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Simplicity
Theory.

Frank.

Wagner's book. Simple Theories.

+ various articles.

Nice Paper: From Stability to Simplicity / Kim & Pillay JSL?

Stability = theory of independence + multiplicity.
 simplicity

types over models have
unique extensions.

Framework of F.O. model theory.

- Organisation:
1. Basic Definitions & Framework
 2. Simplicity & independence.
 3. Canonical Bases.
 4. "Generic Constructions" - adding random predicate etc.
 5. "Simple" groups.
 6. Lovely Pairs.
- Basic stuff
everyone should
know.

Analogue of Monster Model in CAT.

Defn: Let \mathcal{L} be a signature, $\Delta \subseteq \mathcal{L}_{\omega, \omega}^{\text{FO}}$. (set of fo. formulas).

Assume that Δ is closed under positive boolean combinations.
 Then Δ is a positive fragment of \mathcal{L} . $\vee \wedge$.

We fix a positive fragment Δ . A "formula" always means a formula from Δ .

* Work in purely relational language or Δ is closed under substitution of terms for variable.

Definition: An \mathcal{L} -structure \mathcal{U} is a κ -universal domain

(κ is a cardinal) if it satisfies:

1. Homogeneity: If $A \subseteq \mathcal{U}$ & $|A| < \kappa$ and $f: A \rightarrow \mathcal{U}$ is a mapping s.t. $\forall \varphi(\bar{x}) \in \Delta \quad \forall \bar{a} \in A$, if $\mathcal{U} \models \varphi(\bar{a}) \Rightarrow \mathcal{U} \models \varphi(f(\bar{a}))$.

[We say that f is a partial Δ -endomorphism of \mathcal{U} .]

Then $\exists \tilde{f} \in \text{Aut}(\mathcal{U})$ which extends f .

(2). Compactness: If $\Sigma(\bar{x})$ is a set of Δ -formulas where \bar{x} is a possibly infinite tuple of variables, then either $\Sigma(\bar{x})$ is realised in \mathcal{U} (ie $\exists \bar{a} \in \mathcal{U}$ st. $\mathcal{U} \models \Sigma(\bar{a})$) or there is $\Sigma_0 \subseteq \Sigma$ finite which is not realised.

Important

Fact: Assume \mathcal{U} is a universal domain. $\bar{a} \in \mathcal{U}$. $\varphi(\bar{x}) \in \Sigma$ and $\mathcal{U} \not\models \varphi(\bar{a})$. $\exists \bar{y} \varphi(\bar{a}, \bar{y})$.

Then there is a formula $\psi(\bar{x}) \in \Delta$ st.

- ① $\mathcal{U} \models \psi(\bar{a})$.
- ② $\mathcal{U} \models \forall \bar{x} (\psi(\bar{x}) \rightarrow \exists \bar{y} \varphi(\bar{x}, \bar{y}))$.

Proof Set $p(\bar{x}) = \text{tp}(\bar{a}) := \{x(\bar{x}) \in \Delta : \mathcal{U} \models x(\bar{a})\}$

Then $p(\bar{x}) \cup \varphi(\bar{x}, \bar{y})$ is not realised in \mathcal{U} by homogeneity.

(otherwise we'd get $\bar{c}, \bar{d} \in \mathcal{U}$ st. $p(\bar{c}) \wedge \varphi(\bar{c}, \bar{d})$).

so $f: \bar{a} \mapsto \bar{c}$ is a partial endomorphism extending to an automorphism F and then $\mathcal{U} \models \varphi(\bar{a}, f'(\bar{d}))$

by compactness: $\exists x(\bar{x}) \in p(\bar{x})$ st. $x(\bar{x}) \wedge \varphi(\bar{x}, \bar{y})$ is not realised in \mathcal{U} . \square

Remark: IF \mathcal{U} is a universal domain wrt Δ and

$$\Delta' = \exists \Delta := \{ \exists \bar{y} \varphi(\bar{x}, \bar{y}) : \varphi \in \Delta \}$$

Then \mathcal{U} is a universal domain wrt Δ' .

Proof Homogeneity becomes easier ✓

Compactness: by replacing each $\exists \bar{y} \varphi(\bar{x}, \bar{y})$ with $\varphi(\bar{x}, \bar{y}_p)$

new variables

Therefore we allow ourselves the following additional assumption:

Convention: For every $\varphi(\bar{x}, \bar{y}) \in \Delta$, the formula $\exists \bar{y} \varphi(\bar{x}, \bar{y})$ is equivalent in \mathcal{U} to a partial Δ -type.

We say that \mathcal{U} is a universal domain for $T = \text{Th}(\mathcal{U})$
 where $\text{Th}(\mathcal{U}) = \{ \exists \vec{x} \forall \vec{y} \varphi(\vec{x}), : \varphi \in \Delta, \mathcal{U} \models \varphi \}$.

Lemma:
Defn:

$$S_\Delta(T) = \{ \text{tp}(\vec{a}) : \vec{a} \in \mathcal{U}^n \} = \{ \text{all maximal sets of } \Delta\text{-formulas in } (x_0 \dots x_{n-1}) = \vec{x} \text{ consistent with } T \}$$

Proof ① Let $p(\vec{x}) = \text{tp}(\vec{a})$ where $\vec{a} \in \mathcal{U}^n$.
 Then $p(\vec{x})$ is consistent with T since $\mathcal{U} \models p(\vec{a}) \cup T$.

What if not?

If $\varphi(\vec{x}) \notin p(\vec{x})$ (but $\varphi \in \Delta$). then $\mathcal{U} \not\models \varphi(\vec{a})$.
 So by the fact, there is $\psi(\vec{x}) \in p(\vec{x})$ st.
 $\mathcal{U} \models \underbrace{\exists \vec{x} \varphi(\vec{x}) \wedge \psi(\vec{x})}_{\in T}$; (by the fact).

so $p(\vec{x}) \cup \{\varphi(\vec{x})\} \cup T$ is inconsistent.
 $\Rightarrow p$ is maximal.

② Assume that $p(\vec{x})$ is maximal consistent with T .
 Since it is inconsistent with T , it is realized in \mathcal{U} (by compactness).
 Say by $\vec{a} : \mathcal{U} \models p(\vec{a})$.

Then $p(\vec{x}) \subseteq \text{tp}(\vec{a})$. and $\text{tp}(\vec{a})$ is consistent with T .
 So by maximality $p = \text{tp}(\vec{a})$. \square .

From homogeneity, two types are the same type \Leftrightarrow they correspond by an automorphism of \mathcal{U} .

Therefore $S_\Delta(T) \cong \mathcal{U}^\omega / \text{Aut}(\mathcal{U})$. orbits of action of Aut \mathcal{U} on \mathcal{U}^ω .
 ↑
 possibly infinite

The logic topology on $S_\Delta(T)$: If $\varphi(x) \in \Delta$, then $\langle \varphi \rangle \subseteq S_\Delta(T) := \{ p(\vec{x}) : \varphi(\vec{x}) \in p \}$

The topology sets are generated by the sets of this form.

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This is a compact topology.