

MIT OpenCourseWare
<http://ocw.mit.edu>

18.969 Topics in Geometry: Mirror Symmetry
Spring 2009

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.

MIRROR SYMMETRY: LECTURE 22

DENIS AUROUX

1. SYZ CONJECTURE (CNTD.)

Recall:

Proposition 1. *First order deformations of special Lagrangian L in a strict (resp. almost) Calabi-Yau manifold are given by $\mathcal{H}^1(L, \mathbb{R})$ (resp. $\mathcal{H}_\psi^1(L, \mathbb{R})$), where*

$$(1) \quad H_\psi^1(L, \mathbb{R}) = \{\beta \in \Omega^1(L, \mathbb{R}) \mid d\beta = 0, d^*(\psi\beta) = 0\}$$

It is still true that $\mathcal{H}_\psi^1(L, \mathbb{R}) \cong H^1(L, \mathbb{R})$.

Theorem 1 (McLean, Joyce). *Deformations of special Lagrangians are unobstructed, i.e. the moduli space of special Lagrangians is a smooth manifold B with $T_L B \cong \mathcal{H}_\psi^1(L, \mathbb{R}) \cong H^1(L, \mathbb{R})$.*

There are two canonical isomorphisms $T_L B \xrightarrow{\sim} H^1(L, \mathbb{R}), v \mapsto [-\iota_v \omega]$ (“symplectic”) and $T_L B \xrightarrow{\sim} H^{n-1}(L, \mathbb{R}), v \mapsto [\iota_v \text{Im } \Omega]$ “complex”.

Definition 1. *An affine structure on a manifold N is a set of coordinate charts with transition functions in $GL(n, \mathbb{Z}) \ltimes \mathbb{R}^n$.*

Corollary 1. *B carries two affine structures.*

For affine manifolds, mirror symmetry exchanges the two affine structures. Our particular case of interest is that of special Lagrangian tori, so $\dim H^1 = n$. The usual harmonic 1-forms on flat T^n have no zeroes, and give a pointwise basis of T^*L . We will make a standing assumptions that ψ -harmonic 1-forms for $g|_L$ have no zeroes (at least ok for $n \leq 2$). Then a neighborhood of L is fibered by special Lagrangian deformations of L : locally,

$$(2) \quad \begin{array}{ccc} T^n & \longrightarrow & U \subset X \\ & & \downarrow \pi \\ & & V \subset B \end{array}$$

In local affine coordinates, we pick a basis $\gamma_1, \dots, \gamma_n \in H_1(L, \mathbb{Z})$: deforming from L to L' , the deformation of γ_i gives a cylinder Γ_i , and we set $x_i = \int_{\Gamma_i} \omega$ (the flux of the deformation $L \rightarrow L'$). These are affine coordinates on the symplectic

side. On the complex side, pick a basis $\gamma_1^*, \dots, \gamma_n^* \in H_{n-1}(L, \mathbb{Z})$, construct the associated Γ_i^* , and set $x_i^* = \int_{\Gamma_i^*} \text{Im } \Omega$. Globally, there is a monodromy $\pi_1(B, *) \rightarrow \text{Aut } H^*(L, \mathbb{Z})$. In our case, the monodromies in $GL(H^1(L, \mathbb{Z})), GL(H^{n-1}(L, \mathbb{Z}))$ are transposes of each other.

1.1. Prototype construction of a mirror pair. Let B be an affine manifold, $\Lambda \subset TB$ the lattice of integer vectors. Then TB/Λ is a torus bundle over B , and carries a natural complex structure, e.g.

$$(3) \quad T(\mathbb{R}^n) \cong \mathbb{C}^n, \mathbb{C}^n = \mathbb{R}^n \oplus \mathbb{R}^n, GL(n, \mathbb{Z}) \ni A \mapsto \begin{pmatrix} A & 0 \\ 0 & A \end{pmatrix}$$

Setting $\Lambda^* = \{p \in T^*B \mid p(\Lambda) \subset \mathbb{Z}\}$ to be the dual lattice of integer covectors, we find that T^*B/Λ^* has a natural symplectic structure since $GL(n, \mathbb{Z}) \ni A \mapsto \begin{pmatrix} A & 0 \\ 0 & A^T \end{pmatrix} \in \text{Sp}(2n)$.

In our case, we have two affine structures with dual monodromies

$$(4) \quad \begin{array}{ccc} TB & \xrightarrow{\sim} & T^*B \\ \sim \downarrow cx & & \text{symp} \downarrow \sim \\ H^{n-1}(L, \mathbb{R}) & \xrightarrow{\sim PD} & H_1(L, \mathbb{R}) \\ \uparrow & & \uparrow \\ \Lambda_c = H^{n-1}(L, \mathbb{Z}) & \xrightarrow{\sim} & H_1(L, \mathbb{Z}) = \Lambda_s^* \end{array}$$

so the complex manifold TB/Λ_c is diffeomorphic to the symplectic manifold T^*B/Λ_s^* . Dually, $X^\vee \cong T^*B/\Lambda_c^* \cong TB/\Lambda_s$.

1.2. More explicit constructions [cf. Hitchin]. Let

$$(5) \quad M = \{(L, \nabla) \mid L \text{ a special Lagrangian torus in } X, \\ \nabla \text{ flat } U(1) - \text{conn on } \mathbb{C} \times L \text{ mod gauge}\}$$

i.e. $\nabla = d + iA, iA \in \Omega^1(L, i\mathbb{R}), dA = 0 \text{ mod exact forms}$.

$$(6) \quad \begin{aligned} T_{(L, \nabla)} M &= \{(v, i\alpha) \in C^\infty(NL) \oplus \Omega^1(L; i\mathbb{R}) \mid -\iota_v \omega \in \mathcal{H}_\psi^1(L, \mathbb{R}), d\alpha = 0 \text{ mod Im } (d)\} \\ &= \{(v, i\alpha) \in C^\infty(NL) \oplus \Omega^1(L; i\mathbb{R}) \mid -\iota_v \omega + i\alpha \in \mathcal{H}_\psi^1(L; \mathbb{C})\} \\ &= H_\psi^1(L, \mathbb{C}) \end{aligned}$$

which is a complex vector space, and J^\vee is an almost-complex structure.

Proposition 2. J^\vee is integrable.

Proof. We build local holomorphic coordinates. Let $\gamma_1, \dots, \gamma_n$ be a basis of $H_1(L, \mathbb{Z})$, and assume $\gamma_i = \partial\beta_i, \beta_i \in H_2(X, L)$. Set

$$(7) \quad z_i(L, \nabla) = \underbrace{\exp\left(-\int_{\beta_i} \omega\right)}_{\mathbb{R}_+} \underbrace{\text{hol}_{\nabla}(\gamma_i)}_{U(1)} \in \mathbb{C}^*$$

Then

$$(8) \quad \text{dlog } z_i : (v, i\alpha) \mapsto -\int_{\gamma_i} \iota_v \omega + \int_{\gamma_i} i\alpha = \underbrace{\langle [-\iota_v \omega + i\alpha], \gamma_i \rangle}_{H^1(L, \mathbb{C})}$$

is \mathbb{C} -linear. If there are no such β_i , we instead use a deformation tube as constructed earlier. Warning: all of our formulas are up to (i.e. may be missing) a factor of 2π . \square

Next, consider the holomorphic $(n, 0)$ -form on M

$$(9) \quad \Omega^\vee((v_1, i\alpha_1), \dots, (v_n, i\alpha_n)) = \int_L (-\iota_{v_1} \omega + i\alpha_1) \wedge \dots \wedge (-\iota_{v_n} \omega + i\alpha_n)$$

After normalizing $\int_L \Omega = 1$, we have a Kähler form

$$(10) \quad \omega^\vee((v_1, i\alpha_1), (v_2, i\alpha_2)) = \int_L \alpha_2 \wedge (\iota_{v_1} \text{Im } \Omega) - \alpha_1 \wedge (\iota_{v_2} \text{Im } \Omega)$$

Proposition 3. ω^\vee is a Kähler form compatible with J^\vee .

Proof. Pick a basis $[\gamma_i]$ of $H_{n-1}(L, \mathbb{Z})$ with a dual basis $[e_i]$ of $H_1(L, \mathbb{Z})$, i.e. $e_i \cap \gamma_j = \delta_{ij}$. For all $a \in H^1(L), b \in H^{n-1}(L)$

$$(11) \quad \langle a \cup b, [L] \rangle = \sum_i \langle a, e_i \rangle \langle b, \gamma_i \rangle$$

Letting $a = \sum a_i dx_i, b = \sum b_i (-1)^{i-1} (dx_1 \wedge \dots \wedge \widehat{dx_i} \wedge \dots \wedge dx_n)$, $\int_{T^n} a \wedge b = \sum a_i b_i$. Again, take a deformation from L_0 to L' , C_i the tube (an n -chain) formed by the deformation of γ_i , and set $p_i = \int_{C_i} \text{Im } \Omega, \theta_i = \int_{e_i} A$ for A the connection 1-form (i.e. $\text{hol}_{e_i}(\nabla) = \exp(i\theta_i)$). Then

$$(12) \quad \begin{aligned} dp_i : (v, i\alpha) &\mapsto \int_{\gamma_i} \iota_v \text{Im } \Omega = \langle [\iota_v \text{Im } \Omega], \gamma_i \rangle \\ d\theta_i : (v, i\alpha) &\mapsto \int_{e_i} \alpha = \langle [\alpha], e_i \rangle \end{aligned}$$

By (11), $\omega^\vee = \sum dp_i \wedge d\theta_i$, implying that ω^\vee is closed, and

$$\begin{aligned}
 \omega^\vee((v_1, \alpha_1), (v_2, \alpha_2)) &= \int_L \alpha_2 \wedge (-\psi *_g \iota_{v_1} \omega) - \alpha_1 \wedge (-\psi *_g \iota_{v_2} \omega) \\
 (13) \qquad \qquad \qquad &= \int_L \psi \cdot (\langle \alpha_1, \iota_{v_2} \omega \rangle_g - \langle \alpha_2, \iota_{v_1} \omega \rangle_g) \text{vol}_g \\
 \omega^\vee((v_1, \alpha_1), J^\vee(v_2, \alpha_2)) &= \int_L \psi \cdot (\langle \alpha_1, \alpha_2 \rangle_g + \langle \iota_v \omega, \iota_{v_2} \omega \rangle_g) \text{vol}_g
 \end{aligned}$$

which is clearly a Riemannian metric. □