

## CH1, EXERCISES AND FURTHER RESULTS

### A. Manifolds

2. Let  $M$  be a connected manifold and  $p, q$  two points in  $M$ . Then there exists a diffeomorphism  $\Phi$  of  $M$  onto itself such that  $\Phi(p) = q$ .

3. Let  $M$  be a Hausdorff space and let  $\delta$  and  $\delta'$  be two differentiable structures on  $M$ . Let  $\mathfrak{F}$  and  $\mathfrak{F}'$  denote the corresponding sets of  $C^\infty$  functions. Then  $\delta = \delta'$  if and only if  $\mathfrak{F} = \mathfrak{F}'$ .

Deduce that the real line  $\mathbf{R}$  with its ordinary topology has infinitely many different differentiable structures.

4. Let  $\Phi$  be a differentiable mapping of a manifold  $M$  onto a manifold  $N$ . A vector field  $X$  on  $M$  is called *projectable* (Koszul [1]) if there exists a vector field  $Y$  on  $N$  such that  $d\Phi \cdot X = Y$ .

(i) Show that  $X$  is projectable if and only if  $X\mathfrak{F}_0 \subset \mathfrak{F}_0$  where  $\mathfrak{F}_0 = \{f \circ \Phi : f \in C^\infty(N)\}$ .

(ii) A necessary condition for  $X$  to be projectable is that

$$d\Phi_p(X_p) = d\Phi_q(X_q) \quad (1)$$

whenever  $\Phi(p) = \Phi(q)$ . If, in addition,  $d\Phi_p(M_p) = N_{\Phi(p)}$  for each  $p \in M$ , this condition is also sufficient.

(iii) Let  $M = \mathbf{R}$  with the usual differentiable structure and let  $N$  be the topological space  $\mathbf{R}$  with the differentiable structure obtained by requiring the homeomorphism  $\psi : x \rightarrow x^{1/3}$  of  $M$  onto  $N$  to be a diffeomorphism. In this case the identity mapping  $\Phi : x \rightarrow x$  is a differentiable mapping of  $M$  onto  $N$ . The vector field  $X = \partial_j \partial x$  on  $M$  is not projectable although (1) is satisfied.

5. Deduce from §3.1 that diffeomorphic manifolds have the same dimension.

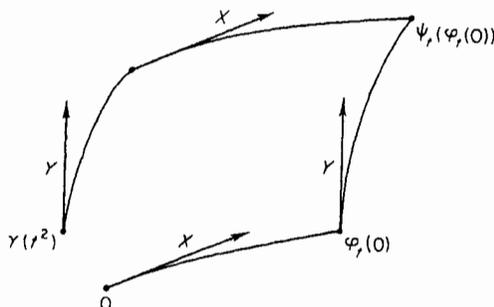
7. Let  $M$  be a manifold,  $p \in M$ , and  $X$  a vector field on  $M$  such that  $X_p \neq 0$ . Then there exists a local chart  $\{x_1, \dots, x_m\}$  on a neighborhood  $U$  of  $p$  such that  $X = \partial_j \partial x_1$  on  $U$ . Deduce that the differential equation  $Xu = f$  ( $f \in C^\infty(M)$ ) has a solution  $u$  in a neighborhood of  $p$ .

8. Let  $M$  be a manifold and  $X, Y$  two vector fields both  $\neq 0$  at a point  $o \in M$ . For  $p$  close to  $o$  and  $s, t \in \mathbb{R}$  sufficiently small let  $\varphi_s(p)$  and  $\psi_t(p)$  denote the integral curves through  $p$  of  $X$  and  $Y$ , respectively. Let

$$\gamma(t) = \psi_{-s}(\varphi_{-s}(\psi_{s}(\varphi_{s}(o))))$$

Prove that

$$[X, Y]_o = \lim_{t \rightarrow 0} \dot{\gamma}(t)$$



(Hint: The curves  $t \rightarrow \varphi_t(\varphi_s(p))$  and  $t \rightarrow \varphi_{t+s}(p)$  must coincide; deduce  $(X^n f)(p) = [d^n/dt^n f(\varphi_t \cdot p)]_{t=0}$ .)

## B. The Lie Derivative and the Interior Product

1. Let  $M$  be a manifold,  $X$  a vector field on  $M$ . The Lie derivative  $\theta(X): \mathfrak{D}^1(M) \rightarrow \mathfrak{D}^1(M)$  which maps  $\mathfrak{D}^1(M)$  into itself can be extended uniquely to a mapping of  $\mathfrak{D}(M)$  into itself such that:

- (i)  $\theta(X)f = Xf$  for  $f \in C^\infty(M)$ .
- (ii)  $\theta(X)$  is a derivation of  $\mathfrak{D}(M)$  preserving type of tensors.
- (iii)  $\theta(X)$  commutes with contractions.

2. Let  $\Phi$  be a diffeomorphism of a manifold  $M$  onto itself. Then  $\Phi$  induces a unique type-preserving automorphism  $T \rightarrow \Phi \cdot T$  of the tensor algebra  $\mathfrak{D}(M)$  such that:

- (i) The automorphism commutes with contractions.
- (ii)  $\Phi \cdot X = X^\Phi$ , ( $X \in \mathfrak{D}^1(M)$ ),  $\Phi \cdot f = f^\Phi$ , ( $f \in C^\infty(M)$ ).

Prove that  $\Phi \cdot \omega = (\Phi^{-1})^* \omega$  for  $\omega \in \mathfrak{D}_*(M)$ .

3. Let  $g_t$  be a one-parameter Lie transformation group of  $M$  and denote by  $X$  the vector field on  $M$  induced by  $g_t$  (Chapter II, §3). Then

$$\theta(X)T = \lim_{t \rightarrow 0} \frac{1}{t} (T - g_t \cdot T)$$

for each tensor field  $T$  on  $M$  ( $g_t \cdot T$  is defined in Exercise 2).

4. The Lie derivative  $\theta(X)$  on a manifold  $M$  has the following properties:

- (i)  $\theta([X, Y]) = \theta(X)\theta(Y) - \theta(Y)\theta(X)$ ,  $X, Y \in \mathfrak{D}^1(M)$ .
- (ii)  $\theta(X)$  commutes with the alternation  $A: \mathfrak{D}_*(M) \rightarrow \mathfrak{A}(M)$  and therefore induces a derivation of the Grassmann algebra of  $M$ .
- (iii)  $\theta(X)d = d\theta(X)$ , that is,  $\theta(X)$  commutes with exterior differentiation.

5. For  $X \in \mathcal{D}^1(M)$  there is a unique linear mapping  $i(X) : \mathfrak{A}(M) \rightarrow \mathfrak{A}(M)$ , the *interior product*, satisfying:

- (i)  $i(X)f = 0$  for  $f \in C^\infty(M)$ .
- (ii)  $i(X)\omega = \omega(X)$  for  $\omega \in \mathfrak{A}_1(M)$ .
- (iii)  $i(X) : \mathfrak{A}_r(M) \rightarrow \mathfrak{A}_{r-1}(M)$  and

$$i(X)(\omega_1 \wedge \omega_2) = i(X)\omega_1 \wedge \omega_2 + (-1)^r \omega_1 \wedge i(X)\omega_2$$

if  $\omega_1 \in \mathfrak{A}_r(M)$ ,  $\omega_2 \in \mathfrak{A}(M)$ .

6. (cf. H. Cartan [1]). Prove that if  $X, Y \in \mathcal{D}^1(M)$ ,  $\omega_1, \dots, \omega_r \in \mathfrak{A}_1(M)$ ,

- (i)  $i(X)^2 = 0$ .
- (ii)  $i(X)(\omega_1 \wedge \dots \wedge \omega_r) = \sum_{1 \leq k \leq r} (-1)^{k+1} \omega_k(X) \omega_1 \wedge \dots \wedge \hat{\omega}_k \wedge \dots \wedge \omega_r$ ;  
 $\omega_i \in \mathfrak{A}_1(M)$ .
- (iii)  $i([X, Y]) = \theta(X)i(Y) - i(Y)\theta(X)$ .
- (iv)  $\theta(X) = i(X)d + di(X)$ .

### C. Affine Connections

2. Let  $\nabla$  be the affine connection on  $R^n$  determined by  $\nabla_X(Y) = 0$  for  $X = \partial/\partial x_i$ ,  $Y = \partial/\partial x_j$ ,  $1 \leq i, j \leq n$ . Find the corresponding affine transformations.

4. Let  $M$  be a manifold with a torsion-free affine connection  $\nabla$ . Suppose  $X_1, \dots, X_m$  is a basis for the vector fields on an open subset  $U$  of  $M$ . Let the forms  $\omega^1, \dots, \omega^m$  on  $U$  be determined by  $\omega^i(X_j) = \delta^i_j$ . Prove the formula

$$d\theta = \sum_{i=1}^m \omega^i \wedge \nabla_{X_i}(\theta)$$

for each differential form  $\theta$  on  $U$ .

5. Let  $S$  be a surface in  $R^3$ ,  $X$  and  $Y$  two vector fields on  $S$ . Let  $s \in S$ ,  $X_s \neq 0$  and  $t \rightarrow \gamma(t)$  a curve on  $S$  through  $s$  such that  $\dot{\gamma}(t) = X_{\gamma(t)}$ ,  $\gamma(0) = s$ . Viewing  $Y_{\gamma(t)}$  as a vector in  $R^3$  and letting  $\pi_s : R^3 \rightarrow S_s$  denote the orthogonal projection put

$$\nabla'_X(Y)_s = \pi_s(\lim_{t \rightarrow 0} \frac{1}{t} (Y_{\gamma(t)} - Y_s)).$$

Prove that this defines an affine connection on  $S$ .

#### D. Submanifolds

1. Let  $M$  and  $N$  be differentiable manifolds and  $\Phi$  a differentiable mapping of  $M$  into  $N$ . Consider the mapping  $\varphi : m \rightarrow (m, \Phi(m))$  ( $m \in M$ ) and the graph

$$G_\Phi = \{(m, \Phi(m)) : m \in M\}$$

of  $\Phi$  with the topology induced by the product space  $M \times N$ . Then  $\varphi$  is a homeomorphism of  $M$  onto  $G_\Phi$  and if the differentiable structure of  $M$  is transferred to  $G_\Phi$  by  $\varphi$ , the graph  $G_\Phi$  becomes a closed submanifold of  $M \times N$ .

2. Let  $N$  be a manifold and  $M$  a topological space,  $M \subset N$  (as sets).

Show that there exists at most one differentiable structure on the topological space  $M$  such that  $M$  is a submanifold of  $N$ .

3. Using the figure 8 as a subset of  $\mathbb{R}^2$  show that

(i) A closed connected submanifold of a connected manifold does not necessarily carry the relative topology.

(ii) A subset  $M$  of a connected manifold  $N$  may have two different topologies and differentiable structures such that in both cases  $M$  is a submanifold of  $N$ .

4. Let  $M$  be a submanifold of a manifold  $N$  and suppose  $M = N$  (as sets). Assuming  $M$  to have a countable basis for the open sets, prove that  $M = N$  (as manifolds). (Use Prop. 3.2 and Lemma 3.1, Chapter II.)

### E. The Hyperbolic Plane

1. Let  $D$  be the open disk  $|z| < 1$  in  $\mathbb{R}^2$  with the usual differentiable structure but given the Riemannian structure

$$g(u, v) = \frac{(u, v)}{(1 - |z|^2)^2} \quad (u, v \in D_z)$$

$(\cdot, \cdot)$  denoting the usual inner product on  $\mathbb{R}^2$ .

(i) Show that the angle between  $u$  and  $v$  in the Riemannian structure  $g$  coincides with the Euclidean angle.

(ii) Show that the Riemannian structure can be written

$$g = \frac{dx^2 + dy^2}{(1 - x^2 - y^2)^2} \quad (z = x + iy).$$

(iii) Show that the arc length  $L$  satisfies

$$L(\gamma_0) \leq L(\gamma)$$

if  $\gamma$  is any curve joining the origin  $0$  and  $x$  ( $0 < x < 1$ ) and  $\gamma_0(t) = tx$  ( $0 \leq t \leq 1$ ).

(iv) Show that the transformation

$$\varphi : z \rightarrow \frac{az + b}{bz + a} \quad (|a|^2 - |b|^2 = 1)$$

is an isometry of  $D$ .

(v) Deduce from (iii) and (iv) that the geodesics in  $D$  are the circular arcs perpendicular to the boundary  $|z| = 1$ .

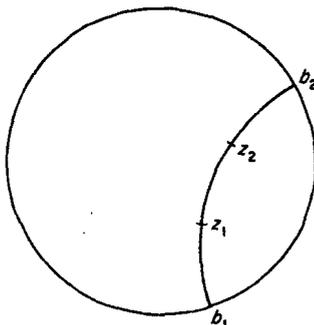
(vi) Prove from (iii) that

$$d(0, z) = \frac{1}{2} \log \frac{1 + |z|}{1 - |z|} \quad (z \in D)$$

and using (iv) that

$$d(z_1, z_2) = \frac{1}{2} \log \left( \frac{z_1 - b_2}{z_1 - b_1} : \frac{z_2 - b_2}{z_2 - b_1} \right) \quad (z_1, z_2 \in D)$$

with  $b_1$  and  $b_2$  as in the figure.



(vii) Show that the maps  $\varphi$  in (iv) together with the complex conjugation  $z \rightarrow \bar{z}$  generate the group of all isometries of  $D$ .