

1.1.5 A related open problem

We now show an interesting open problem posed by Mallat and Zeitouni at [MZ11]

Open Problem 1.1 (Mallat and Zeitouni [MZ11]) *Let $g \sim \mathcal{N}(0, \Sigma)$ be a gaussian random vector in \mathbb{R}^p with a known covariance matrix Σ and $d < p$. Now, for any orthonormal basis $V = [v_1, \dots, v_p]$ of \mathbb{R}^p , consider the following random variable Γ_V : Given a draw of the random vector g , Γ_V is the squared ℓ_2 norm of the largest projection of g on a subspace generated by d elements of the basis V . The question is:*

What is the basis V for which $\mathbb{E}[\Gamma_V]$ is maximized?

The conjecture in [MZ11] is that the optimal basis is the eigendecomposition of Σ . It is known that this is the case for $d = 1$ (see [MZ11]) but the question remains open for $d > 1$. It is not very difficult to see that one can assume, without loss of generality, that Σ is diagonal.

A particularly intuitive way of stating the problem is:

1. Given $\Sigma \in \mathbb{R}^{p \times p}$ and d
2. Pick an orthonormal basis v_1, \dots, v_p
3. Given $g \sim \mathcal{N}(0, \Sigma)$
4. Pick d elements $\tilde{v}_1, \dots, \tilde{v}_d$ of the basis
5. **Score:** $\sum_{i=1}^d (\tilde{v}_i^T g)^2$

The objective is to pick the basis in order to maximize the expected value of the **Score**.

Notice that if the steps of the procedure were taken in a slightly different order on which step 4 would take place before having access to the draw of g (step 3) then the best basis is indeed the eigenbasis of Σ and the best subset of the basis is simply the leading eigenvectors (notice the resemblance with PCA, as described above).

More formally, we can write the problem as finding

$$\operatorname{argmax}_{\substack{V \in \mathbb{R}^{p \times p} \\ V^T V = I}} \left(\mathbb{E} \left[\max_{\substack{S \subset [p] \\ |S|=d}} \sum_{i \in S} (v_i^T g)^2 \right) \right],$$

where $g \sim \mathcal{N}(0, \Sigma)$. The observation regarding the different ordering of the steps amounts to saying that the eigenbasis of Σ is the optimal solution for

$$\operatorname{argmax}_{\substack{V \in \mathbb{R}^{p \times p} \\ V^T V = I}} \left(\max_{\substack{S \subset [p] \\ |S|=d}} \mathbb{E} \left[\sum_{i \in S} (v_i^T g)^2 \right) \right].$$

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[MZ11] S. Mallat and O. Zeitouni. A conjecture concerning optimality of the karhunen-loeve basis in nonlinear reconstruction. Available online at [arXiv:1109.0489 \[math.PR\]](https://arxiv.org/abs/1109.0489), 2011.

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