

Single-shot Multidomain Camera

Roarke Horstmeyer

Gary Euliss, Ravi Athale, The MITRE Corp

Marc Levoy, Stanford University

2009

Background

- Megapixel race has resulted in an excess of pixels
- Other types of useful information that a camera can capture:

Polarization

Images removed due to copyright restrictions.
See references [1], [2], [3].

[1-3]

Multispectral

Images removed due to copyright restrictions.
See references [4], [5].

[4,5]

High Dynamic Range

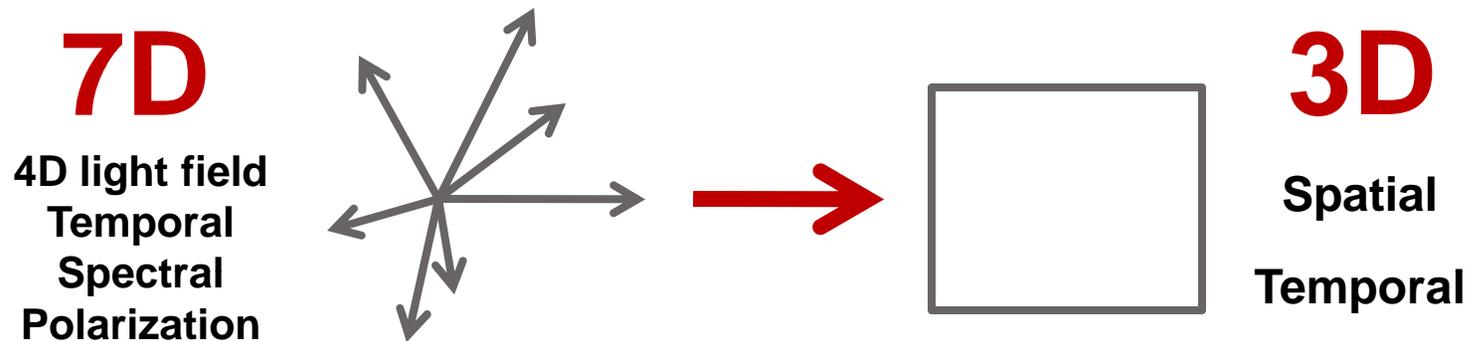
Images removed due to copyright restrictions.
See reference [6].

[6]

- **Can all of this be captured in a single image?**

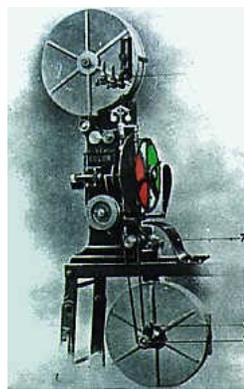
Background

- Presented with a dimensionality mismatch during multidimensional information capture:



- There are many different methods of encoding/decoding spectral and polarimetric information

- One of the most direct methods is through the temporal domain
- Full 2D spatial resolution preserved at the expense of time response



Kinemacolor [7]
Images: public domain

Image removed due to copyright restrictions.
See reference [8].

Pushbroom
Hyperspectral [8]

Background

- There are many spatial encoding/decoding schemes:

1. At the focal plane:

Tradeoffs: Fixed, Integration

Images removed due to copyright restrictions.

Bayer Filter [11]

Polarization [10]

Assorted Pixels [9]

2. Multi-aperture :

Tradeoffs: Registration, Alignment

Images removed due to copyright restrictions.

PERIODIC [12]

TOMBO [13]

3. Code-division multiplexing:

Tradeoffs: Computation, SNR

Images removed due to copyright restrictions.

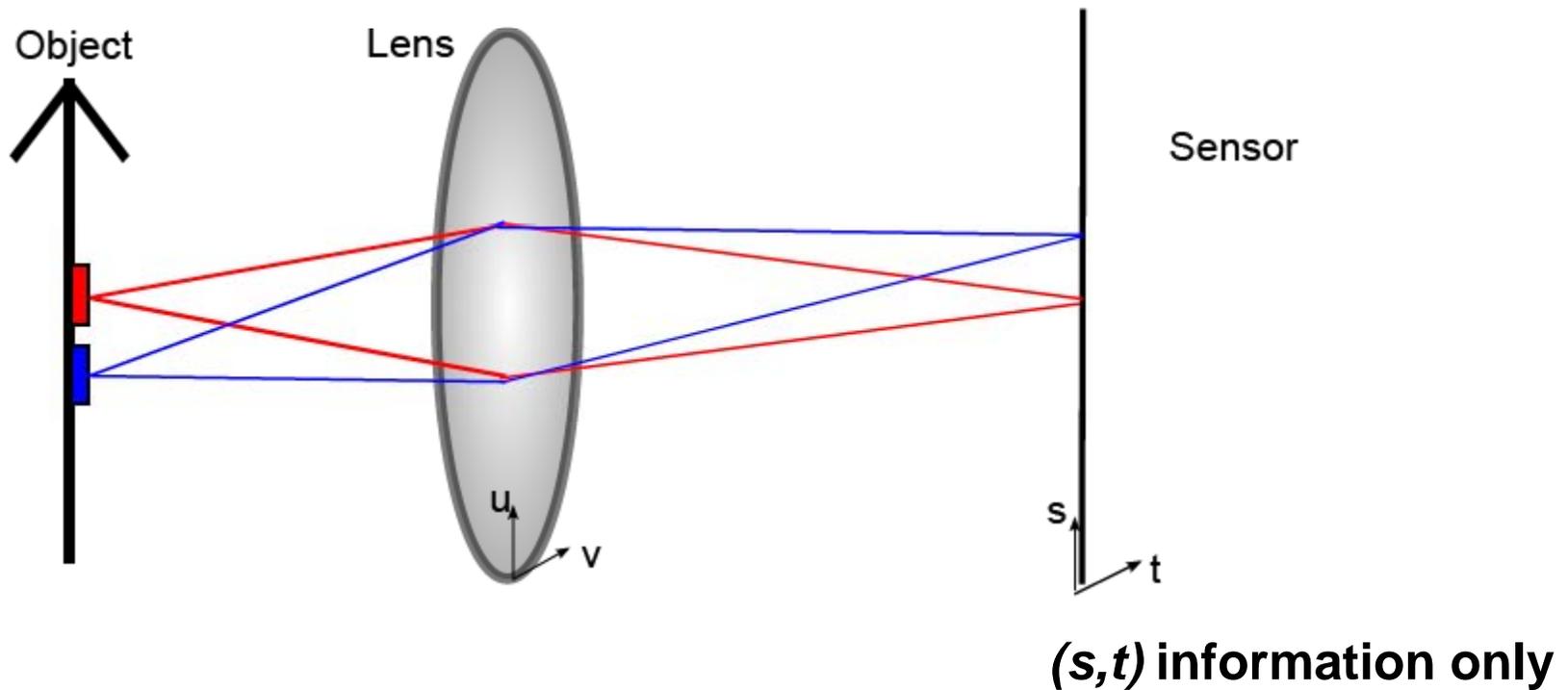
CASSI [14]

CTIS [15]

- **Reduced spatial resolution \propto number of samples**

Background

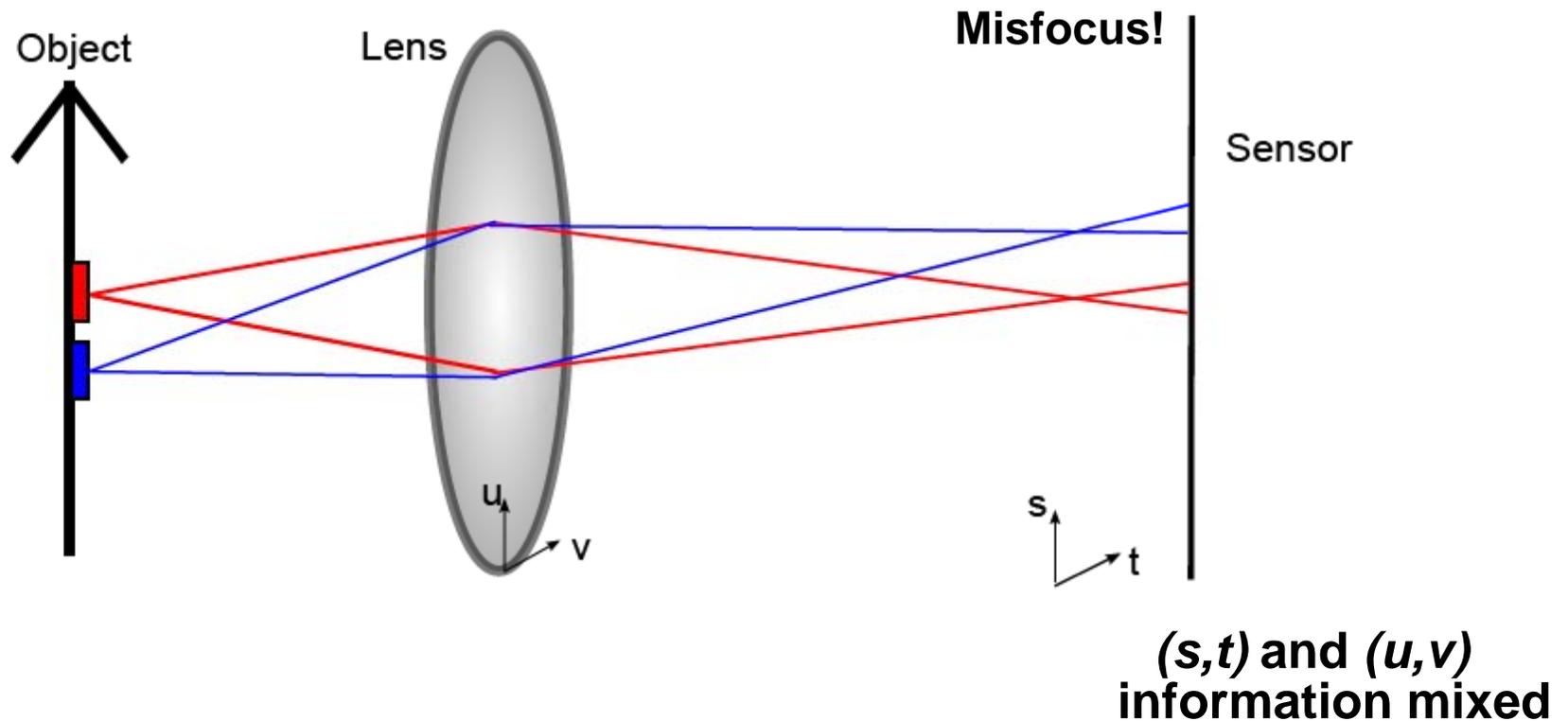
- Basic idea of a light field camera:



- **Sensor integrates over all rays originating from a particular object point**

Background

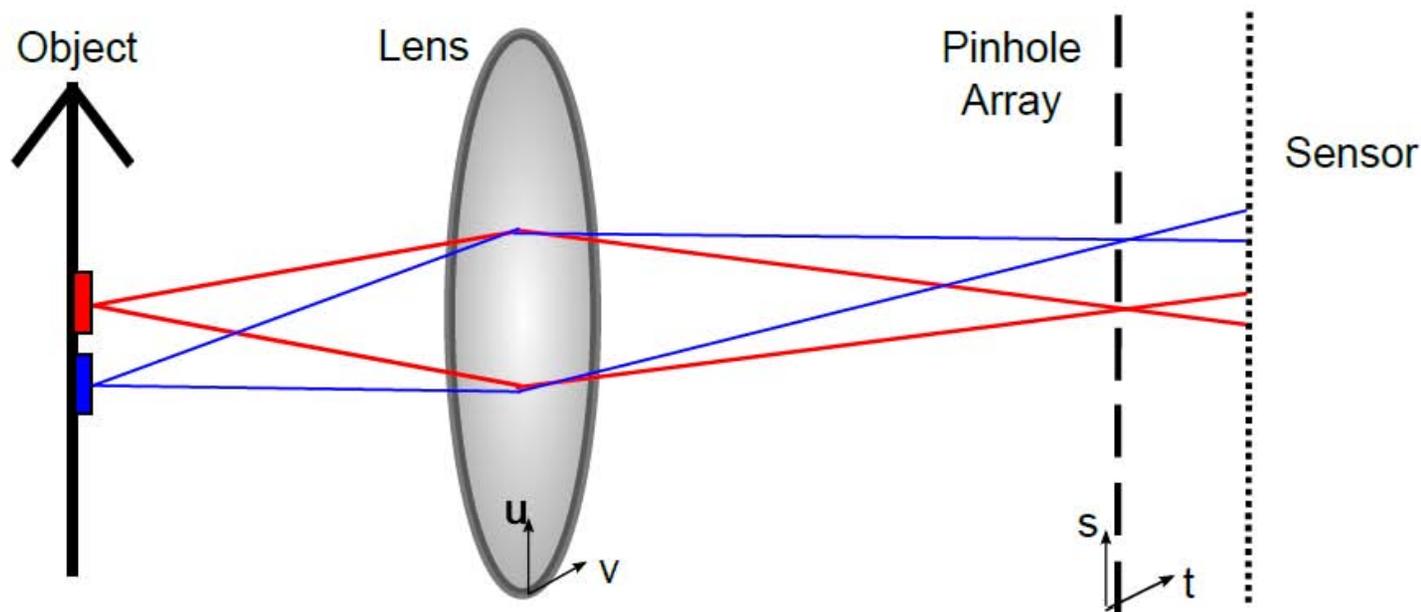
- Basic idea of a light field camera:



- **Misfocus reintroduces (u, v) info, but it is not distinguishable from structure of light from object**

Our Approach:

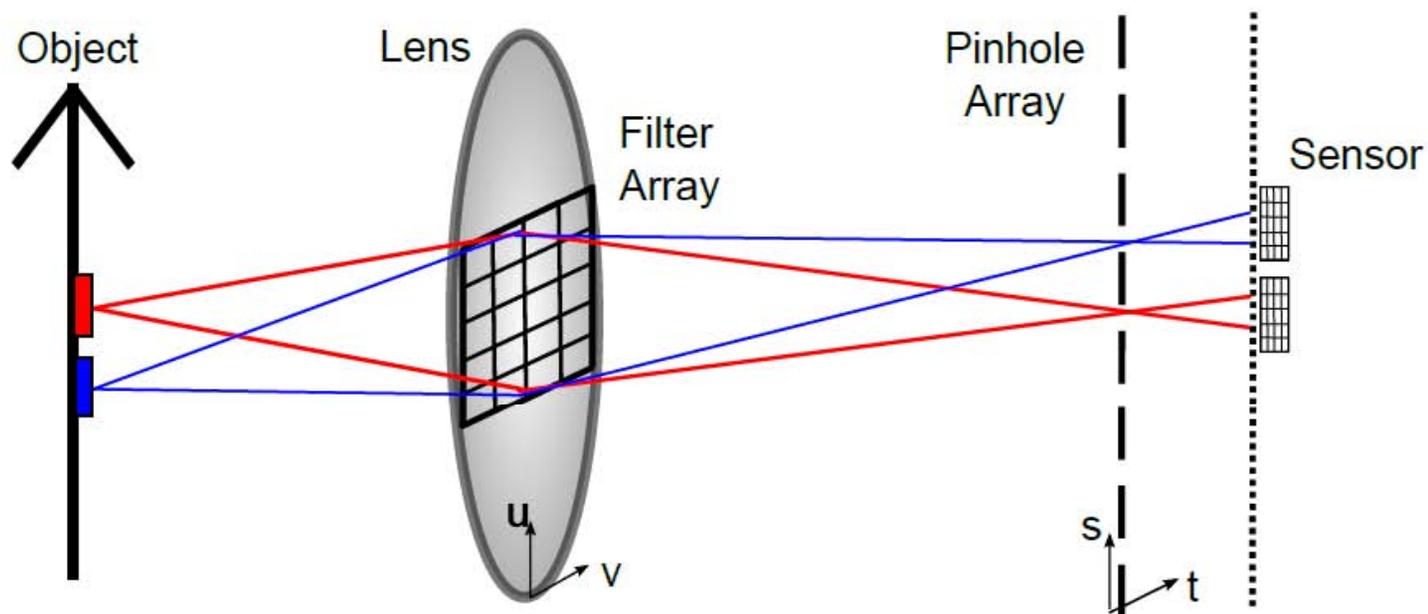
- Encode over ray angle (spatial frequency variable)
- Basic idea of a light field camera:



- Pinhole is imaging pupil plane, providing (u,v) angular info
- Used for depth (Adelson and Wang [16]), refocusability (Ng et al. [17]) glare removal (Raskar et al. [18])

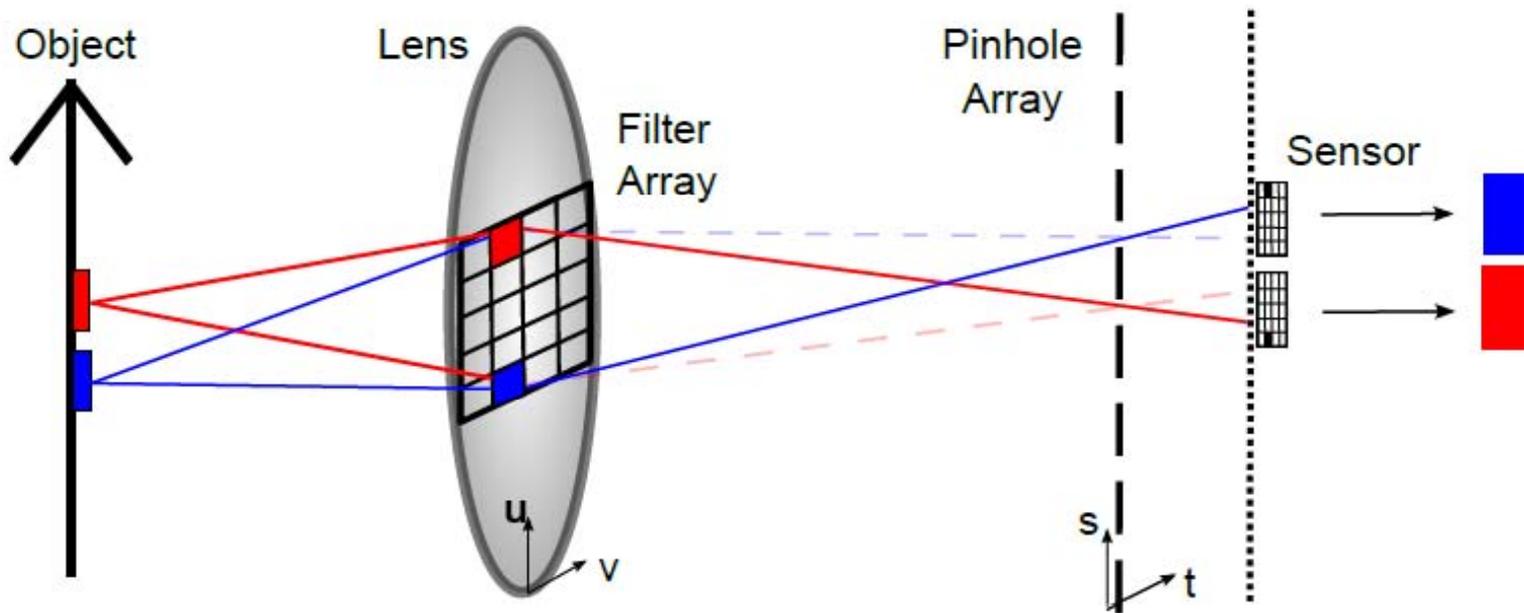
Our Approach

- Place a filter array in the camera's pupil plane:



- Now, each pinhole at a particular (s,t) creates an image of the filter array in the (u,v) plane

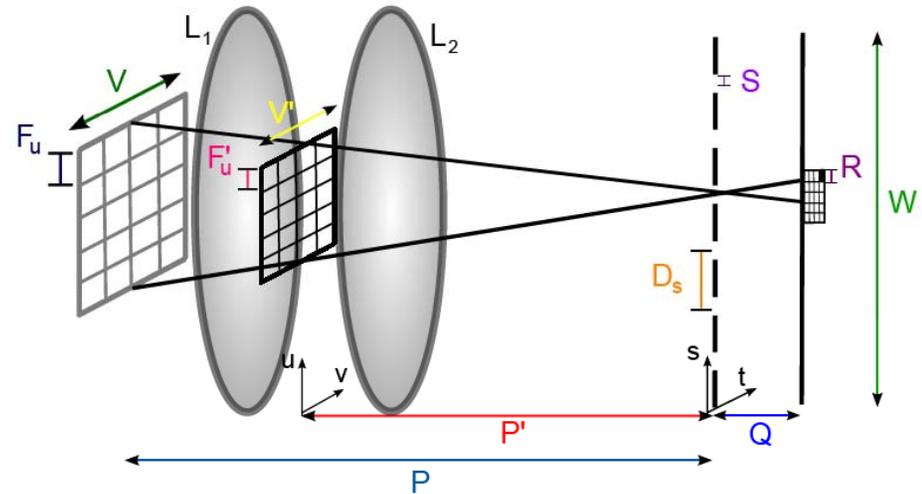
Our Approach



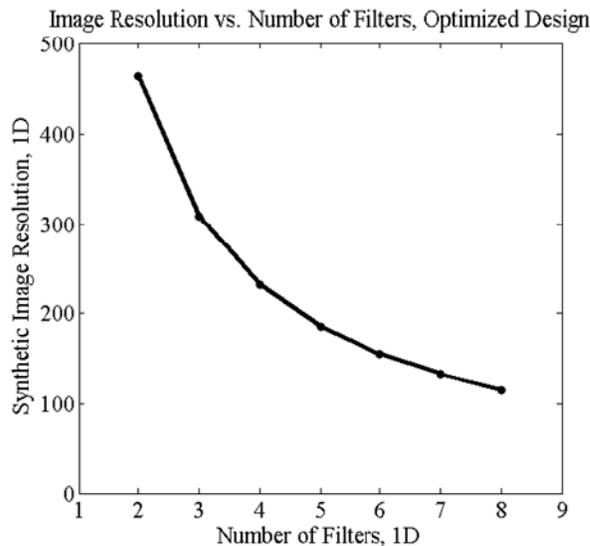
- Color information (e.g.) is available at each spatial location in (s,t) from each filter array image
- Spatial resolution from # pinholes, filter resolution from # filters

Camera Design

- A conventional setup sets P and Q :
 $P' \approx 50 \text{ mm}$ (standard lens)
 $Q = 1.14 \text{ mm}$ (cover glass)



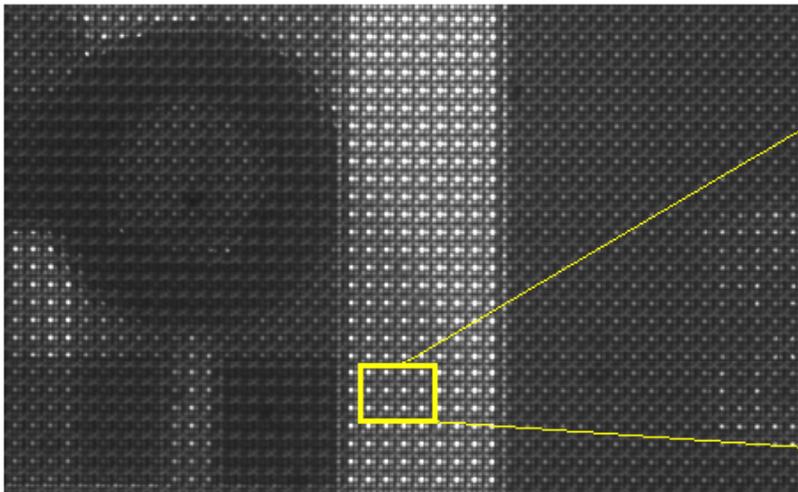
S	R	F	M_2	W
25.32μ	38.83μ	1.51 mm	1.15	3.61 cm



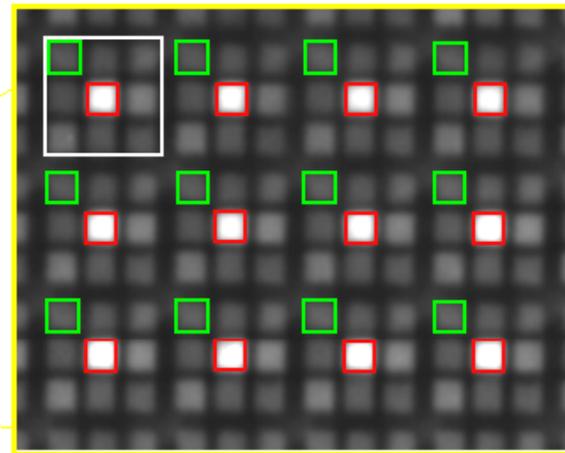
- Tradeoff between synthesized image resolution and number of filters similar to (u, v) and (s, t) tradeoff in refocusing light field systems
- Pinholes = optics-limited ($R > \text{pixel size}$)

Image Reconstruction Process

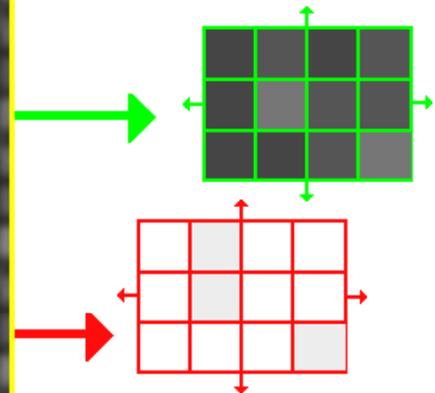
Filtered Synthetic Images



(Portion of) raw image roughly resembles scene



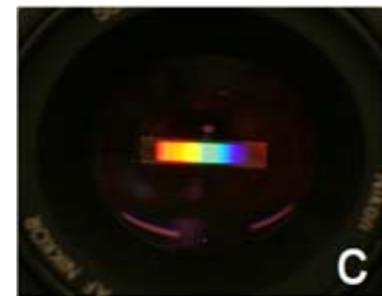
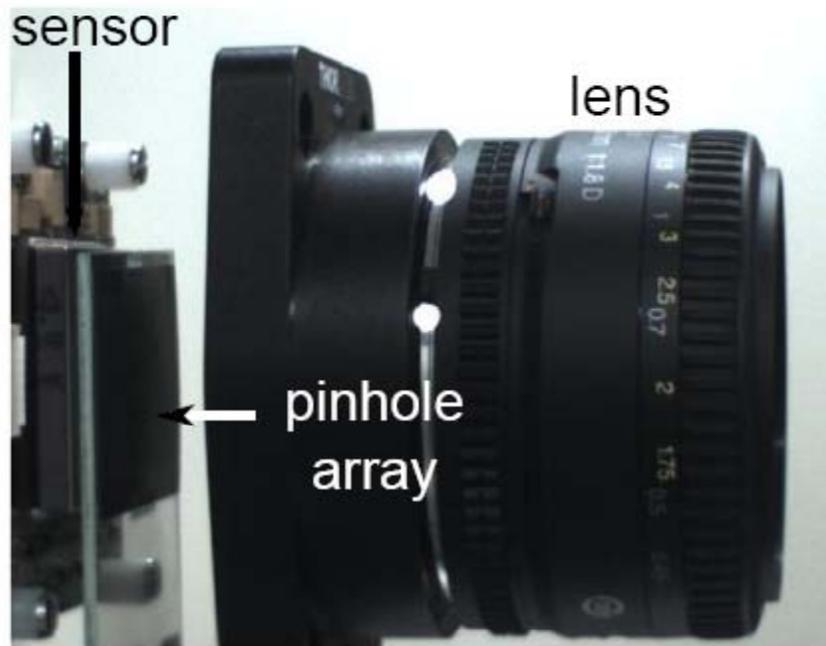
Close up, images of filter array apparent (3x3 square array)



Combine similarly filtered areas from every pinhole

Camera Setup

- Use conventional Nikon 50mm f/1.8 lens, 10Mpix 9 μ CCD
- Pinhole arrays printed on transparencies, varying size + pitch
- Filters cut and arranged on laser-cut plastic holders, placed inside lens over aperture stop



© 2009 IEEE. Courtesy of IEEE. Used with permission. Source: Horstmeyer, R., G. W. Euliss, R. A. Athale, and M. Levoy. "Flexible Multimodal Camera Using a Light Field Architecture." Proceedings of IEEE ICCP, 2009.

Experimental Results

- Six filters: R, G, B, 0° , 45° , 90° (pinhole $r = 25\mu$, pitch = 200μ)



Lambertian
division \rightarrow



RGB



LDOP



Experimental Results

layout

B	G	M	C
R	No Filter	Y	IR
0°	RC	0.4	0.6
45°	135°	90°	1

■ Sixteen filters:



Experimental Results

- An example of foveation

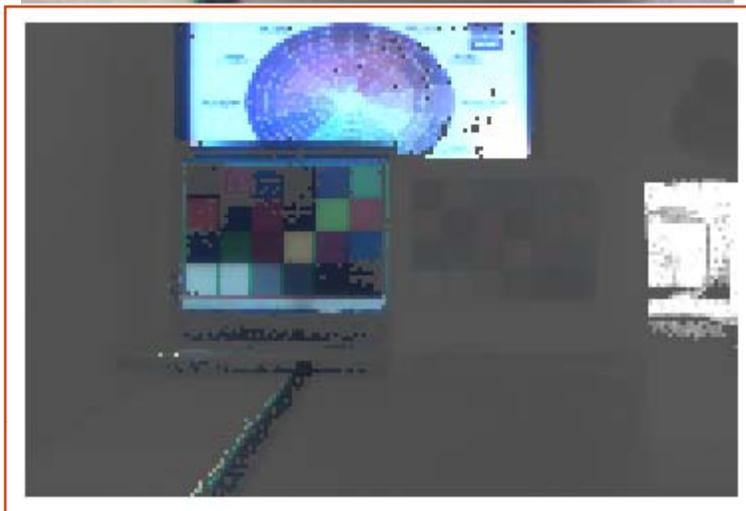
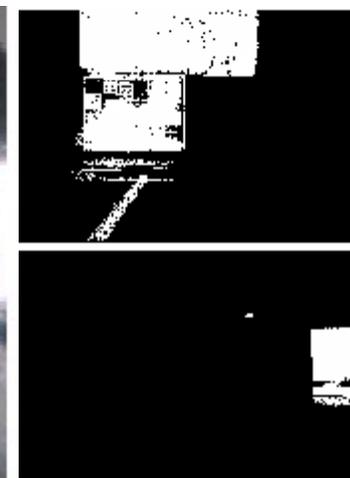
RGB



RGB HDR



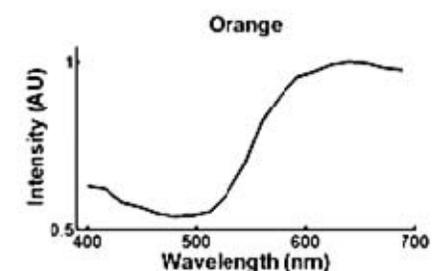
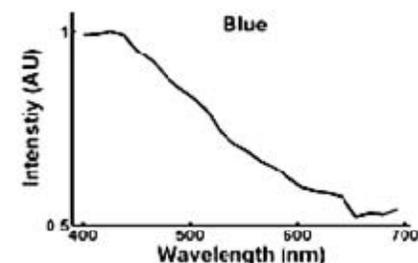
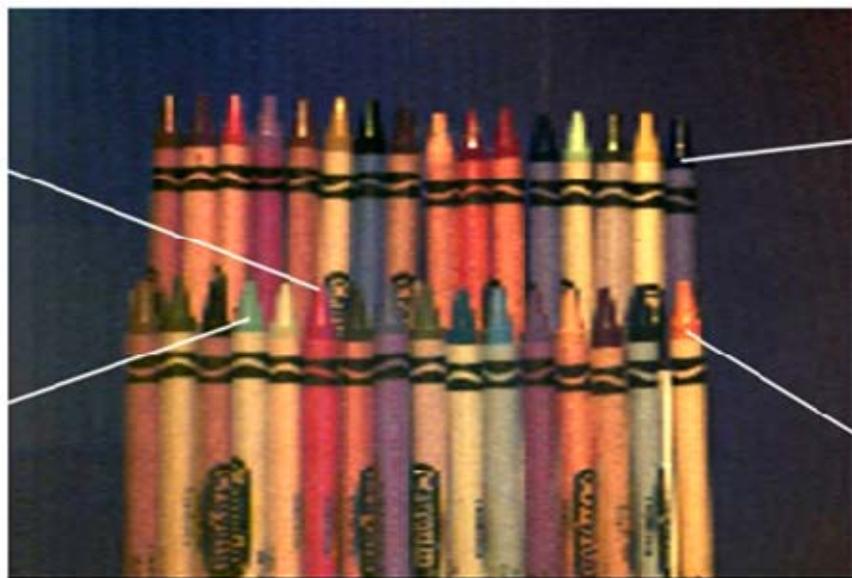
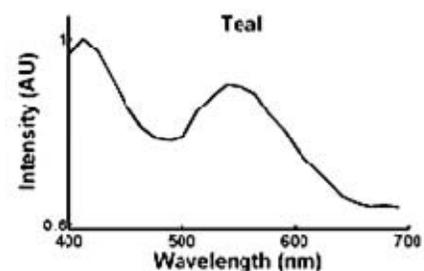
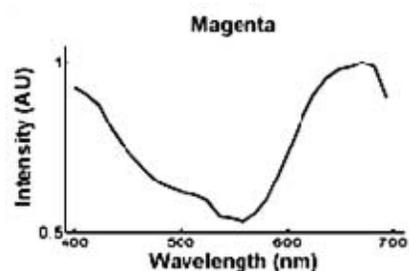
DOP + NIR



- A total of 12 filters used to create color image, extend dynamic range, and find “regions of interest”
- Error associated with low pixel values, angular diversity of compared images

Experimental Results

■ An example of spectral imaging

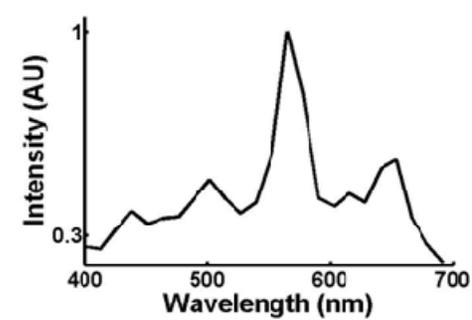
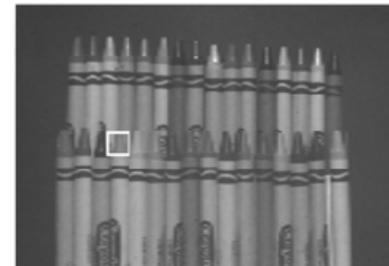
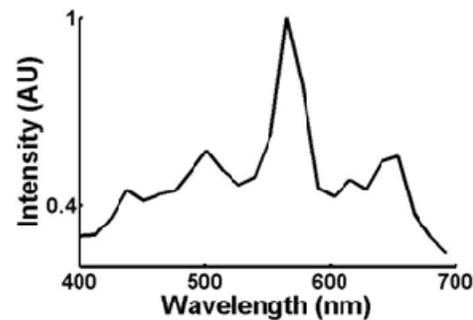
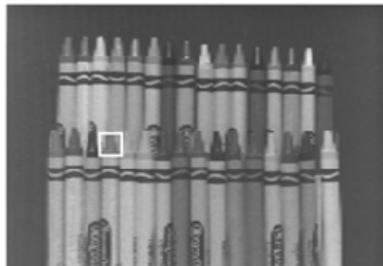
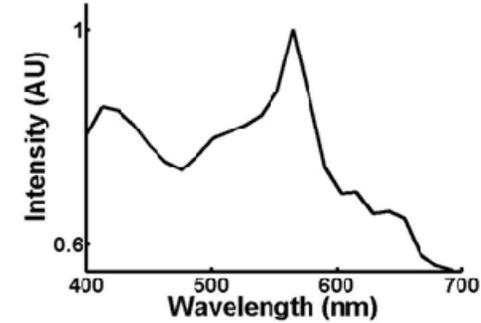
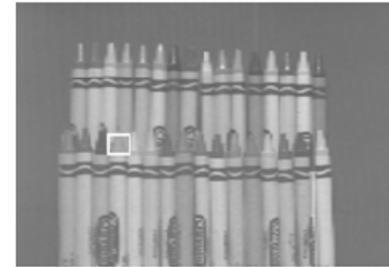
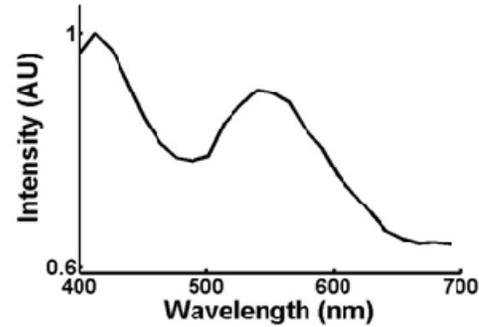
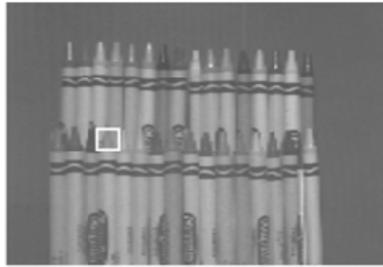


Courtesy of SPIE. Used with permission. Source: Horstemeyer, R., R. A. Athale, and G. Euliss.

"Light Field Architecture for Reconfigurable Multimode Imaging." Proc. of SPIE 7468, August 2009. doi: 10.1117/12.828653

- **With Spectral filter in aperture, have roughly 25 spectral channels per pixel**

- Another example:
Changing the lighting causes a shift in spectrum:



References

1. Arete Associates, "Polarization Imaging Streak Tube LIDAR (PISTL)," http://www.arete.com/index.php?view=ms_stil
2. <http://bobatkings.com/photography/tutorials/polarizers.html>
3. Davidhazy, A. , "Stressed Plastics by Polarization", <http://people.rit.edu/andpph/text-polarization.html>
4. http://www.classzone.com/books/earth_science/terc/content/investigations/esu101/esu101page07.cfm
5. Barnard, R., Gray, B., van der Gracht, J., Mirotznik, M., Mathews, S., "PERIODIC: state-of-the-art array imaging technology," Proc. 45th annual ACM southeast regional conference, 544-545 (2007)
6. http://en.wikipedia.org/wiki/High_dynamic_range_imaging
7. Kinemacolor: <http://www.widescreenmuseum.com/oldcolor/kinemaco.htm>
8. <http://www.ebajapan.jp/images/remotesensing.jpg>
9. Generalized Mosaicing: http://www1.cs.columbia.edu/CAVE/projects/gen_mos/
10. C.S.L Chun and F. A. Sadjadi. Polarimetric imaging system for automatic target detection and recognition. DTIC No. ADA392865, 2000
11. http://en.wikipedia.org/wiki/Bayer_filter
12. S. K. Nayar and S. G. Narasimhan. Assorted pixels: multi-sampled imaging with structural models. Proc ECCV, 2002
13. R. J. Plemmons, S. Prasad, S. Matthews, M. Mirotznik, R. Barnard, G. Gray, V. P. Pauca, T. C. Torgersen, J. van der Gracht, and G. Behrmann. PERIODIC: Integrated Computational Array Imaging Technology. Adaptive Optics OSA Technical Digest, CMA1, 2007
14. M.E. Gehm, R. John, D.J. Brady, R.M. Willett, and T.J. Schult, Single-shot compressive spectral imaging with a dual disperser architecture, Optics Express, 2007
15. N. Hagen, E.L. Dereniak. Analysis of computed tomographic imaging spectrometers. Spatial and spectral resolution. Applied Optics 47 (28) 2008.

References

16. E. H. Adelson and J. Y. A. Wang. Single lens stereo with a plenoptic camera. *IEEE Trans. Pattern Anal. Machine Intell.* 14(2): 99-106, 1992
17. R. Ng, M. Levoy, M. Bredif, G. Duval, M. Horowitz, and P Hanaran. Light field photography with a hand-held plenoptic camera. Stanford Tech Report CTSR 2005-02, 2005
18. R. Raskar, A. Agrawal, C.A. Wilson, and A. Veeraraghavan. Glare aware photography: 4D ray sampling for reducing glare effects of camera lenses. *ACM Trans. Graph* 27(3), 56, 2008
19. F. N. Lanchester. English Patent No. 16548/95 (1895)
20. R. E. Liesegang. *British Journal of Photography* Vol. 43: 569, 1896
21. J. A. C. Branfill. *British Journal of Photography* Vol. 44: 142, 1897
22. R. Berthon. English Patent No. 10611/09 (1909)
23. J. S. Friedman. *History of Color Photography*. Read Books: 222-250, 2007
24. M. Young. Pinhole Optics. *Applied Optics* 10(12): 2763-2767, 1971

MIT OpenCourseWare
<http://ocw.mit.edu>

MAS.531 Computational Camera and Photography
Fall 2009

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.