

1) $u = ax^2 + bxy + cy^2$

$$w = 0$$

find v $v(y=0) = 0$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \Rightarrow \frac{\partial u}{\partial x} = -\frac{\partial v}{\partial y}$$

$$\frac{\partial u}{\partial x} = 2ax + by + 0 = -\frac{\partial v}{\partial y}$$

$$\int \partial v = -(2ax + by) dy \Rightarrow v = (2axy + \frac{by^2}{2}) = -2axy - \frac{by^2}{2}$$

$$\boxed{v = -2axy - \frac{by^2}{2}}$$

i) Total acceleration of $\vec{u} \Rightarrow \frac{D\vec{u}}{Dt} = \frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u}$

$$\vec{u} \cdot \vec{\nabla} \vec{u} = ? \quad \text{let } \vec{u} = 2yt\hat{i} + xt\hat{j} + xy^2\hat{k} \quad [\text{m/sec}]$$

if we let $\vec{u}_i = u\hat{i} + v\hat{j} + w\hat{k}$

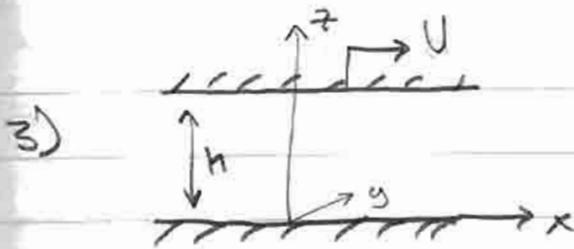
$$\text{then } \vec{u}_i \cdot \vec{\nabla} \vec{u}_i = \left(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}\right)\hat{i} + \left(u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}\right)\hat{j} + \left(u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}\right)\hat{k}$$

now substitute

$$\vec{u} \cdot \vec{\nabla} \vec{u} = (2y \cdot 0 + xt \cdot 2 + xy^2 \cdot 0)\hat{i} + (2y \cdot t + xt \cdot 0 + xy^2 \cdot 0)\hat{j} + (2y \cdot 0 + xt \cdot 2xy + xy^2 \cdot 0)\hat{k}$$

$$\vec{u} \cdot \vec{\nabla} \vec{u} = 2xt\hat{i} + 2yt\hat{j} + (2y^3 + 2x^2yt)\hat{k}$$

$$\frac{\partial \vec{u}}{\partial t} = x\hat{j} \Rightarrow \frac{D\vec{u}}{Dt} = 2xt\hat{i} + (x + 2yt)\hat{j} + (2y^3 + 2x^2yt)\hat{k}$$



$$V = 0 \quad W = 0$$

$$u = \frac{Uz}{h} \quad \left\{ \begin{array}{l} u=0 @ z=0 \\ u=U @ z=h \end{array} \right.$$

a) by continuity equation $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

\downarrow
 $0 \neq 0 \quad 0 = 0$

$\therefore \frac{\partial u}{\partial x} = 0$ Plug into navier stokes equations

ignoring coriolis forces and gravity.

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

\downarrow
 $0 \neq 0 \quad v=0 \quad w=0$

\downarrow
 0 steady

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right)$$

\downarrow
 $0 \quad 0 \quad 0 \quad v=0 \quad v=0 \quad v=0$

\downarrow
 $v=0 \quad v=0 \quad v=0$

\downarrow
 $\frac{\partial v}{\partial x} = 0 \quad \text{no change in } y$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)$$

\downarrow
 $0 \quad 0 \quad 0 \quad w=0 \quad w=0 \quad w=0$

\downarrow
 $w=0 \quad \frac{\partial p}{\partial w} = 0$

let $M = g \cdot \nu$

$$\therefore \frac{\partial p}{\partial x} = \mu \frac{\partial^2 u}{\partial z^2} \quad u = \frac{Uz}{h} \quad \frac{\partial^2 u}{\partial z^2} = 0$$

$$\frac{\partial p}{\partial x} = 0 \quad \therefore P = \text{constant!}$$

b) suppose $\frac{\partial P}{\partial x} = K$

what is the velocity distribution?

$$\frac{\partial P}{\partial x} = K = \mu \frac{\partial^2 u}{\partial z^2} \Rightarrow \partial z^2 \cdot K = \mu \partial^2 u$$

$$\partial^2 u = \frac{K}{\mu} \partial z^2$$

$$\frac{\partial u}{\partial z} = \frac{K}{\mu} z + C_1$$

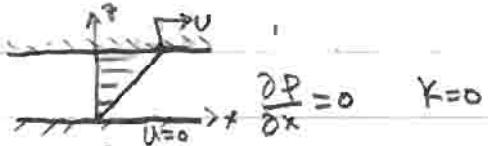
$$u = \frac{K}{\mu} \frac{z^2}{2} + C_1 z + C_2$$

$$u = 0 @ z=0 \Rightarrow C_2 = 0$$

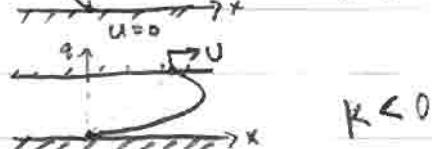
$$\vec{u} = U @ z=h \Rightarrow C_1 = \frac{U}{h} - \frac{Kh}{2\mu}$$

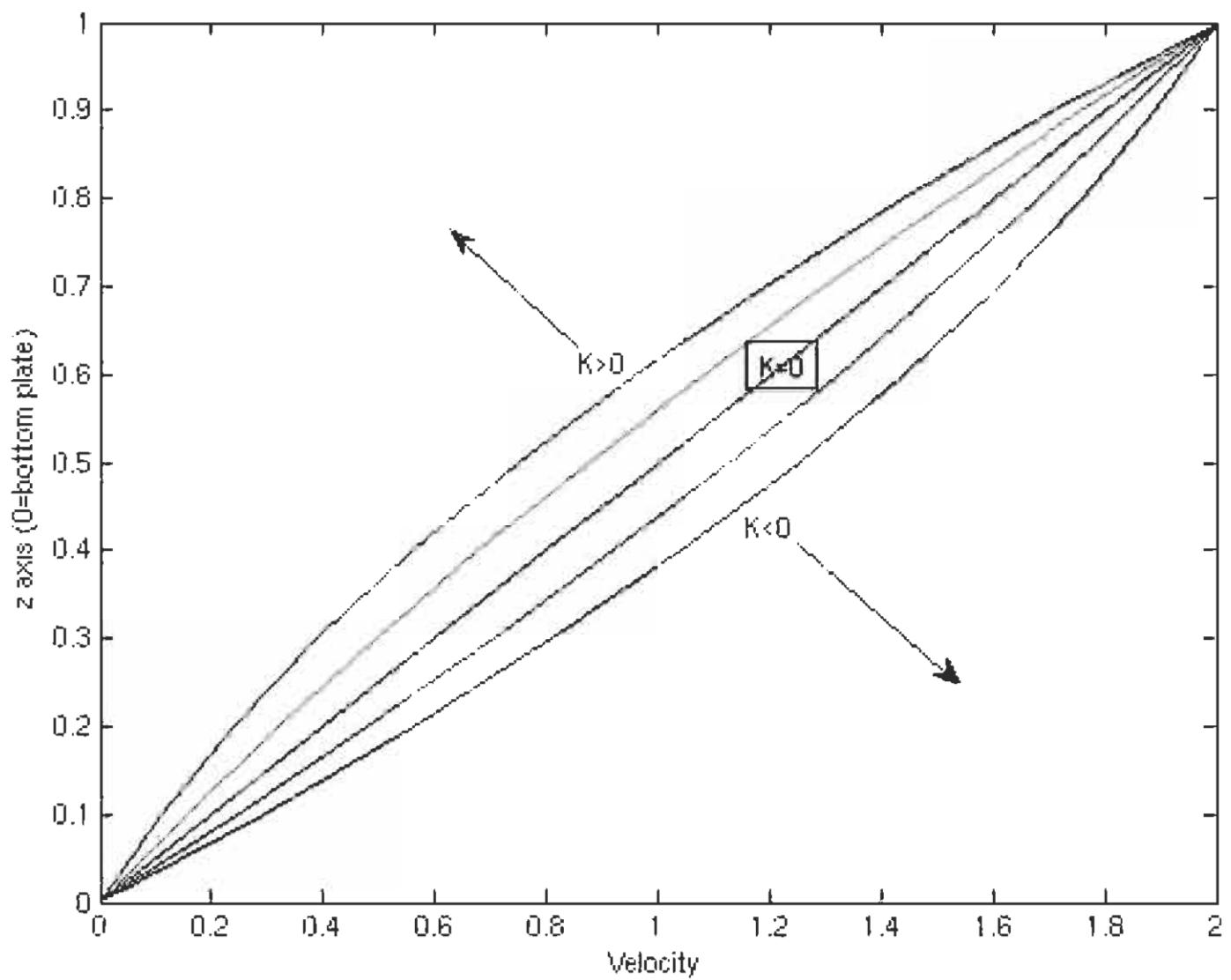
$$u = \frac{K}{2\mu} z^2 + \left(\frac{U}{h} - \frac{Kh}{2\mu} \right) z \Rightarrow \vec{v} = \left[\frac{K}{2\mu} z^2 + \left(\frac{U}{h} - \frac{Kh}{2\mu} \right) z \right] \hat{z}$$

sketch for several values



$$K > 0$$





c) what is τ_{xz} on each plate

$$\tau_{xz} = \mu \frac{\partial u}{\partial z} = \mu \left[\frac{zkz}{2h} + \frac{u}{h} - \frac{kh}{2h} \right] = kz + \frac{uh}{h} - \frac{kh}{2}$$

$$\tau_{xz} = kz + \frac{uh}{h} - \frac{kh}{2} \quad \left. \begin{array}{l} \text{top plate } z=h \\ \text{bottom plate } z=0 \end{array} \right\} \quad \tau_{xz} = \frac{uh}{h} + \frac{kh}{2}$$

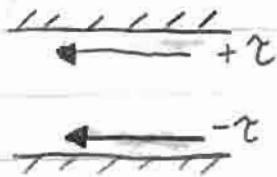
letting $\tau_{xz}=0$

$$\text{top plate } k = -\frac{2uh}{h^2}$$

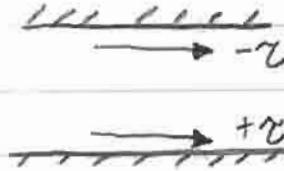
$$\text{bottom plate } k = \frac{2uh}{h^2}$$

sketch direction of τ_{xz} for positive; negative values of k .

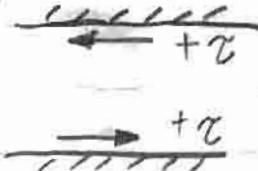
$$k > \frac{2uh}{h^2}$$



$$k < -\frac{2uh}{h^2}$$



$$-\frac{2uh}{h^2} < k < \frac{2uh}{h^2}$$

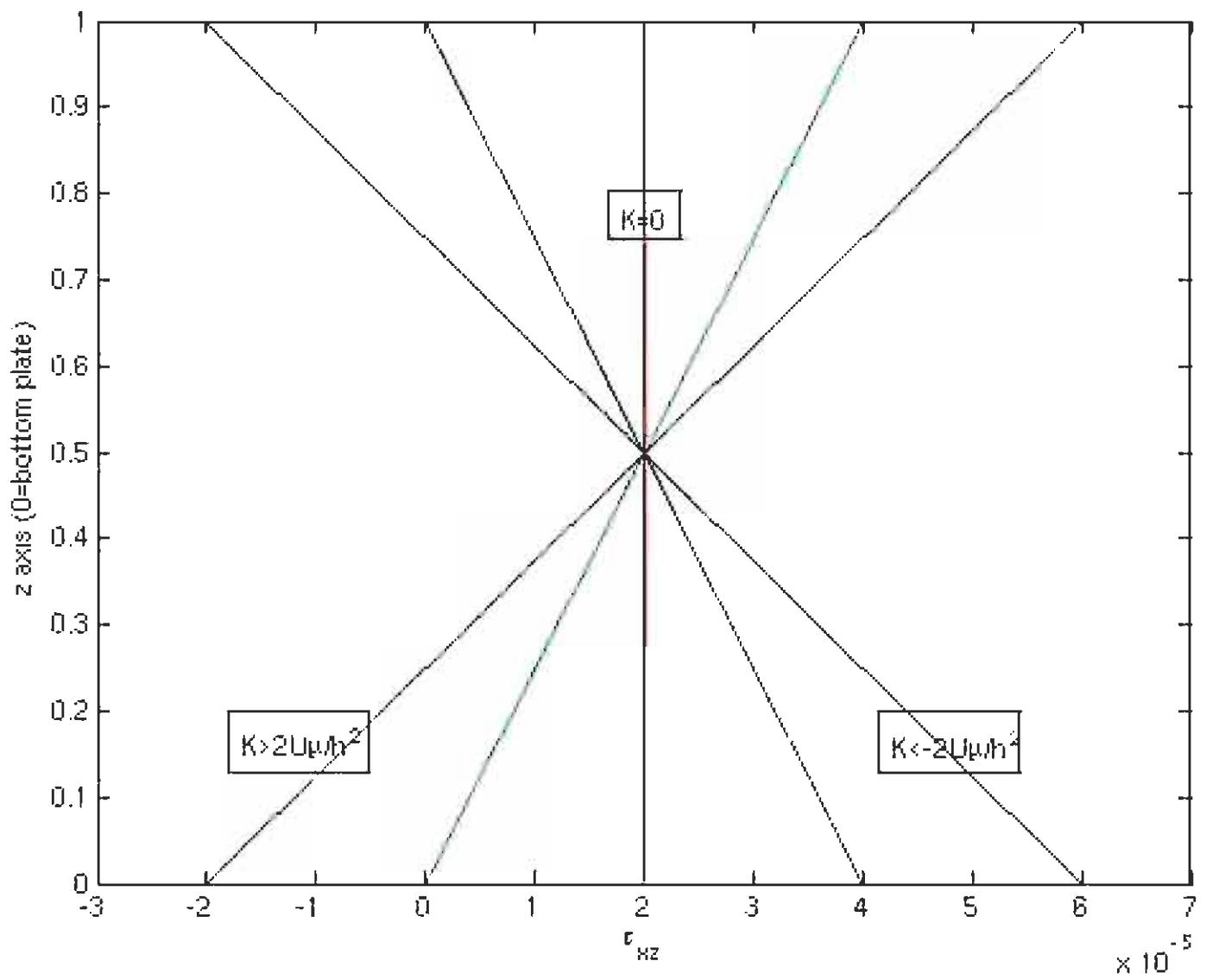


I define
 τ positive on a face

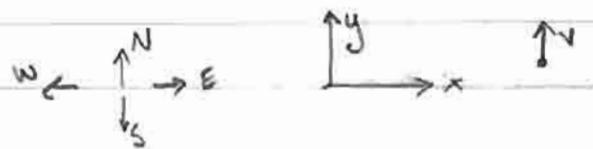
looks like \rightarrow



There are 2 points where shear stress goes to zero, one on the top face $k = -\frac{2uh}{h^2}$
once on bottom face $k = \frac{2uh}{h^2}$.



4) a) $\phi = 42^\circ$ lat. $v = 75 \text{ m/hr}$ $2y = 60 \text{ feet}$



Use coriolis acceleration: $\frac{\partial u}{\partial t} = 2\omega v \sin \phi$

$$\begin{aligned}\frac{\partial u}{\partial t} &= 2 \cdot 7.292 \times 10^{-5} [\text{rad/sec}] \cdot 75 [\text{m/hr}] \cdot \sin(42^\circ) \\ &= 2 \cdot 7.292 \times 10^{-5} [\text{rad/s}] \cdot 33.53 [\text{m/s}] \cdot \sin(42^\circ)\end{aligned}$$

$$\frac{\partial u}{\partial t} = 0.00327 [\text{m/s}^2] = a_0$$

$$x(t) = x_0 + v_0(t) + \frac{1}{2} a_0 (t^2) \quad x_0 = 0 \quad v_0 = 0$$

$$x(t) = \frac{a_0}{2} t^2$$

$$\begin{aligned}\text{time of flight} &= 60 \text{ feet} / 75 \text{ m/hr} = 0.545 \text{ sec} \\ &= 60 \text{ ft. } 1 \text{ hr} =\end{aligned}$$

$$x(0.545) = \frac{0.545^2 \cdot 0.00327}{2} = 0.000486 [\text{m}]$$

deflection = 0.486 [mm] to the east

b) Thrown east $\Rightarrow \frac{\partial v}{\partial t} = -2\omega u \sin \phi$ - same magnitude but deflects south!

Thrown south $\Rightarrow \frac{\partial u}{\partial t} = 2\omega v \sin \phi$ - same magnitude but deflected west!

Thrown west $\Rightarrow \frac{\partial v}{\partial t} = -2\omega u \sin \phi$ - same magnitude deflected north!

c) if thrown in Wellington New Zealand $\phi = -42^\circ$

Therefore, ball thrown North will deflect 0.486 mm West instead!

d) at equator $\sin(0) = 0$ No deflection

e) if ball velocity = 100 m/hr direction is still
eastward but magnitude goes to 0.365 [mm]

$$100 \text{ m/hr} = 44.7 \text{ m/s}$$

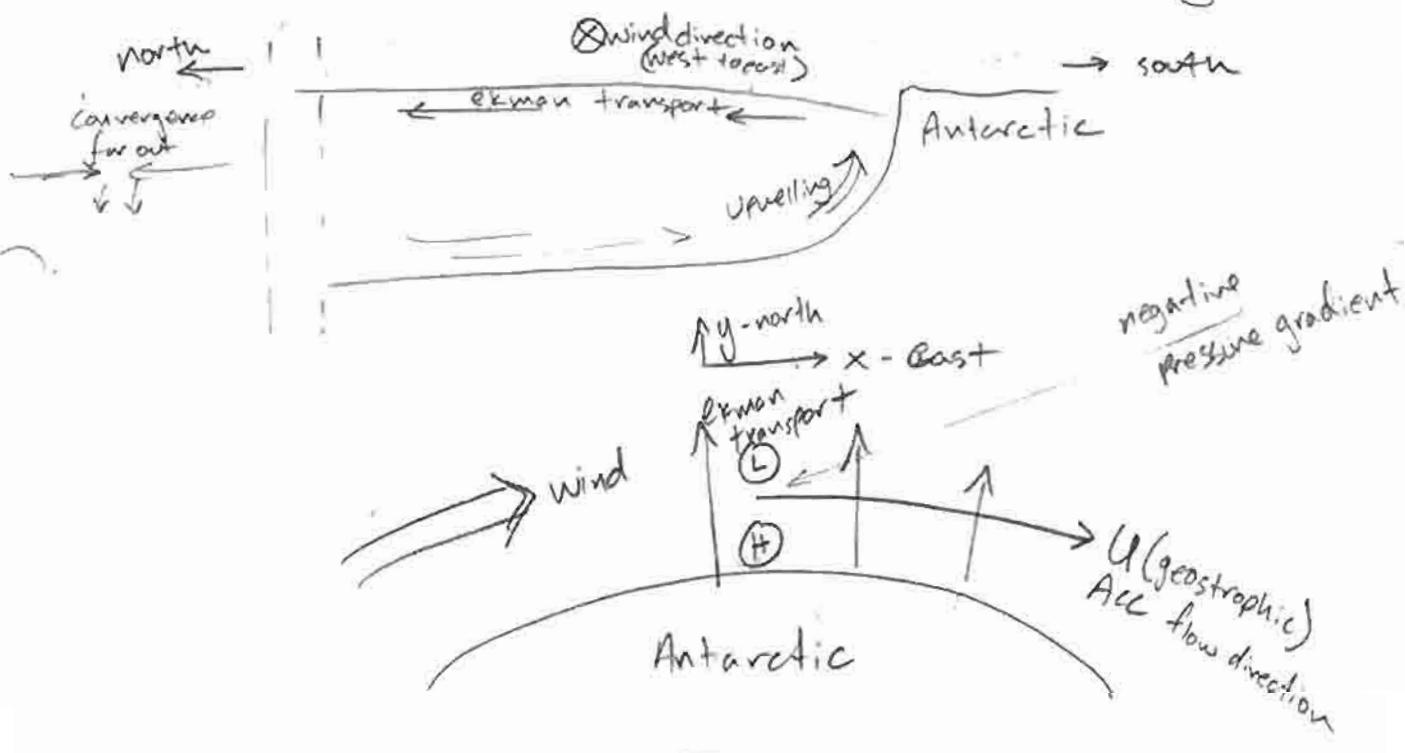
$$t = \frac{60 \text{ ft}}{100 \text{ m/hr}} = 0.409 \text{ s}$$

$$\frac{\partial v}{\partial t} = a_0 = 2 \cdot 7.292 \times 10^{-5} [\text{rad/s}] \cdot 100 [\text{m/hr}] \cdot \sin(42^\circ) = 0.00436 [\text{m/s}^2]$$

$$x(t) = \frac{a_0}{2} t^2 = \frac{0.00436}{2} \cdot (0.409)^2 = 0.000365 [\text{m}]$$

Antarctic Circumpolar Current

Ekman transport occurs @ 90° to wind direction near antartica. Wind is from the west and therefore ekman transport carries fluid away from Antarctica. Conservation of mass enables cooler deeper water near the coast to replace water moving out to sea. This cooler water is more dense because it is also more salty.



$$\text{geostrophic flow east west} \quad u = -\frac{1}{fS} \frac{\partial p}{\partial y}$$

For Antarctic Circumpolar Current is a negative pressure gradient in the northern direction (y). This makes flow from west to east.

See pg. 232 in text.