

➤ Last Lecture

- Newton's Three Laws

➤ Today

- More discussion
- Lots of examples

➤ Important Concepts

- Think carefully about what object each force acts on
- Think carefully about which forces have well defined values and which one you need to calculate from $F=ma$
- Think carefully about the acceleration

Important Reminders

- Pset # 3 due Friday at 10am.
- Exam #1 average = 64.
- Final class grade will be on a curve.
- We don't give letter grade equivalents on individual exams. General guidance is:
 - >80 is good, <60 is not good, <45 is poor
- If you want to discuss your exam or general class performance, contact me or your recitation instructor during office hours or by appointment.

Newton's Three Laws

- 1) If \vec{v} is constant, then $\Sigma \vec{F}$ must be zero and if $\Sigma \vec{F}=0$, then \vec{v} must be constant.
- 2) $\Sigma \vec{F} = m\vec{a}$
- 3) Force **due to** object **A on** object **B** is always exactly equal in magnitude and always exactly opposite in direction to the force **due to** object **B on** object **A**.

Some Advice

- Your instincts are often wrong. Be careful!
- $\Sigma \vec{F} = m\vec{a}$ is your friend. Trust what it tells you.

Inertial Reference Frames

- These principles only apply for observers who are not accelerating, a so-called "inertial" frame
- There are philosophical objections to this concept since it's hard to precisely define an inertial frame except as one where Newton's Laws are valid
- Alternative formulations are beyond the scope of this course, you don't need to worry about it

Forces you know about (so far)

- ➔ Gravity near Earth's surface: $|F|=Mg$, points "down"
- ➔ String tension: Can be given explicitly or implicitly or found from $\sum \vec{F} = m\vec{a}$
 - ➔ One example: "String breaks if tension is larger than XX."
- ➔ External forces: Can be given explicitly or found from $\sum \vec{F} = m\vec{a}$
- ➔ Normal force: Almost always found from $\sum \vec{F} = m\vec{a}$

➔ Problem Solving Tool:(Revised)Free-Body Checklist

- ➔ Draw a clear diagram of (each) object
- ➔ Think carefully about all of the forces on (each) object
- ➔ Think carefully about the angles of the forces
- ➔ Chose an axis, put it on your drawing
- ➔ Think carefully about the acceleration and put what you know on your drawing
- ➔ Calculate components: $\sum F_x = ma_x$ $\sum F_y = ma_y$...
- ➔ Solve...

An Old Friend: Component Checklist

- ➔ Loop through vectors, is there a component?
- ➔ Is there an angle factor
- ➔ Is it sine or cosine?
- ➔ Is it positive or negative?

Summary

- ➔ $\sum \vec{F} = m\vec{a}$ $\sum \vec{F} = m\vec{a}$ $\sum \vec{F} = m\vec{a}$
- ➔ Action-reaction pairs are an important concept in solving problems but need to be considered very carefully, especially the fact that the two forces in the pair act on different objects
- ➔ Think carefully about which forces can almost always only be determined using $\sum \vec{F} = m\vec{a}$
 - ➔ Typical examples are the normal force and string tension