

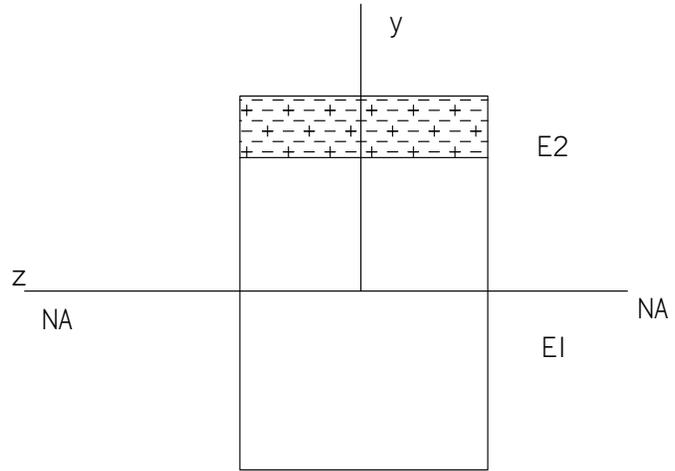
Dissimilar material such as a composite structure:

what if E and I are not constant??

assuming bending only; M_z applied; determine I_z

In this cross section, the upper region has a modulus = E_2 where the remainder has modulus E_1

as with Euler bending, plane sections remain plane etc....



$$\epsilon_x = \frac{-y}{R}$$

ϵ is axial strain
 y the distance from the neutral (z) axis
 R the radius of curvature

$$\sigma_x = E \cdot \epsilon_x = \frac{-E \cdot y}{R}$$

Hooke applies (although E is now dependent on y)
 signs consistent with Shames 11.2

pure (only) bending => $F_x = \int \sigma_x dA = 0 = - \int \frac{E(y) \cdot y}{R} dA$ net axial force = 0

suppose we define a parameter T_i such that $T_i = \frac{E_i}{E_1}$ that is, a fraction of a reference modulus E_1

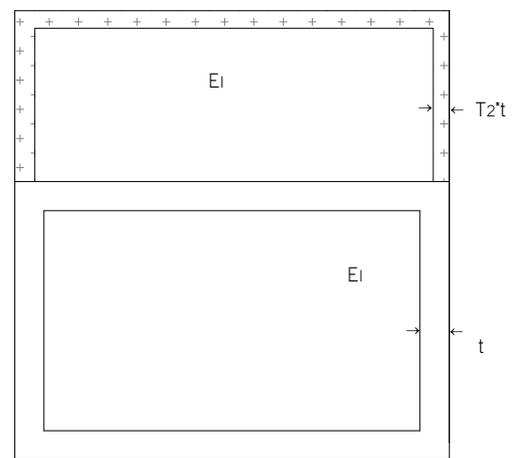
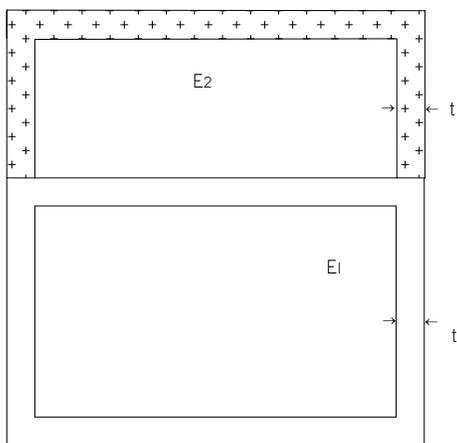
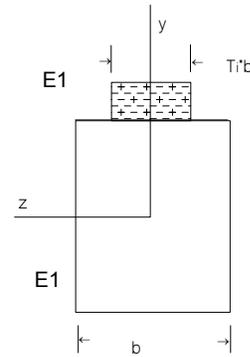
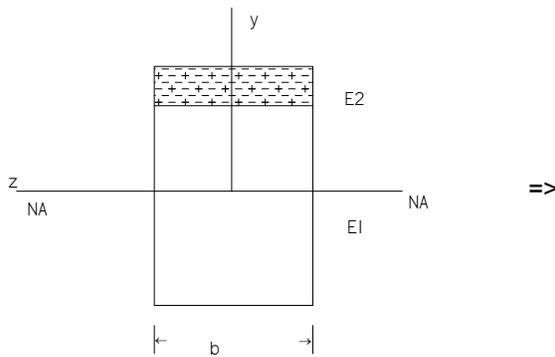
then: $-\int \frac{E(y) \cdot y}{R} dA = \frac{-E_1}{R} \int T_i(y) \cdot y dA$

"transfer" T_i to the area, in such a way that y is not affected => $T_i(y) \cdot y \cdot dA = y \cdot (T_i(y) \cdot dA) = y \cdot dy \cdot (T_i(y) \cdot dz)$

which means "transfer" to dz , and in rectangular shape, equivalent to applying to z dimension, for thin walled vertical sections that's the thickness. that is over the different moduli:

$$\int T_i(y) \cdot y dA = T_i \cdot b \cdot \int y dy$$

in a horizontal thin walled section, $y \sim \text{constant} \Rightarrow$ can still apply to thickness:



$$\int T_i(y) \cdot y \, dA = 0 \quad \Rightarrow \text{NA is at the cg of the transformed section}$$

now continue looking at the bending moment:

$$M_z = - \int \sigma_x \cdot y \, dA = \frac{-1}{R} \cdot \int E(y) \cdot y^2 \, dA = \frac{-E_1}{R} \cdot \int T_i \cdot y^2 \, dA \quad \text{using the relation defined above}$$

$$\text{define } I_{z_tr} = \int T_i \cdot y^2 \, dA \quad \Rightarrow \quad \frac{1}{R} = \frac{M_z}{E_1 \cdot I_{z_tr}}$$

and again we can apply T_i to the z dimension in vertical sections and to the y in horizontal

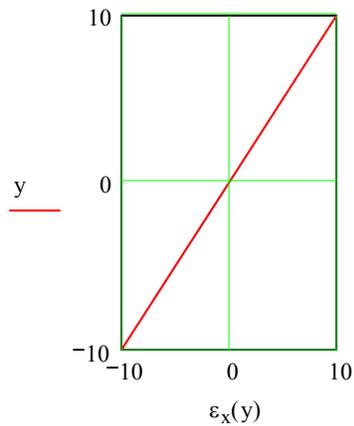
$$\varepsilon_x = \frac{-y}{R} \quad \sigma_x = E \cdot \varepsilon_x = \frac{-E(y) \cdot y}{R} = -E(y) \cdot \frac{M_z}{E_1 \cdot I_{z_tr}} \cdot y$$

where we have written $E(y)$ as it varies

$$T_i = \frac{E_i}{E_1} \quad \sigma_x = -E_i(y) \cdot \frac{M_z}{E_1 \cdot I_{z_tr}} \cdot y = -T_i \cdot \frac{M_z}{E_1 \cdot I_{z_tr}} \cdot y = -T_i(y) \cdot \frac{M_z}{I_{z_tr}} \cdot y$$

assume for plot like text $R := -1$

$$\varepsilon_x(y) := \frac{-y}{R}$$



(plane sections remain plane)

to evaluate stress

at y_i (where modulus changes, substitute $E(y) = T_i \cdot E_1 \Rightarrow$

$$I_{z_tr} := 1 \quad M_z := -1$$

$$yy := \begin{pmatrix} 0 \\ 0.7 \\ 1.0 \end{pmatrix} \quad TT := \begin{pmatrix} 1 \\ 0.5 \end{pmatrix}$$

$$i := 0..1 \quad y := 0, 0.01..1$$

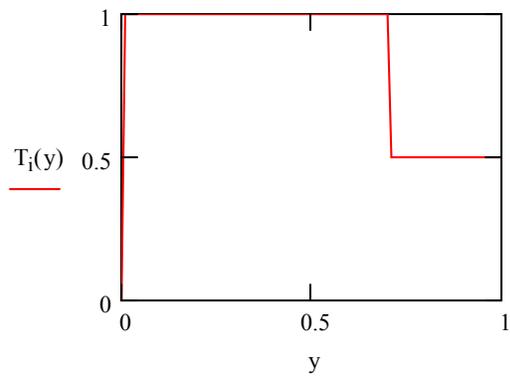
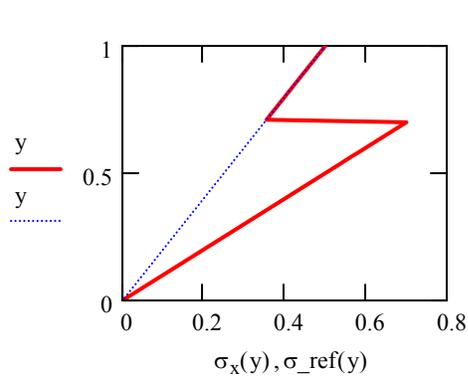
$$T_i(y) := \sum_i TT_i \cdot (yy_i < y \leq yy_{i+1})$$

summation is to superpose the values appropriate to the (y) dependence

$$\sigma_x(y) := -T_i(y) \cdot \frac{M_z}{I_{z_tr}} \cdot y$$

$$\sigma_ref(y) := -TT_1 \cdot \frac{M_z}{I_{z_tr}} \cdot y$$

hence the stress variation is



$x := 0..10$ $v(x) := 1$ $E := 1$ $I := 1$ $\text{constant} := 0$ $z := 0..10$

$I_n := 1$ $n := 1..2$ $d_g := 1$ $A_n := 1$ $i_{0_n} := 1$
 $d_n := 1$

$n := 1..2$ $t := 1$

$V(x) := 1$ $N_0 := 0$

$\sigma_z := 6$ $\tau_{xz} := 1$

$\tau_{yz} := 4$

$\sigma_1 := 1$ $\tau_{xy} := 1$ $\sigma_2 := 2$ $\sigma_3 := 3$ $\sigma_y := 5$ $\sigma_Y := 4$ $\sigma_x := 2$