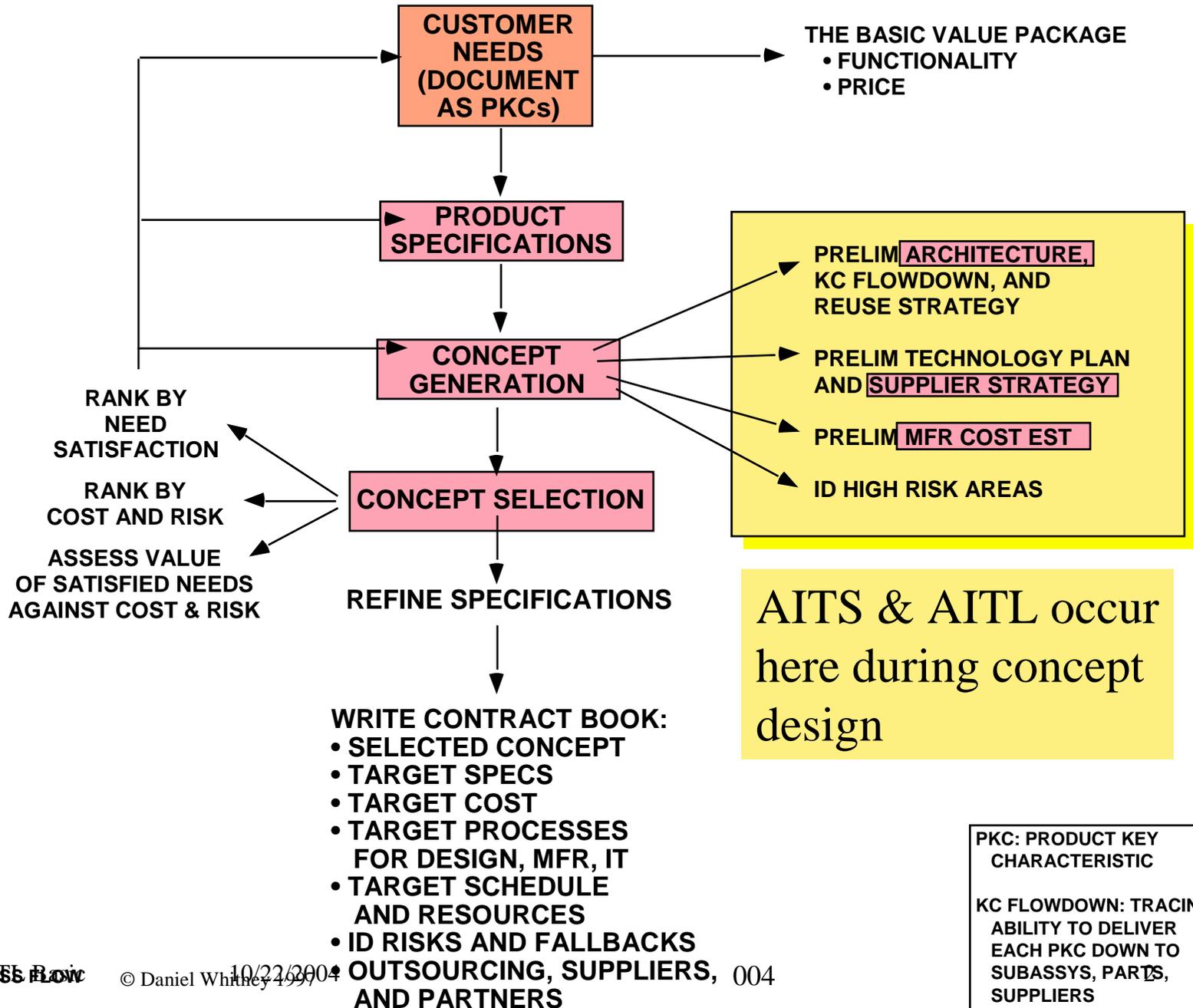


# Assembly in the Large: Basic Issues

- Goals of this class
  - put assembly in the large in the context of product development
  - relate it to customer expectations
  - start to think about architecture

# FRONT-END PRODUCT DEVELOPMENT PROCESS



**PKC: PRODUCT KEY CHARACTERISTIC**

**KC FLOWDOWN: TRACING ABILITY TO DELIVER EACH PKC DOWN TO SUBASSYS, PARTS, SUPPLIERS**

# A Little History

- Is my product ready for robot assembly?
- Well, is your product ready for assembly at all?
- What are the requirements for assembly?
- Can we explain them to a machine?
- Do we understand the product well enough that our suggestions
  - make sense
  - do not compromise performance
- We may have to reverse engineer it to find out

# “Product Character”

- Which of the following products is most like a fire extinguisher?
  - (a) sewing machine
  - (b) hand grenade
  - (c) lawn sprinkler
- What are the issues that go into answering this question?

# Two Kinds of Copiers

- Industrial strength and capacity
  - Costs a lot
  - Is finnick: design is not robust
  - Customer can afford full time service person
- Home or small business
  - Must be low cost
  - Must work
  - Can't afford service person on site
- The manufacturer did OK with the first but failed with the second

# Manual Sewing

Image removed for copyright reasons.

Source:

Figure 1-11 in [Whitney 2004] Whitney, D. E. *Mechanical Assemblies: Their Design, Manufacture, and Role in Product Development*. New York, NY: Oxford University Press, 2004. ISBN: 0195157826.

**Source: "Real Robots Do Need Jigs," Daniel E Whitney,  
Harvard Business Review, May-June 1986, pp 110-116**

# Machine Sewing - 1

Image removed for copyright reasons.

Source:

Figure 1-12 in [Whitney 2004] Whitney, D. E. *Mechanical Assemblies: Their Design, Manufacture, and Role in Product Development*. New York, NY: Oxford University Press, 2004. ISBN: 0195157826.

# Machine Sewing - 2

Image removed for copyright reasons.

Source:

Figure 1-12 in [Whitney 2004] Whitney, D. E. *Mechanical Assemblies: Their Design, Manufacture, and Role in Product Development*. New York, NY: Oxford University Press, 2004. ISBN: 0195157826.

The needle pokes through the cloth and leaves a loop.

The bobbin is shown passing through the loop.

In fact, a hook catches the loop and slips it under the bobbin.

When this step is finished, an arm above pulls the loop tight.

# Comparison of Manual and Machine Sewing Methods

	Manual	Machine
<b>Number of "hands"</b>	<b>Two</b>	<b>One</b>
<b>Number of threads</b>	<b>One</b>	<b>Two</b>
<b>Grasp of needle</b>	<b>Repeated grasp/ungrasp</b>	<b>Never ungrasp</b>
<b>Location of eye</b>	<b>Rear of needle</b>	<b>Tip of needle</b>
<b>Needle movement</b>	<b>Passes through Flips 180°</b>	<b>Point penetrates Never flips</b>
<b>Joining method</b>	<b>One thread passes through repeatedly</b>	<b>Two threads interlock but never pass through</b>

Images removed for copyright reasons.

Source:

Figure 12-2 in [Whitney 2004] Whitney, D. E. *Mechanical Assemblies: Their Design, Manufacture, and Role in Product Development*. New York, NY: Oxford University Press, 2004. ISBN: 0195157826.

# Comparing 4 Ways to Print

	<b>Typewriter</b>	<b>Ballhead</b>	<b>Dot Matrix</b>	<b>Inkjet</b>
<b>Basic actuation method and power source</b>	Manual, complex linkages	Manual input, solenoid actuation, simple linkages	Electro-magnet for each dot maker	Piezo-electric for each color of ink
<b># DOF</b>	Carriage:2 Ribbon: 2 Keys: 1 each*50+ keys*many links/key Key carrier: 1	Platen: 1 Ribbon: 2 Keys: 1 each*50+ keys electrically actuated Ball carrier: 3	Platen: 1 Ribbon: 2 No keys Dot carrier: 1 Each dot: 1	Platen: 1 No ribbon No keys Jet carrier: 1
<b># of parts</b>	Many hundreds	Hundreds	25-50	10-20
<b>Structure</b>	Heavy metal	Heavy metal	Metal and plastic	Almost all plastic
<b>Shapes printed</b>	Fixed character shapes	Fixed character shapes but different balls have different fonts	Unlimited shapes but low resolution	Unlimited shapes and high resolution
<b>Colors</b>	Two	Two	Two	Unlimited
<b>Media</b>	Paper, two or three sheets	Paper, several sheets	Paper, many sheets	Any, but one sheet
<b>Assembly</b>	Manual, lengthy, tedious	Manual, lengthy, easy	Automatic & manual	Manual, quick, easy

# Takeaways

- There are many ways to implement a function
- They differ in technology choice, materials, degrees of freedom, allocation of dof, number of parts
- Different implementations have different capabilities for function, customization, upgrade
- They also have different assembly requirements
- Sometimes assembly requirements can drive redesign – IBM ProPrinter example

# Steps in AITL - 1

- Understand the business context
  - product character, type of market, customer expectations
  - sales volume anticipated
  - model variety anticipated
  - plans for new versions
  - delayed commitment
  - supplier logistics and make vs buy
  - cost limits
  - labor costs and any regulations
  - cost calculation and ROI methods
  - ROI targets

# Steps in AITL - 2

- Understand the factory context
  - labor conditions, training, shift policies
  - space and facility constraints
- Understand the as -is assembly (AITL)
  - study the existing manual process, if any
    - inspecting fiber
  - **ignore** the existing manual process and focus on
    - technical and economic **requirements**
  - may give rise to a new level of “DFA” especially if automatic assembly is under consideration
    - sewing, Sony VCR line, RAM with fuses
  - do not **ever** imply that performance might have to be compromised!

# Steps in AITL - 3

- Identify system requirements
  - alternate assembly sequences
  - tentative cycle time
  - production flow and floor layout
  - parts presentation
  - feasible methods and equipment
  - required sensing and communication
  - required displays and controls
  - fixtures and parts carriers

# Steps in AITL - 4

- Design a concept assembly system
  - system architecture
  - equipment selection and task assignment
  - cost and economic performance
  - simulation
    - average flow and production rate
    - model changeovers and maintenance (scheduled downtime)
    - failures, repair time (unscheduled downtime)
    - queues, blockage, starvation (unscheduled downtime)

# Steps in AITL - 5

- Make final recommendations
  - additional design improvements
  - line design or sequence options
  - remaining risk areas
  - cost estimates

# Structure of System Design Issues

	Global	Local
Product	<ul style="list-style-type: none"> <li>• Economics and market targets</li> <li>• Volume growth</li> <li>• Model varieties</li> <li>• Design volatility</li> <li>• Quality, reliability, safety</li> <li>• Make or buy decisions</li> <li>• Build to order/stock</li> </ul>	<ul style="list-style-type: none"> <li>• Assembly sequences</li> <li>• Types of operations</li> <li>• Geometric constraints</li> <li>• Part size and weight</li> <li>• Shape, stiffness</li> <li>• Tolerances and clearances</li> <li>• Tests and inspections</li> </ul>
Assembly System	<ul style="list-style-type: none"> <li>• Cost and productivity goals</li> <li>• How it interfaces to the factory</li> <li>• Labor policies</li> <li>• Failure modes and repair policies</li> <li>• Space needs</li> </ul>	<ul style="list-style-type: none"> <li>• System layout</li> <li>• Equipment choice</li> <li>• Task assignment</li> <li>• Part feeding and logistics</li> </ul>