

Solutions to Problem Set 5

Edited by Chris H. Rycroft*

December 5, 2006

1 Restoring force for highly stretched polymers

1.1 A globally valid asymptotic approximation

Using the substitution $t = ua$ the expression can be rewritten as

$$\begin{aligned} P_N(r) &= \frac{1}{2\pi^2 r} \int_0^\infty \frac{t}{a} \sin(rt/a) \left[\frac{\sin t}{t} \right]^N \frac{dt}{a} \\ &= \frac{1}{2\pi^2 a^2 r} \int_0^\infty t \sin(rt/a) \left[\frac{\sin t}{t} \right]^N dt \end{aligned}$$

The integrand is even, and can be rewritten as

$$\begin{aligned} P_N(r) &= \frac{1}{4\pi^2 a^2 r} \int_{-\infty}^\infty t \sin(rt/a) \left[\frac{\sin(t)}{t} \right]^N dt \\ &= \frac{1}{8i\pi^2 a^2 r} \int_{-\infty}^\infty u \left(e^{irt/a} - e^{-irt/a} \right) \left[\frac{\sin(t)}{t} \right]^N dt \\ &= \frac{1}{4i\pi^2 a^2 r} \int_{-\infty}^\infty t e^{irt/a} \left[\frac{\sin(t)}{t} \right]^N dt \\ &= \frac{1}{4i\pi^2 a^2 r} \int_{-\infty}^\infty t \exp[-Nf(t)] dt \end{aligned}$$

where

$$f(t) = -\frac{irt}{Na} - \log\left(\frac{\sin t}{t}\right).$$

We define $\xi = r/Na$ and keep it fixed. The first and second derivatives are

$$\begin{aligned} f'(t) &= -i\xi - \cot t + \frac{1}{t} \\ f''(t) &= 1 + \cot^2 t - \frac{1}{t^2}. \end{aligned}$$

*Solution to problem 1 based on sections of *Random Walks and Random Environments* by Barry Hughes. Solutions 2 and 3 based on previous years.

By putting $f'(t) = 0$, we find that there is a saddle point at $t_0 = iL^{-1}(\xi)$ where L is the Langevin function $L(\xi) = \coth \xi - 1/\xi$. Over the range $0 < \xi < 1$ the Langevin function is monotonic and thus has a well-defined inverse. We see that the second derivative of f can be written as

$$\begin{aligned} f''(t) &= 1 - \coth^2(-it) + \frac{1}{(-it)^2} \\ &= 1 - \left(\coth(-it) - \frac{1}{(-it)} \right)^2 - \frac{2 \coth(-it)}{(-it)} + \frac{2}{(-it)^2} \\ &= 1 - \xi^2 - \frac{2\xi}{L^{-1}(\xi)}. \end{aligned}$$

This function is positive, so we deform the contour of integration to the line $\text{Im}(t) = L^{-1}(\xi)$. Our main contribution comes from the above saddle point and we obtain

$$\begin{aligned} P_N(r) &\sim \frac{L^{-1}(\xi)}{4\pi^2 r a^2} \sqrt{\frac{2\pi}{N(1 - \xi^2 - 2\xi/L^{-1}(\xi))}} e^{-N\xi L^{-1}(\xi)} \left[\frac{\sinh(L^{-1}(\xi))}{L^{-1}(\xi)} \right]^N \\ &\sim \frac{L^{-1}(\xi)}{\xi \sqrt{8\pi^3 N^3 a^6 (1 - \xi^2 - 2\xi/L^{-1}(\xi))}} e^{-N\xi L^{-1}(\xi)} \left[\frac{\sinh(L^{-1}(\xi))}{L^{-1}(\xi)} \right]^N \\ &\sim \frac{L^{-1}(r/aN)}{r \sqrt{8\pi^3 N a^4 (1 - (r/aN)^2 - 2r/aN L^{-1}(r/aN))}} e^{-rL^{-1}(r/aN)/a} \left[\frac{\sinh(L^{-1}(r/aN))}{L^{-1}(r/aN)} \right]^N. \end{aligned}$$

1.2 Free energy

The free energy is given by

$$\begin{aligned} F &= TS \\ &= -T \log P_N(r) \\ &\sim \frac{T}{2} \log [8\pi^3 N a^4 (1 - (r/aN)^2 - 2r/aN L^{-1}(r/aN))] + \frac{rTL^{-1}(r/aN)}{a} \\ &\quad - T \log L^{-1}(r/aN) + T \log r - TN \log \left[\frac{\sinh(L^{-1}(r/aN))}{L^{-1}(r/aN)} \right]. \end{aligned}$$

The restoring force is given by

$$\begin{aligned} f &= -\frac{dF}{dr} \\ &= -\frac{T(-2r/a^2 N^2 - 2/aN L^{-1}(r/aN) + 2rM(r/aN)/(aN L^{-1}(r/aN))^2)}{2(1 - (r/aN)^2 - 2r/aN L^{-1}(r/aN))} \\ &\quad - \frac{TL^{-1}(r/aN)}{a} - \frac{TrM(r/aN)}{Na^2} + T \frac{M(r/aN)}{aN L^{-1}(r/aN)} - T/r \\ &\quad + \frac{TN \coth(L^{-1}(r/aN))M(r/aN)}{Na} - \frac{TNM(r/aN)}{Na L^{-1}(r/aN)} \\ &= \frac{T(-2r/a^2 N^2 - 2/aN L^{-1}(r/aN) + 2rM(r/aN)/(aN L^{-1}(r/aN))^2)}{2(1 - (r/aN)^2 - 2r/aN L^{-1}(r/aN))} \\ &\quad - \frac{TL^{-1}(r/aN)}{a} + T \frac{M(r/aN)}{aN L^{-1}(r/aN)} - T/r \end{aligned}$$

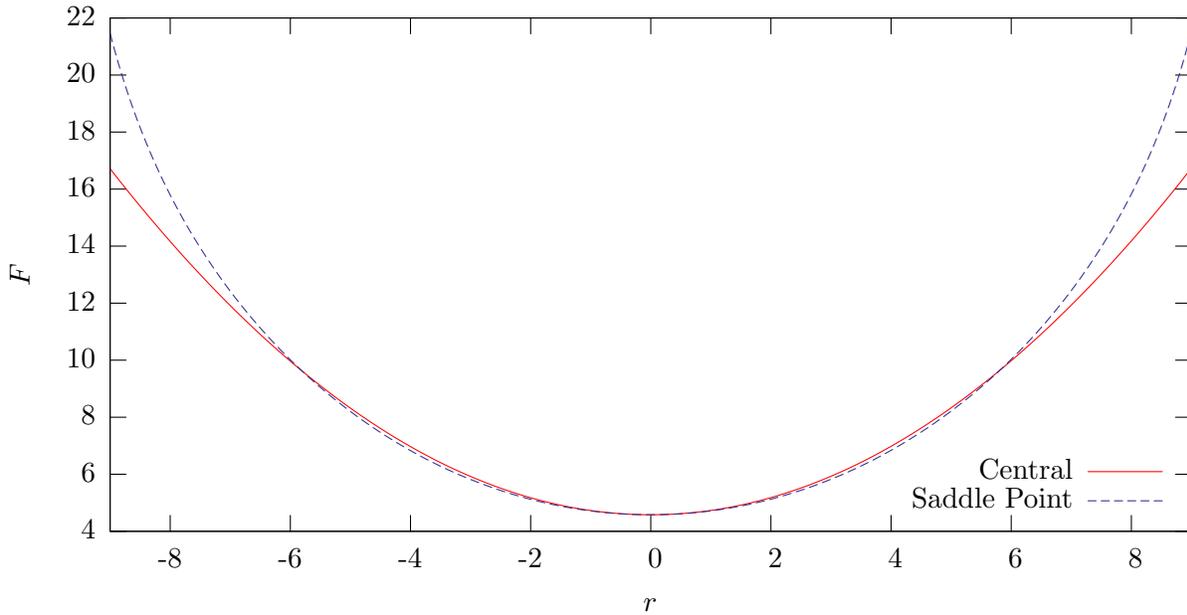


Figure 1: Comparison between the two approximations for free energy for the case when $a = T = 1$ and $N = 10$.

where $M(z)$ is the first derivative of $L^{-1}(z)$. By the inverse function theorem, we know that

$$M(z) = \frac{1}{L'(L^{-1}(z))}.$$

We compare this to the central region approximation, shown on problem set 1 to be

$$P_N^c(r) \sim \left(\frac{3}{2\pi a^2 N}\right)^{3/2} \exp\left(-\frac{3r^2}{2a^2 N}\right).$$

The free energy for this expression is

$$F^c = -\frac{3}{2} \log\left(\frac{3}{2\pi a^2 N}\right) + \frac{3r^2}{2a^2 N}.$$

and the restoring force is

$$f^c \sim -\frac{3r}{a^2 N}.$$

A comparison between the two expressions for free energy and restoring force are shown in figures 1 and 2 respectively. We see a good match in the central region between the two approximations. As $r \rightarrow a$, we see that the restoring force begins to get very large, as would be expected for a highly stretched polymer.

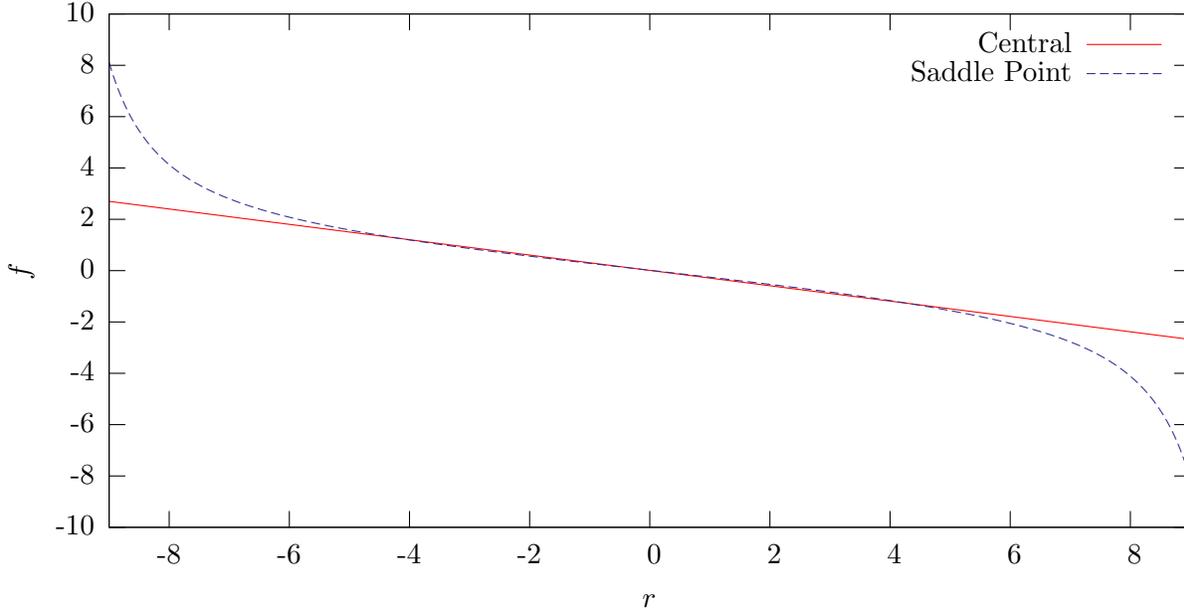


Figure 2: Comparison between the two approximations for the restoring force for the case when $a = T = 1$ and $N = 10$.

2 Linear Polymer Structure

2.1 Mean Total Energy

We define $\eta = \alpha\sigma^2/kT$ so that $p(\theta) \propto e^{\eta \cos \theta}$. The normalizing constant can be found as

$$\begin{aligned} A(\eta) &= \int_0^{2\pi} \int_0^\pi e^{\eta \cos \theta} \sin \theta d\theta d\phi \\ &= 2\pi \frac{e^\eta - e^{-\eta}}{\eta} = 4\pi \frac{\sinh \eta}{\eta}. \end{aligned}$$

Thus we have the normalized $p(\theta)$ as

$$p(\theta) = \frac{1}{A(\eta)} e^{\eta \cos \theta} = \frac{\eta}{4\pi \sinh \eta} e^{\eta \cos \theta}.$$

To get $\langle E_N \rangle$ we first calculate the correlation coefficient $\rho(T)$, which is

$$\rho(T) = \frac{\langle \vec{\Delta x}_n \cdot \vec{\Delta x}_{n+1} \rangle}{a^2} = \langle \cos \theta \rangle.$$

We can get this easily using the derivative of $A(\eta)$:

$$\begin{aligned} \langle \cos \theta \rangle &= \frac{1}{A(\eta)} \int_0^{2\pi} \int_0^\pi \cos \theta e^{\eta \cos \theta} \sin \theta d\theta d\phi \\ &= \frac{1}{A(\eta)} \frac{dA(\eta)}{d\eta} = \coth \eta - \frac{1}{\eta}. \end{aligned}$$

Therefore

$$\langle E_N \rangle = -(N-1)\alpha a^2 \rho(T) = -(N-1)\alpha a^2 \left(\coth \eta - \frac{1}{\eta} \right).$$

2.2 Asymptotic scaling

Since two adjacent steps have correlation $\rho(T)$, the correlation between n -th and $n+m$ -th steps is generally given by

$$\frac{\langle \Delta \vec{x}_n \cdot \Delta \vec{x}_{n+m} \rangle}{a^2} = \rho(T)^m.$$

From the lecture we know

$$\langle R_N^2 \rangle \sim \frac{1 + \rho(T)}{1 - \rho(T)} a^2 \quad \text{and} \quad a_{\text{eff}}(T) \sim \sqrt{\frac{1 + \rho(T)}{1 - \rho(T)}} a \quad \text{as } N \rightarrow \infty.$$

Thus the asymptotic behaviors of $\rho(T)$ and $a_{\text{eff}}(T)$ are

$$\rho(T) = \frac{e^\eta + e^{-\eta}}{e^\eta - e^{-\eta}} - \frac{1}{\eta} = \begin{cases} \frac{\eta}{3} = \frac{3\alpha\sigma^2}{k_B T} & (\eta \rightarrow 0 \text{ or } T \rightarrow \infty) \\ 1 - \frac{1}{\eta} = 1 - \frac{k_B T}{\alpha\sigma^2} & (\eta \rightarrow \infty \text{ or } T \rightarrow 0), \end{cases}$$

$$\frac{a_{\text{eff}}(T)}{a} \sim \begin{cases} 1 + \frac{3\alpha\sigma^2}{k_B T} & (T \rightarrow \infty) \\ \sqrt{\frac{2\alpha\sigma^2}{k_B T}} & (T \rightarrow 0). \end{cases}$$

3 A persistent Lévy flight

First we take the sum of our non-independent steps, each expressed in terms of the independent steps, denoted with primes.

$$X_N = \sum_{n=1}^N \Delta x_n = (1 + \rho)\Delta x'_1 + \sum_{n=2}^{N-1} \Delta x'_n + (1 - \rho)\Delta x'_N.$$

The structure function, $\hat{P}(k)$, of the PDF of $\sum \Delta x_n$ is given by the product of the structure functions associated with each step. The length scales of the first and last steps are renormalized by $1 + \rho$ and $1 - \rho$ respectively. Thus the structure function for the entire walk is given by

$$\hat{P}_N(k) = \exp\{-a(1 + \rho)|k| - a(N - 2)|k| - a(1 - \rho)|k|\} = e^{-aN|k|}$$

and the corresponding PDF as found in Homework 1 is given by

$$P_N(x) = \frac{aN}{\pi(x^2 + a^2 N^2)}.$$

Thus the half-width scales as $\Delta x_{1/2} \sim aN$ and it doesn't depend on ρ at all.

4 A continuous-time random walk

As shown in the lecture notes (2005, lecture 23), if the waiting time distribution is $\psi(t) = e^{-t}$, then the number of steps N that have taken place by time t follows a Poisson distribution

$$\mathcal{P}(N, t) = \frac{t^N}{e^{-t} N!}.$$

We also know that the probability of a Bernoulli walker being at a location x after N steps is

$$P(x, N) = \begin{cases} 2^{-N} \binom{N+x}{2} & \text{for } x + N \text{ even} \\ 0 & \text{for } x + N \text{ odd.} \end{cases}$$

By summing over all possible numbers of steps taken, we find that the probability distribution of the walker being at a location x after time t is

$$P(x, t) = \sum_{N=0}^{\infty} P(x, N) \mathcal{P}(N, t)$$

Only the terms in this sum of the form $N = x + 2m$ where $m = 0, 1, 2, \dots$ will have a non-zero contribution, so

$$\begin{aligned} P(x, t) &= \sum_{m=0}^{\infty} P(x + 2m, t) \mathcal{P}(x + 2m, t) \\ &= \sum_{m=0}^{\infty} \frac{2^{-x-2m} \binom{x+2m}{m} t^{x+2m} e^{-t}}{(x + 2m)!} \\ &= \sum_{m=0}^{\infty} \frac{(t/2)^{x+2m} e^{-t}}{(x + m)! m!} \\ &= I_x(t) e^{-t} \end{aligned}$$

where $I_x(t)$ is the modified Bessel function.