2 P$

$$\Rightarrow \nabla^2 p = \frac{1}{\Delta t} \nabla \cdot U^* \quad \text{Poisson equation for pressure}$$

Discretization:

Solution:

$$u = v = 0,$$

$$p = \text{constant}$$

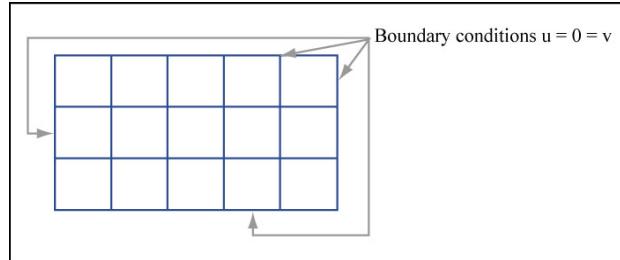


Image by MIT OpenCourseWare.

But: Central differences  
on grid allow solution

$$U_{ij} = V_{ij} = 0,$$

$$P_{ij} = \begin{cases} P_1 & \text{for } i+j \text{ even} \\ P_2 & \text{for } i+j \text{ odd} \end{cases}$$

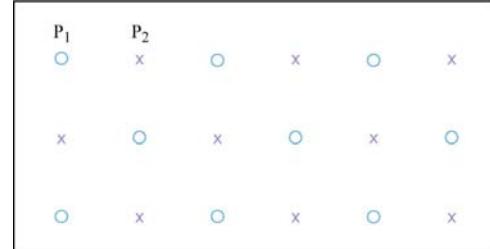
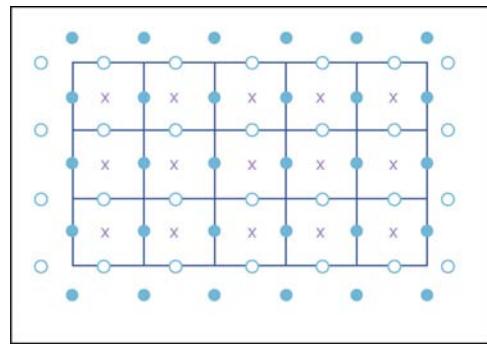


Image by MIT OpenCourseWare.

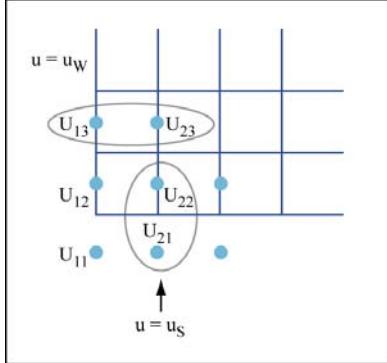
Fix: Staggered grid



- × pressure  $p$
- velocity  $u$
- velocity  $v$

Image by MIT OpenCourseWare.

## Boundary Conditions:



$$U_{13} = u_w$$

$$\frac{U_{21} + U_{22}}{2} = u_s \Rightarrow U_{21} + U_{22} = 2u_s$$

Image by MIT OpenCourseWare.

## Numerical Method:

### I. a) Treat Nonlinear Terms

$$uu_x + vu_y = (u^2)_x + (uv)_y$$

$$uv_x + vv_y = (uv)_x + (v^2)_y \quad (\text{use } u_x + v_y = 0)$$

$$\left[ \frac{\partial(U^2)}{\partial x} \right]_{ij} = \frac{(U_{i+\frac{1}{2},j})^2 - (U_{i-\frac{1}{2},j})^2}{\Delta x}$$

$$\left[ \frac{\partial(UV)}{\partial y} \right]_{ij} = \frac{U_{i,j+\frac{1}{2}} V_{i,j+\frac{1}{2}} - U_{i,j-\frac{1}{2}} V_{i,j-\frac{1}{2}}}{\Delta y}$$

$$\left[ \frac{\partial(UV)}{\partial x} \right]_{ij} = \frac{U_{i+\frac{1}{2},j} V_{i+\frac{1}{2},j} - U_{i-\frac{1}{2},j} V_{i-\frac{1}{2},j}}{\Delta x}$$

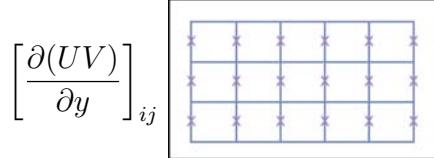
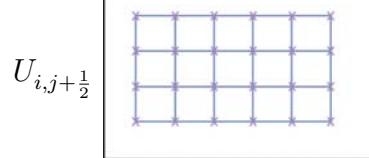
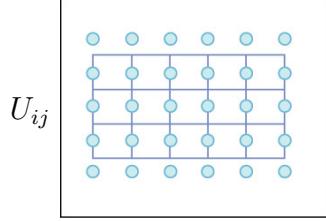


Image by MIT OpenCourseWare.

$$\text{where } U_{i+\frac{1}{2},j} = \frac{U_{i,j} + U_{i+1,j}}{2}, \quad U_{i,j+\frac{1}{2}} = \frac{U_{i,j} + U_{i,j+1}}{2}$$

$$\frac{U_{i,j}^* - U_{i,j}^n}{\Delta t} = - \left[ \frac{\partial(U^2)}{\partial x} \right]_{i,j}^n - \left[ \frac{\partial(UV)}{\partial y} \right]_{i,j}^n$$

$$\frac{V_{i,j}^* - V_{i,j}^n}{\Delta t} = - \left[ \frac{\partial(UV)}{\partial x} \right]_{i,j}^n - \left[ \frac{\partial(V^2)}{\partial y} \right]_{i,j}^n$$

### I. b) Implicit Diffusion

$$\frac{\underline{U}^{**} - \underline{U}^*}{\Delta t} = \frac{1}{\text{Re}} K 2D \cdot \underline{U}^{**}$$

$$\frac{\underline{V}^{**} - \underline{V}^*}{\Delta t} = \frac{1}{\text{Re}} K 2D \cdot \underline{V}^{**}$$

↑  
5 point Laplace stencil with Dirichlet boundary conditions

### II. Pressure Correction

$$K 2D \cdot \underline{P} = \frac{1}{\Delta t} \left( \frac{\partial \underline{U}^{**}}{\partial x} + \frac{\partial \underline{V}^{**}}{\partial y} \right)$$

with Neumann boundary conditions  $\frac{\partial p}{\partial n} = 0$

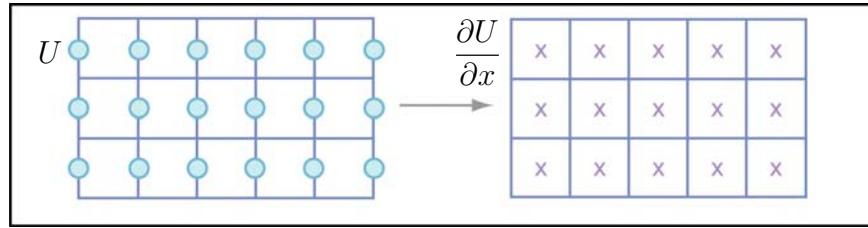


Image by MIT OpenCourseWare.

$$\frac{\underline{U}^{n+1} - \underline{U}^{**}}{\Delta t} = - \frac{\partial \underline{P}}{\partial x}$$

$$\frac{\underline{V}^{n+1} - \underline{V}^{**}}{\Delta t} = - \frac{\partial \underline{P}}{\partial y}$$

MIT OpenCourseWare  
<http://ocw.mit.edu>

18.336 Numerical Methods for Partial Differential Equations  
Spring 2009

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.