

## Finite Difference (FD) Approximation

Consider  $u \in C^l$ .

Goal: Approximate derivative by finitely many function values:

$$\frac{\partial^k u}{\partial x^k}(x_0) \approx \sum_{i=0}^m a_i u(x_i) \quad (k \leq l)$$

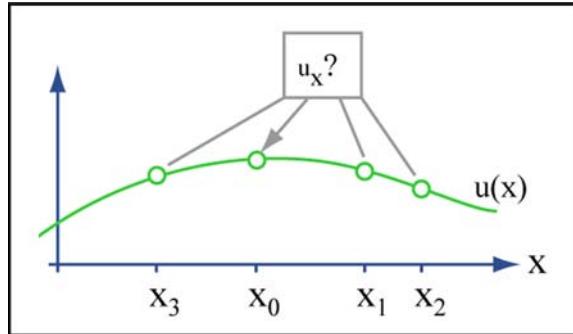


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Vector of coefficients  $a = (a_0, a_1, \dots, a_m)$  is called FD stencil.

How to get stencil?

Taylor expansion

$$\begin{aligned} \text{In 1D: } u(x) &= u(x_0) + u_x(x_0) \cdot (x - x_0) + \frac{1}{2} u_{xx}(x_0) \cdot (x - x_0)^2 \\ &\quad + \frac{1}{6} u_{xxx}(x_0) \cdot (x - x_0)^3 + O(|x - x_0|^4) \end{aligned}$$

Name  $\bar{x}_i = x_i - x_0$

$$\begin{aligned} \Rightarrow u(x_i) &= u(x_0) + u_x(x_0) \cdot \bar{x}_i + \frac{1}{2} u_{xx}(x_0) \cdot \bar{x}_i^2 + \frac{1}{6} u_{xxx}(x_0) \cdot \bar{x}_i^3 + O(|\bar{x}_i|^4) \\ \Rightarrow \sum_{i=0}^m a_i u(x_i) &= u(x_0) \cdot \left( \sum_{i=0}^m a_i \right) + u_x(x_0) \cdot \left( \sum_{i=0}^m a_i \bar{x}_i \right) \\ &\quad + u_{xx}(x_0) \cdot \left( \frac{1}{2} \sum_{i=0}^m a_i \bar{x}_i^2 \right) + O(h^3) \quad \text{where } \bar{x}_i \leq h \forall i. \end{aligned}$$

Match coefficients:

$$\sum_{i=0}^m a_i u(x_i) \approx u_x(x_0) \Rightarrow \sum_i a_i = 0, \sum_i a_i \bar{x}_i = 1 \quad \left[ \sum a_i \bar{x}_i^2 \text{ small} \right]$$

$$\sum_{i=0}^m a_i u(x_i) \approx u_{xx}(x_0) \Rightarrow \sum_i a_i = 0, \sum_i a_i \bar{x}_i = 0, \sum_i a_i \bar{x}_i^2 = 2 \left[ \sum a_i \bar{x}_i^3 \text{ small} \right]$$

etc.

Vandermonde matrix

$$V = V(x_0, x_1, \dots, x_m) = \begin{bmatrix} 1 & \dots & 1 \\ \bar{x}_0 & \dots & \bar{x}_m \\ \bar{x}_0^2 & \dots & \bar{x}_m^2 \\ \vdots & & \vdots \\ \bar{x}_0^k & \dots & \bar{x}_m^k \end{bmatrix} = \begin{bmatrix} 1 & 1 & \dots & 1 \\ 0 & \bar{x}_1 & \dots & \bar{x}_m \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \bar{x}_1^k & \dots & \bar{x}_m^k \end{bmatrix}$$

Constraints for stencil:

$$V \cdot a = b$$

linear system

$$k=1 : \sum a_i u(x_i) \approx u_x(x_0) : \begin{bmatrix} 1 & \dots & 1 \\ \bar{x}_0 & \dots & \bar{x}_m \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$k=2 : \sum a_i u(x_i) \approx u_{xx}(x_0) : \begin{bmatrix} 1 & \dots & 1 \\ \bar{x}_0 & \dots & \bar{x}_m \\ \bar{x}_0^2 & \dots & \bar{x}_m^2 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$$

If  $m = k \implies$  In general one unique stencil  $a$

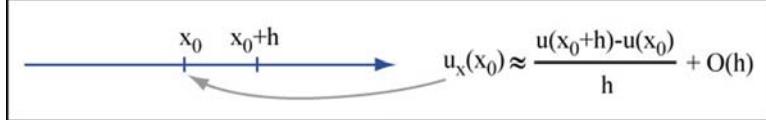
If  $m > k \implies$  Multiple stencils

Can add additional criteria, e.g. require higher order.

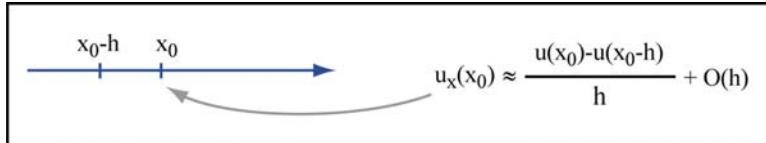
Ex.:  $k = 1, m = 1$

$$\begin{bmatrix} 1 & 1 \\ \hat{x}_0 & \hat{x}_1 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\bar{x}_0 = 0, \bar{x}_1 = h \implies a_0 = -\frac{1}{h}, a_1 = \frac{1}{h}$$



$$\bar{x}_0 = 0, \bar{x}_1 = -h \implies a_0 = \frac{1}{h}, a_1 = -\frac{1}{h} \quad \text{Image by MIT OpenCourseWare.}$$



Ex.:  $k = 1, m = 2 \quad x = (x_0, x_0 + h, x_0 - h)$  Image by MIT OpenCourseWare.

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & h & -h \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \implies \left\{ \begin{array}{l} a_1 - a_2 = \frac{1}{h} \\ a_0 = -a_1 - a_2 \end{array} \right\}$$

One-parameter family of stencils

Additional criterion: second order accuracy

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & h & -h \\ 0 & h^2 & h^2 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \implies a_0 = 0, a_1 = \frac{1}{2h}, a_2 = -\frac{1}{2h}$$

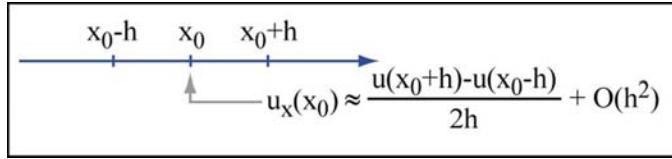


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Ex.:  $k = 2, m = 2$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & \bar{x}_1 & \bar{x}_2 \\ 0 & \bar{x}_1^2 & \bar{x}_2^2 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix} \implies \begin{cases} a_0 = -a_1 - a_2 \\ a_1 = \frac{2}{\bar{x}_1} \cdot (\bar{x}_1 - \bar{x}_2) \\ a_2 = \frac{2}{\bar{x}_2} \cdot (\bar{x}_2 - \bar{x}_1) \end{cases}$$

Equidistant:  $x = (x_0, x_0 + h, x_0 - h)$

$$a_0 = -\frac{2}{h^2}, \quad a_1 = a_2 = \frac{1}{h^2}$$

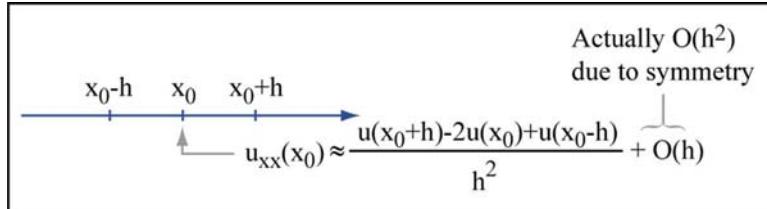


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Higher space dimensions

2D

$$\vec{x}_i = (x_i, y_i)$$

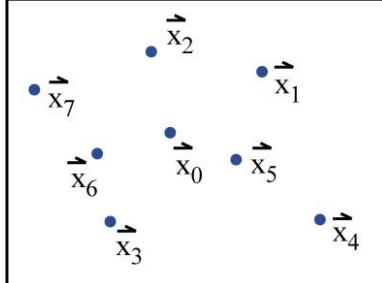


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$$\begin{bmatrix} 1 & 1 & \dots & 1 \\ 0 & \bar{x}_1 & \dots & \bar{x}_m \\ 0 & \bar{y}_1 & \dots & \bar{y}_m \\ 0 & \bar{x}_1^2 & \dots & \bar{x}_m^2 \\ 0 & \bar{x}_1 \bar{y}_1 & \dots & \bar{x}_m \bar{y}_m \\ 0 & \bar{y}_1^2 & \dots & \bar{y}_m^2 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow \text{stencil } \vec{a} \text{ for } u_{xx}(x_0)$$

3D

$$\begin{bmatrix} 1 & \dots & 1 & \dots & 1 \\ 0 & \dots & \bar{x}_i & \dots & \\ 0 & \dots & \bar{y}_i & \dots & \\ 0 & \dots & \bar{z}_i & \dots & \\ 0 & \dots & \bar{x}_i^2 & \dots & \\ 0 & \dots & \bar{y}_i^2 & \dots & \\ 0 & \dots & \bar{z}_i^2 & \dots & \\ 0 & \dots & \bar{x}_i \bar{y}_i & \dots & \\ 0 & \dots & \bar{x}_i \bar{z}_i & \dots & \\ 0 & \dots & \bar{y}_i \bar{z}_i & \dots & \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 2 \\ 2 \\ 2 \\ 0 \\ 0 \\ 0 \end{bmatrix} \leftarrow \text{stencil for } \nabla^2 u(x_0) = u_{xx} + u_{yy} + u_{zz}$$

Ex.: [2D]  $\nabla^2 u(x_0)$

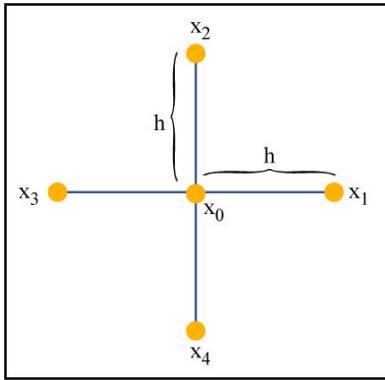


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$$\vec{a} = \left( -\frac{4}{h^2}, \frac{1}{h^2}, \frac{1}{h^2}, \frac{1}{h^2}, \frac{1}{h^2} \right) = \left( -\frac{2}{h^2}, \frac{1}{h^2}, 0, \frac{1}{h^2}, 0 \right) + \left( -\frac{2}{h^2}, 0, \frac{1}{h^2}, 0, \frac{1}{h^2} \right)$$

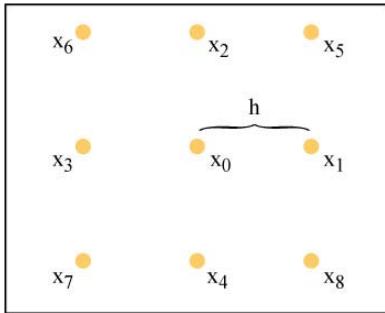


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$$\vec{a} = (\cdots \text{ exercise } \cdots)$$

# Poisson Equation

1D  $\begin{cases} -u_{xx} = f(x) & \text{in } ]0, 1[ \\ u(0) = a \\ u_x(1) = c \end{cases}$   $\leftarrow$  Dirichlet boundary condition  
 $\leftarrow$  Neumann boundary condition

Discretize on regular grid  $\vec{x} = (0, h, 2h, \dots, nh, 1)$ , where  $h = \frac{1}{n+1}$

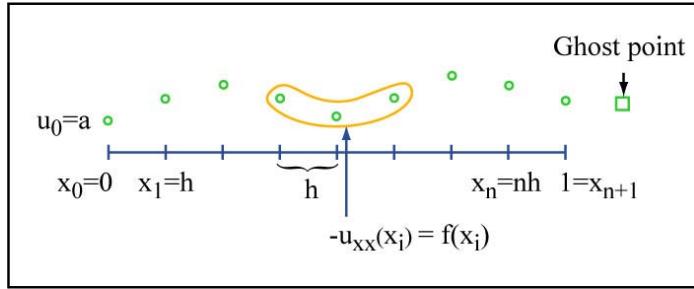


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Interior:  $f(x_i) = -u_{xx}(x_i) = \frac{-u(x_{i-1}) + 2u(x_i) - u(x_{i+1})}{h^2} + O(h^2)$   
 $= \left(-\frac{1}{h^2}, \frac{2}{h^2}, -\frac{1}{h^2}\right) \cdot \begin{pmatrix} u_{i-1} \\ u_i \\ u_{i+1} \end{pmatrix} + O(h^2)$

Dirichlet boundary condition:  $u_0 = u(x_0) = a$  (exact)

Neumann boundary condition:

- Naive choice:  $c = u_x(1)$   
 $= \frac{u_{n+1} - u_n}{h} + O(h) = \left(-\frac{1}{h}, \frac{1}{h}\right) \cdot \begin{pmatrix} u_n \\ u_{n+1} \end{pmatrix} + O(h)$

$O(h)$  on a single cell  $\Rightarrow$  Could preserve  $O(h^2)$  globally, or drop accuracy to  $O(h)$ . Here the bad event happens.

- Second order approximation:

$$c = u_x(1) = \frac{u(x_{n+2}) - u(x_n)}{2h} + O(h^2)$$

Obtain  $u_{n+2}$  by  $\frac{-u_n + 2u_{n+1} - u_{n+2}}{h^2} = f(1)$

$$\Rightarrow \left(-\frac{1}{h}, \frac{1}{h}\right) \cdot \begin{pmatrix} u_n \\ u_{n+1} \end{pmatrix} = c + \underbrace{\frac{h}{2}f(1)}$$

right hand side correction yields 2<sup>nd</sup> order

- Alternative:

$$\left(-\frac{1}{2h}, \frac{2}{h}, -\frac{3}{2h}\right) \cdot \begin{pmatrix} u_{n-1} \\ u_n \\ u_{n+1} \end{pmatrix} = c$$

2<sup>nd</sup> order one-sided stencil (check by  $V \cdot a = b$ ).

Discretization generates linear system:

$$\underbrace{\begin{bmatrix} 1 & & & \\ -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} & \\ & \ddots & \ddots & \ddots \\ & \ddots & \ddots & \ddots \\ & & -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} \end{bmatrix}}_A \cdot \underbrace{\begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ u_n \\ u_{n+1} \end{bmatrix}}_{\vec{u}} = \underbrace{\begin{bmatrix} a \\ f(x_1) \\ \vdots \\ f(x_n) \\ c + \frac{h}{2}f(1) \end{bmatrix}}_{\vec{b}} \quad (*)$$

Second order approximation (try it yourself!)

Big Question:

How to solve sparse linear systems  $A \cdot \vec{u} = \vec{b}$ ?  
 → lecture 11.

Rem.:  $(*) \Leftrightarrow (**)$

$$\underbrace{\begin{bmatrix} \frac{2}{h^2} & -\frac{1}{h^2} & & \\ -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} & \\ & \ddots & \ddots & \ddots \\ & \ddots & \ddots & \ddots \\ & & -\frac{1}{h^2} & \frac{2}{h^2} & -\frac{1}{h^2} \end{bmatrix}}_{\frac{1}{h^2} \text{ from Neumann boundary conditions}} \cdot \underbrace{\begin{bmatrix} u_1 \\ \vdots \\ \vdots \\ u_n \end{bmatrix}}_{\vec{u}} = \underbrace{\begin{bmatrix} f(x_1) + \frac{1}{h^2}a \\ f(x_2) \\ \vdots \\ \vdots \\ f(x_{n-1}) \\ f(x_n) + \frac{c}{h} + \frac{f(1)}{2} \end{bmatrix}}_{\vec{b}} \quad (**)$$

$$u_{n+1} = u_n + h \left( c + \frac{h}{2}f(1) \right) \\ \Rightarrow -\frac{1}{h^2}u_{n+1} = \frac{1}{h^2}u_n + \frac{1}{h} \left( c + \frac{h}{2}f(1) \right)$$

Advantages: • fewer equations  
 • matrix symmetric

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18.336 Numerical Methods for Partial Differential Equations  
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