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Solutions Manual for Electromechanical Dynamics

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PROBLEM 13.1

In static equilibrium, we have

$$-\nabla p - \rho g \bar{i}_1 = 0 \quad (a)$$

Since $p = \rho RT$, (a) may be rewritten as

$$RT \frac{d\rho}{dx_1} + \rho g = 0 \quad (b)$$

Solving, we obtain

$$\rho = \rho_0 e^{-\frac{g}{RT} x_1} \quad (c)$$

PROBLEM 13.2

Since the pressure is a constant, Eq. (13.2.25) reduces to

$$\rho v \frac{dv}{dz} = -J_y B \quad (a)$$

where we use the coordinate system defined in Fig. 13P.4. Now, from Eq. (13.2.21) we obtain

$$J_y = \sigma(E_y + vB) \quad (b)$$

If the loading factor K , defined by Eq. (13.2.32) is constant, then

$$-KvB = +E \quad (c)$$

$$\text{Thus, } J_y = \sigma vB(1-K) \quad (d)$$

$$\text{Then } \rho v \frac{dv}{dz} = -\sigma vB^2(1-K) \quad (e)$$

$$\text{or } \rho \frac{dv}{dz} = -\sigma B^2(1-K) = -\sigma(1-K) \frac{B_1^2 A_1}{A(z)} \quad (f)$$

From conservation of mass, Eq. (13.2.24), we have

$$\rho_1 v_1 A_1 = \rho A(z) v \quad (g)$$

Thus

$$\frac{\rho_1 v_1 A_1}{v} \frac{dv}{dz} = -\sigma(1-K) B_1^2 A_1 \quad (h)$$

Integrating, we obtain

$$\ln v = \frac{-\sigma(1-K) B_1^2}{\rho_1 v_1} z + C \quad (i)$$

or

$$v = v_i e^{-\frac{z}{\ell_d}} \quad (j)$$

where $\ell_d = \frac{\rho_1 v_1}{\sigma(1-K) B_1^2}$ and we evaluate the arbitrary constant by realizing that

$$v = v_i \text{ at } z = 0.$$

PROBLEM 13.3
Part a

We assume T , B_o , w , σ , c_p and c_v are constant. Since the electrodes are short-circuited, $E = 0$, and so

$$J_y = v B_o. \quad (a)$$

We use the coordinate system defined in Fig. 13P.4. Applying conservation of energy, Eq. (13.2.26), we have

$$\rho v \frac{d}{dz} \left(\frac{1}{2} v^2 \right) = 0, \text{ where we have set } h = \text{constant}. \quad (b)$$

Thus, v is a constant, $v = v_i$. Conservation of momentum, Eq. (13.2.25), implies

$$\frac{dp}{dz} = -v_i B_o^2 \quad (c)$$

$$\text{Thus, } p = -v_i B_o^2 z + p_i \quad (d)$$

The mechanical equation of state, Eq. (13.1.10) then implies

$$\rho = \frac{n}{RT} = -\frac{v_i B_o^2 z + p_i}{RT} = \rho_i - \frac{v_i B_o^2 z}{RT} \quad (e)$$

From conservation of mass, we then obtain

$$\rho_i v_i w d_i = \left(-\frac{v_i B_o^2 z}{RT} + \rho_i \right) v_i w d(z) \quad (f)$$

Thus

$$d(z) = \frac{\rho_i d_i}{\left(\rho_i - \frac{v_i B_o^2 z}{RT} \right)} \quad (g)$$

Part b

Then

$$\rho(z) = \rho_i - \frac{v_i B_o^2 z}{RT} \quad (h)$$

PROBLEM 13.4
Note:

There are errors in Eqs. (13.2.16) and (13.2.31). They should read:

$$\frac{1}{M^2} \frac{d(M^2)}{dx_1} = \frac{\{(\gamma-1)(1+\gamma M^2)E_3 + \gamma[2 + (\gamma-1)M^2]v_1 B_2\} J_3}{(1-M^2)\gamma p v_1} \quad (13.2.16)$$

and

$$\frac{1}{M^2} \frac{d(M^2)}{dx_1} = \frac{1}{(1-M^2)} \left\{ [(\gamma-1)(1+\gamma M^2)E_3 + \gamma[2 + (\gamma-1)M^2]v_1 B_2] \frac{J_3}{\gamma p v_1} - \frac{[2 + (\gamma-1)M^2]dA}{A} \frac{dA}{dx_1} \right\} \quad (13.2.31)$$

Part a

We assume that σ , γ , B_o , K and M are constant along the channel. Then, from the corrected form of Eq. (13.2.31), we must have

PROBLEM 13.4 (continued)

$$0 = \frac{1}{1-M^2} \left\{ [(\gamma-1)(1+\gamma M^2)(-K) + \gamma(2+(\gamma-1)M^2)] \frac{v B_o^2 \sigma (1-K)}{\gamma p} - \frac{[2+(\gamma-1)M^2]}{A} \frac{dA}{dz} \right\} \quad (a)$$

Now, using the relations

$$v^2 = M^2 \gamma R T$$

and $p = \rho R T$

we write

$$\frac{v}{\gamma p} = \frac{M^2}{\rho v} \quad (b)$$

Thus, we obtain

$$\frac{1}{A^2} \frac{dA}{dz} = \frac{[(\gamma-1)(1+\gamma M^2)(-K) + \gamma(2+(\gamma-1)M^2)] \frac{B_o^2 \sigma (1-K) M^2}{\rho v A}}{2+(\gamma-1)M^2} \quad (c)$$

From conservation of mass,

$$\rho v A = \rho_1 v_1 A_1 \quad (d)$$

Using (d), we integrate (c) and solve for $\frac{A(z)}{A_1}$

to obtain

$$\frac{A(z)}{A_1} = \frac{1}{1 - \beta_1 z} \quad (e)$$

where

$$\beta_1 = \frac{[(\gamma-1)(1+\gamma M^2)(-K) + \gamma(2+(\gamma-1)M^2)] \sigma B_o^2 M^2 (1-K)}{\rho_1 v_1 [2+(\gamma-1)M^2]}$$

We now substitute into Eq. (13.2.27) to obtain

$$\frac{1}{v} \frac{dv}{dz} = \frac{1}{(1-M^2)} [(\gamma-1)(-K) + \gamma] \frac{v B_o^2 (1-K) \sigma}{\gamma p} - \frac{1}{A} \frac{dA}{dz} \quad (f)$$

Thus may be rewritten as

$$\frac{1}{v} \frac{dv}{dz} = \frac{1}{(1-M^2)} \left[[(\gamma-1)(-K) + \gamma] \frac{\sigma B_o^2 (1-K) M^2}{\rho_1 v_1 A_1} - \frac{\beta_1}{A_1} \right] A \quad (g)$$

Solving, we obtain

$$\ln v = -\frac{\beta_2}{\beta_1} \ln(1 - \beta_1 z) + \ln v_1 \quad (h)$$

or

$$\frac{v(z)}{v_1} = (1 - \beta_1 z)^{-\beta_2/\beta_1} \quad (i)$$

where $\beta_2 = \frac{1}{(1-M^2)} \frac{[(\gamma-1)(-K) + \gamma] \sigma B_o^2 (1-K) M^2 - \beta_1}{\rho_1 v_1}$

Now the temperature is related through Eq. (13.2.12), as

PROBLEM 13.4 (continued)

$$M^2 \gamma RT = v^2 \quad (j)$$

Thus
$$\frac{T(z)}{T_i} = \left(\frac{v}{v_i} \right)^2 \quad (k)$$

From (d), we have

$$\frac{\rho(z)}{\rho_i} = \frac{v_i A_i}{v A} \quad (l)$$

Thus, from Eq. (13.1.10)

$$\frac{p(z)}{p_i} = \frac{v_i A_i T}{v A T_i} \quad (m)$$

Since the voltage across the electrodes is constant,

$$E = - \frac{V}{w(z)} = - Kv(z)B_o \quad (n)$$

or
$$w(z) = \frac{Kv_i B_o w_i}{Kv(z)B_o} = \frac{v_i}{v(z)} w_i \quad (o)$$

Thus,
$$\frac{w(z)}{w_i} = \frac{v_i}{v(z)} \quad (p)$$

Then
$$\frac{d(z)}{d_i} = \frac{A(z)}{A_i} \frac{w_i}{w(z)} \quad (q)$$

Part b

We now assume that σ , γ , B_o , K and v are constant along the channel. Then, from Eq. (13.2.27) we have

$$0 = \frac{1}{(1-M^2)} \left\{ [(\gamma-1)(-K) + \gamma] v_i B_o^2 \frac{(1-K)\sigma}{\gamma p} - \frac{1}{A} \frac{dA}{dz} \right\} \quad (r)$$

But, from Eq. (13.2.25) we know that

$$\frac{p}{p_i} = 1 - \frac{(1-K)\sigma v_i B_o^2 z}{p_i} = 1 - \beta_3 z \quad (s)$$

where
$$\beta_3 = (1-K) \frac{\sigma v_i B_o^2}{p_i}$$

Substituting the results of (b), into (a) and solving for $\frac{A(z)}{A_i}$, we obtain

$$\frac{A(z)}{A_i} = \left(\frac{p}{p_i} \right)^{-\beta_4 / \beta_3} \quad (t)$$

where
$$\beta_4 = [(\gamma-1)(-K) + \gamma] \frac{v_i B_o^2}{\gamma p_i} (1-K)\sigma$$

From conservation of mass,

$$\frac{\rho(z)}{\rho_i} = \frac{A_i}{A(z)} \quad (u)$$

PROBLEM 13.4 (continued)

and so, from Eq. (13.1.10)

$$\frac{T(z)}{T_i} = \frac{p(z)}{p_i} \frac{\rho_i}{\rho(z)} \quad (v)$$

As in (p)

$$\frac{w(z)}{w_i} = \frac{v_i}{v(z)} = 1 \quad (w)$$

Thus

$$\frac{d(z)}{d_i} = \frac{A(z)}{A_i} \quad (x)$$

Part c

We wish to find the length ℓ such that

$$\frac{C_p T(\ell) + \frac{1}{2} [v(\ell)]^2}{C_p T(o) + \frac{1}{2} [v(o)]^2} = .9 \quad (y)$$

For the constant M generator of part (a), we obtain from (i) and (k)

$$\frac{C_p \left[\frac{v(\ell)}{v_i} \right]^2 T_i + \frac{1}{2} [v(\ell)]^2}{C_p \left[\frac{v(o)}{v_i} \right]^2 T_i + \frac{1}{2} [v(o)]^2} = \frac{C_p (1 - \beta_1 \ell)^{-2\beta_2/\beta_1} T_i + \frac{1}{2} [v_i (1 - \beta_1 \ell)]^2}{C_p T_i + \frac{1}{2} v_i^2} = .9 \quad (z)$$

Reducing, we obtain

$$(1 - \beta_1 \ell)^{-2\beta_2/\beta_1} = .9 \quad (aa)$$

Substituting the given numerical values, we have

$$\beta_1 = .396 \quad \text{and} \quad \beta_2/\beta_1 = -7.3 \times 10^{-2}$$

We then solve (aa) for ℓ , to obtain

$$\ell \approx 1.3 \text{ meters}$$

For the constant v generator of part (b), we obtain from (s), (t), (u) and (v)

$$\frac{C_p T_i \left[\frac{p(\ell)}{p_i} \frac{\rho_i}{\rho(\ell)} \right] + \frac{1}{2} v_i^2}{C_p T_i + \frac{1}{2} v_i^2} = .9 \quad (bb)$$

or

$$\frac{C_p T_i (1 - \beta_3 \ell)^{(1 - \beta_4/\beta_3)} + \frac{1}{2} v_i^2}{C_p T_i + \frac{1}{2} v_i^2} = .9 \quad (cc)$$

Substituting the given numerical values, we have

PROBLEM 13.4 (continued)

$$\beta_3 = .45 \quad \text{and} \quad \beta_4/\beta_3 = .857$$

Solving for l , we obtain

$$l \approx 1.3 \text{ meters.}$$

PROBLEM 13.5

We are given the following relations:

$$\frac{B(z)}{B_i} = \frac{E(z)}{E_i} = \frac{w_i}{w(z)} = \frac{d_i}{d(z)} = \left(\frac{A_i}{A(z)} \right)^{1/2}$$

and that v , σ , γ , and K are constant.

Part a

From Eq. (13.2.33),

$$J = (1-K)\sigma v B \tag{a}$$

For constant velocity, conservation of momentum yields

$$\frac{dp}{dz} = - (1-K)\sigma v B^2 \tag{b}$$

Conservation of energy yields

$$\rho v c \frac{dT}{dz} = - K(1-K)\sigma (vB)^2 \tag{c}$$

Using the equation of state,

$$p = \rho RT \tag{d}$$

we obtain

$$T \frac{d\rho}{dz} + \rho \frac{dT}{dz} = - \frac{(1-K)}{R} \sigma v B^2 \tag{e}$$

or

$$T \frac{d\rho}{dz} + \frac{(-K)(1-K)\sigma v B^2}{c_p} = - \frac{(1-K)\sigma v B^2}{R} \tag{f}$$

Thus,

$$T \frac{d\rho}{dz} = \sigma v B^2 (1-K) \left(- \frac{1}{R} + \frac{K}{c_p} \right) \tag{g}$$

Also

$$B^2 = \frac{B_i^2 (A_i)}{A(z)}$$

and

$$\rho_i A_i = \rho(z) A(z)$$

Therefore
$$T \frac{d\rho}{dz} = \frac{\sigma v B_i^2 (1-K) \left(- \frac{1}{R} + \frac{K}{c_p} \right)}{\rho_i} \rho(z) \tag{h}$$

and

$$\rho c_p \frac{dT}{dz} = -K(1-K)\sigma v \frac{B_i^2}{\rho_i} \tag{i}$$

PROBLEM 13.5 (continued)

and so

$$\frac{dT}{dz} = - \frac{K(1-K)\sigma v B_i^2}{\rho_i c_p} \quad (j)$$

Therefore

$$T = - K(1-K) \frac{\sigma v B_i^2}{\rho_i c_p} z + T_i \quad (k)$$

Let

$$\alpha = \frac{-K(1-K)\sigma v B_i^2}{\rho_i c_p} \quad (l)$$

Then

$$T = T_i \left(\frac{\alpha z}{T_i} + 1 \right) \quad (m)$$

$$\frac{d\rho}{\rho} = \frac{+ \sigma v B_i^2 (1-K) \left(\frac{K}{c_p} - \frac{1}{R} \right)}{\rho_i (\alpha z + T_i)} dz \quad (n)$$

We let

$$\begin{aligned} \beta &= \frac{+ \sigma v B_i^2 (1-K) \left(\frac{K}{c_p} - \frac{1}{R} \right)}{\rho_i \alpha} \\ &= \frac{c_p}{KR} - 1 \end{aligned}$$

Integrating (n), we then obtain

$$\ln \rho = \beta \ln(\alpha z + T_i) + \text{constant}$$

or

$$\rho = \rho_i \left(\frac{\alpha z}{T_i} + 1 \right)^\beta \quad (o)$$

Therefore

$$A(z) = \frac{A_i}{\left(\frac{\alpha z}{T_i} + 1 \right)^\beta} \quad (p)$$

Part b

From (m),

$$\frac{T(\ell)}{T_i} = \frac{\alpha \ell + T_i}{T_i} = .8$$

or

$$\frac{\alpha \ell}{T_i} = -.2$$

Now

$$\frac{\alpha}{T_i} = - \frac{K(1-K)\sigma v B_i^2}{\rho_i c_p T_i}$$

But

$$c_p T_i = \frac{R T_i}{\left(1 - \frac{1}{\gamma}\right)} = \frac{P_i}{\rho_i \left(1 - \frac{1}{\gamma}\right)} = 2.5 \times 10^6$$

PROBLEM 13.5 (Continued)

Thus

$$\frac{\alpha}{T_1} = \frac{-.5(.5)50(700)16}{.7(2.5 \times 10^6)} = -8.0 \times 10^{-2}$$

Solving for ℓ , we obtain

$$\ell = \frac{.2}{8} \times 10^2 = 1.25 \text{ meters}$$

Part c

$$\rho = \rho_1 \left(\frac{\alpha z}{T_1} + 1 \right)^\beta$$

Numerically

$$\beta = \frac{c_p}{KR} - 1 = \frac{1}{(1-\frac{1}{\gamma})K} - 1 \approx 6.$$

Thus

$$\rho(z) = .7(1 - .08z)^6$$

Then it follows:

$$p(z) = \rho RT = p_1 (1 - .08z)^7 = 5 \times 10^5 (1 - .08z)^7$$

$$T(z) = T_1 (1 - .08z)$$

From the given information, we cannot solve for T_1 , only for

$$RT_1 = \frac{p_1}{\rho_1} = \frac{v_1^2}{\gamma M_1^2} \approx 7 \times 10^5$$

Now

$$\begin{aligned} M^2(z) &= \frac{v_1^2}{\gamma RT(z)} = \frac{v_1^2}{\gamma p(z)} \rho(z) = \frac{v_1^2}{\gamma} \frac{\rho_1 \left(\frac{\alpha z}{T_1} + 1 \right)^\beta}{p_1 \left(\frac{\alpha z}{T_1} + 1 \right)^{(\beta+1)}} \\ &= \frac{.5}{1 - .08z} \end{aligned}$$

Part d

The total electric power drawn from this generator is

$$\begin{aligned} p^e &= VI = -E(z)w(z)J(z)\ell d(z) \\ &= -E(z)(1-K)\sigma v B(z)\ell d(z)w(z) \\ &= -E_1 w_1 (1-K)\sigma v B_1 d_1 \ell \end{aligned}$$

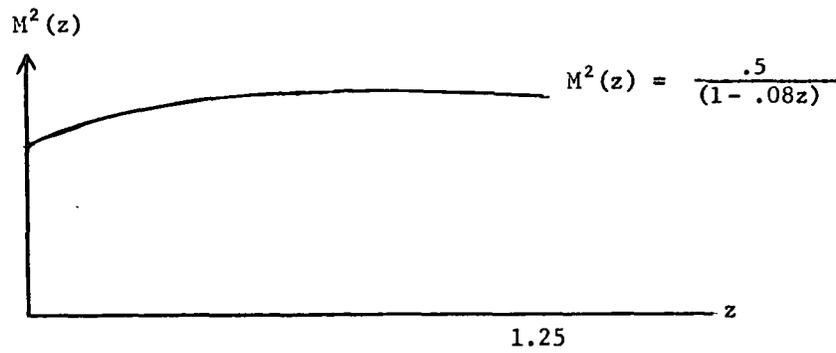
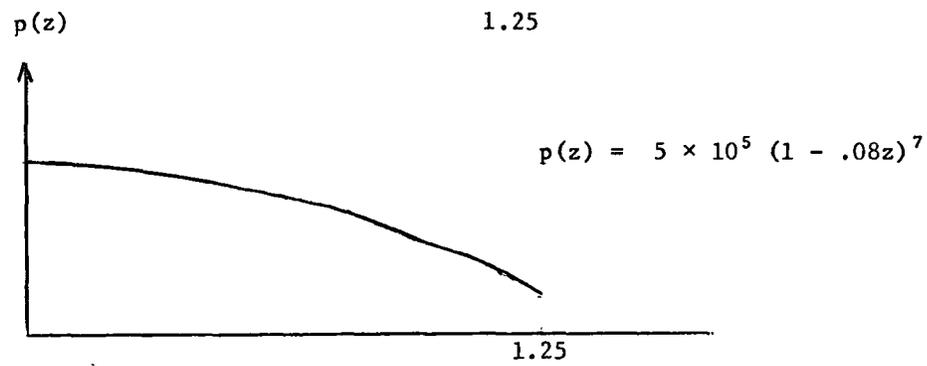
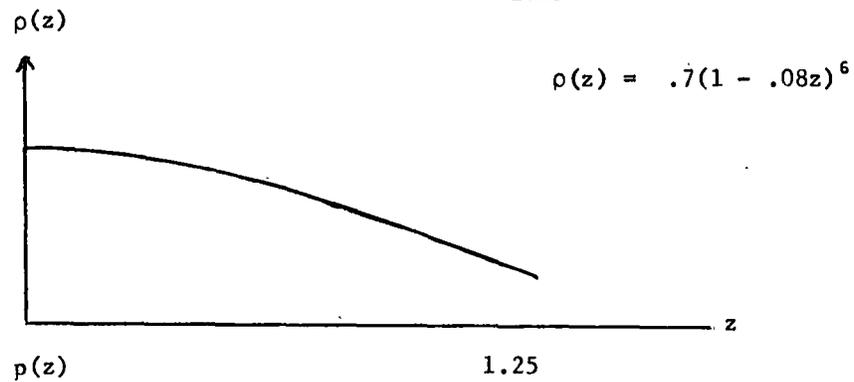
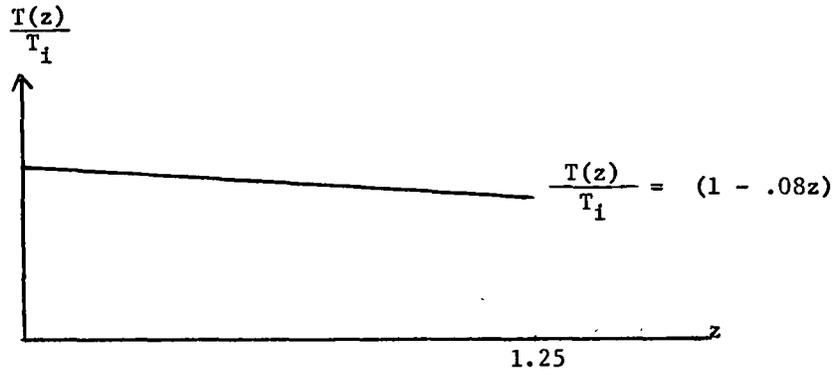
But

$$E_1 = -KvB_1$$

Thus

$$\begin{aligned} p^e &= K(vB_1)^2 w_1 d_1 \sigma (1-K)\ell \\ &= .5(700)^2 16(.5)50(.5)1.25 \\ &= 61.3 \times 10^6 \text{ watts} = 61.3 \text{ megawatts} \end{aligned}$$

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PROBLEM 13.6Part a

We are given that

$$\bar{E} = \bar{i}_x \frac{4}{3} \frac{V_o}{L^{1/3}} x^{1/3} \quad (a)$$

and

$$\rho_e = \frac{4}{9} \frac{\epsilon_o V_o}{L^{1/3} x^{2/3}} \quad (b)$$

The force equation in the steady state is

$$\rho_m v_x \frac{dv_x}{dx} \bar{i}_x = \rho_e \bar{E} \quad (c)$$

Since $\rho_e/\rho_m = q/m = \text{constant}$, we can write

$$\frac{d}{dx} \left(\frac{1}{2} v_x^2 \right) = \frac{q}{m} \frac{4}{3} \frac{V_o}{L^{1/3}} x^{1/3} \quad (d)$$

Solving for v_x we obtain

$$v_x = \sqrt{\frac{2q}{m} V_o \left(\frac{x}{L} \right)^{2/3}} \quad (e)$$

Part b

The total force per unit volume acting on the accelerator system is

$$\bar{F} = \rho_e \bar{E} \quad (f)$$

Thus, the total force which the fixed support must exert is

$$\begin{aligned} \bar{f}_{\text{total}} &= - \int_0^L F dV \bar{i}_x \\ &= - \int_0^L \frac{16}{27} \frac{\epsilon_o V_o^2}{L^{2/3}} x^{-1/3} A dx \bar{i}_x \\ \bar{f}_{\text{total}} &= - \frac{8}{9} \frac{\epsilon_o V_o^2}{L^2} A \bar{i}_x \end{aligned}$$

PROBLEM 13.7Part a

We refer to the analysis performed in section 13.2.3a. The equation of motion for the velocity is, Eq. (13.2.76),

$$\frac{\partial^2 v}{\partial t^2} = a^2 \frac{\partial^2 v}{\partial x_1^2} \quad (a)$$

The boundary conditions are

$$\begin{aligned} v(-L) &= V_o \cos \omega t \\ v(0) &= 0 \end{aligned}$$

We write the solution in the form

PROBLEM 13.7 (continued)

$$v(x_1, t) = \operatorname{Re}[A e^{j(\omega t - kx_1)} + B e^{j(\omega t + kx_1)}] \quad (b)$$

where $k = \frac{\omega}{a}$

Using the boundary condition at $x_1 = 0$, we can alternately write the solution as

$$v = \operatorname{Re}[A \sin kx_1 e^{j\omega t}]$$

Applying the other boundary condition at $x_1 = -L$, we finally obtain

$$v(x_1, t) = -\frac{V_0}{\sin kL} \sin kx_1 \cos \omega t. \quad (d)$$

The perturbation pressure is related to the velocity through Eq. (13.2.74)

$$\rho_0 \frac{\partial v'}{\partial t} = -\frac{\partial p'}{\partial x_1} \quad (e)$$

Solving, we obtain

$$\frac{\rho_0 V_0 \omega}{\sin kL} \sin kx_1 \sin \omega t = -\frac{\partial p'}{\partial x_1} \quad (f)$$

or

$$p' = \frac{\rho_0 V_0 \omega}{k \sin kL} \cos kx_1 \sin \omega t \quad (g)$$

where ρ_0 is the equilibrium density, related to the speed of sound a , through Eq. (13.2.83).

Thus, the total pressure is

$$p = p_0 + p' = p_0 + \frac{\rho_0 V_0 \omega}{k \sin kL} \cos kx_1 \sin \omega t \quad (h)$$

and the perturbation pressure at $x_1 = -L$ is

$$p'(-L, t) = \frac{\rho_0 V_0 a}{\sin kL} \cos kL \sin \omega t \quad (i)$$

Part b

There will be resonances in the pressure if

$$\sin kL = 0 \quad (j)$$

or $kL = n\pi \quad n = 1, 2, 3, \dots \quad (k)$

Thus

$$\omega = \frac{n\pi}{L} a \quad (l)$$

PROBLEM 13.8

Part a

We carry through an analysis similar to that performed in section 13.2.3b.

We assume that

$$\vec{E} = \vec{i}_2 E_2(x_1, t)$$

$$\vec{J} = \vec{i}_2 J_2(x_1, t)$$

PROBLEM 13.8

$$\bar{B} = \bar{i}_3 [\mu_0 H_0 + \mu_0 H'_3(x_1, t)]$$

Conservation of momentum yields

$$\rho \frac{Dv_1}{Dt} = - \frac{\partial p}{\partial x_1} + J_2 \mu_0 (H_0 + H'_3) \quad (a)$$

Conservation of energy gives us

$$\rho \frac{D}{Dt} \left(u + \frac{1}{2} v_1^2 \right) = - \frac{\partial}{\partial x_1} (pv_1) + J_2 E_2 \quad (b)$$

We use Ampere's and Faraday's laws to obtain

$$\frac{\partial H'_3}{\partial x_1} = - J_2 \quad (c)$$

and

$$\frac{\partial E_2}{\partial x_1} = - \frac{\mu_0 \partial H'_3}{\partial t} \quad (d)$$

while

Ohm's law yields

$$J_2 = \sigma [E_2 - v_1 B_3] \quad (e)$$

Since $\sigma \rightarrow \infty$

$$E_2 = v_1 B_3 \quad (f)$$

We linearize, as in Eq. (13.2.91), so $E_2 \approx v_1 \mu_0 H_0$

Substituting into Faraday's law

$$\mu_0 H_0 \frac{\partial v_1}{\partial x_1} = - \mu_0 \frac{\partial H'_3}{\partial t} \quad (g)$$

Linearization of the conservation of mass yields

$$\frac{\partial \rho'}{\partial t} = - \rho_0 \frac{\partial v_1}{\partial x_1} \quad (h)$$

Thus, from (g)

$$\frac{\mu_0 H_0}{\rho_0} \frac{\partial \rho'}{\partial t} = \mu_0 \frac{\partial H'_3}{\partial t} \quad (i)$$

Then

$$\frac{H_0}{H'_3} = \frac{\rho_0}{\rho'}$$

Linearizing Eq. (13.2.71), we obtain

$$\frac{Dp'}{Dt} = \frac{\gamma p_0}{\rho_0} \frac{D\rho'}{Dt} \quad (k)$$

PROBLEM 13.8 (continued)

Defining the acoustic speed

$$a_s = \left(\frac{\gamma p_o}{\rho_o} \right)^{1/2} \text{ where } p_o \text{ is the equilibrium pressure,}$$

$$p_o = p_1 - \frac{\mu_o H_o^2}{2}$$

we have

$$p' = a_s^2 \rho' \tag{l}$$

Linearization of conservation of momentum (a) yields

$$\rho_o \frac{\partial v_1}{\partial t} = - \frac{\partial p'}{\partial x_1} - \frac{\partial H'}{\partial x_1} \mu_o H_o \tag{m}$$

or, from (j) and (l),

$$\rho_o \frac{\partial v_1}{\partial t} = \frac{\partial \rho'}{\partial x_1} \left(- a_s^2 - \frac{\mu_o H_o^2}{\rho_o} \right) \tag{n}$$

Differentiating (n) with respect to time, and using conservation of mass (h), we finally obtain

$$\frac{\partial^2 v_1}{\partial t^2} = \left(a_s^2 + \frac{\mu_o H_o^2}{\rho_o} \right) \frac{\partial^2 v_1}{\partial x_1^2} \tag{o}$$

Defining

$$a^2 = a_s^2 + \frac{\mu_o H_o^2}{\rho_o} \tag{p}$$

we have

$$\frac{\partial^2 v_1}{\partial t^2} = a^2 \frac{\partial^2 v_1}{\partial x_1^2} \tag{q}$$

Part b

We assume solutions of the form

$$v_1 = \text{Re} [A_1 e^{j(\omega t - kx_1)} + A_2 e^{j(\omega t + kx_1)}] \tag{r}$$

where $k = \frac{\omega}{a}$

The boundary condition at $x_1 = -L$ is

$$v(-L, t) = v_s \cos \omega t = v_s \text{Re} e^{j\omega t} \tag{s}$$

and at $x_1 = 0$

$$M \frac{dv_1}{dt}(0, t) = p' A \Big|_{x_1=0} + \mu_o H_o H'_3 A \Big|_{x_1=0} \tag{t}$$

From (h), (j) and (l),

$$\frac{1}{a_s^2} \frac{\partial p'}{\partial t} = - \rho_o \frac{\partial v_1}{\partial x_1} \tag{u}$$

PROBLEM 13.8 (continued)

$$\frac{H_3'}{H_0} = \frac{p'}{a_s^2 \rho_0} \quad (v)$$

Thus

$$M \frac{dv_1(0,t)}{dt} = A \left(\frac{\mu_0 H_0^2}{a_s^2 \rho_0} + 1 \right) p' = A \frac{a^2}{a_s} p' \quad (w)$$

From (u), we solve for p' at $x_1=0$ to obtain:

$$p' \Big|_{x_1=0} = - \frac{\rho_0 a_s^2 k}{w} (A_2 - A_1) e^{j\omega t} \quad (x)$$

Substituting into (s) and (t), we have

$$Mj\omega(A_1 + A_2) = A \left(\frac{a}{a_s} \right)^2 \left(\frac{\rho_0 a_s^2 k}{w} \right) (A_1 - A_2)$$

and

$$A_1 e^{+jkl} + A_2 e^{-jkl} = v_s \quad (y)$$

Solving for A_1 and A_2 , we obtain

$$A_1 = \frac{(Mj\omega + Aa\rho_0)V_s}{2(-Mw \sin kl + Aa\rho_0 \cos kl)}$$

$$A_2 = \frac{(Aa\rho_0 - Mj\omega)V_s}{2(-Mw \sin kl + Aa\rho_0 \cos kl)} \quad (z)$$

Thus, the velocity of the piston is

$$v_1(0,t) = \text{Re} [A_1 + A_2] e^{j\omega t}$$

$$v_1(0,t) = \frac{Aa\rho_0 V_s}{-Mw \sin kl + Aa\rho_0 \cos kl} \cos \omega t \quad (aa)$$

PROBLEM 13.9

Part a

The differential equation for the velocity as derived in problem 13.8 is

$$\frac{\partial^2 v_1}{\partial t^2} = a^2 \frac{\partial^2 v_1}{\partial x_1^2} \quad (a)$$

where

$$a^2 = a_s^2 + \frac{\mu_0 H_0^2}{\rho_0}$$

with $a_s^2 = \left(\frac{\gamma p_0}{\rho_0} \right)^{1/2}$ where $p_0 = p_1 - \frac{\mu_0 H_0^2}{2}$

Part b

We assume a solution of the form

PROBLEM 13.9 (continued)

$$V(x_1, t) = \text{Re} [De^{j(\omega t - kx_1)}] \quad \text{where } k = \frac{\omega}{a}$$

We do not consider the negatively traveling wave, as we want to use this system as a delay line without distortion. The boundary condition at $x_1 = -L$ is

$$V(-L, t) = \text{Re } V_s e^{j\omega t}$$

and at $x_1 = 0$ is

$$M \frac{dV(0, t)}{dt} = p'(0, t)A - BV_1(0, t) + \mu_0 H_0 H_3' A \quad (b)$$

From problem 13.8, (h), (j) and (l)

$$p' = a_s^2 \rho' \quad , \quad \frac{\partial \rho'}{\partial t} = -\rho_0 \frac{\partial v_1}{\partial x_1} \quad \text{and} \quad \frac{H_3'}{H_0} = \frac{p'}{a_s^2 \rho_0}$$

Thus, (b) becomes

$$-BDe^{j\omega t} + \left(\frac{a}{a_s}\right)^2 p'A = 0 \quad (c)$$

where

$$p' \Big|_{x_1=0} = -\frac{\rho_0 D(-jk)}{j\omega} a_s^2 e^{j\omega t} \quad (d)$$

Thus, for no reflections

$$-B + \left(\frac{a}{a_s}\right)^2 \frac{A\rho_0 a_s^2}{a} = 0 \quad (e)$$

or

$$B = Aa\rho_0 \quad (f)$$

PROBLEM 13.10

The equilibrium boundary conditions are

$$T[-(L_1 + L_2 + \Delta), t] = T_0$$

$$T[-(L_1 + \Delta), t]A_s = -p_0 A_c$$

Boundary conditions for incremental motions are

- 1) $T[-(L_1 + L_2 + \Delta), t] = T_s(t)$
- 2) $-T[-(L_1 + \Delta), t]A_s - p(-L_1, t)A_c = M \frac{d}{dt} v_\ell(-L_1, t)$
- 3) $v_\ell(-L_1, t) = v_e[-(L_1 + \Delta), t]$ since the mass is rigid
- and 4) $v_\ell(0, t) = 0$ since the wall at $x=0$ is fixed.

PROBLEM 13.11

Part a

We can immediately write down the equation for perturbation velocity, using equations (13.2.76) and (13.2.77) and the results of chapters 6 and 10.

PROBLEM 13.11 (continued)

We replace $\partial/\partial t$ by $\partial/\partial t + \mathbf{v} \cdot \nabla$ to obtain

$$\left(\frac{\partial}{\partial t} + V_0 \frac{\partial}{\partial x}\right)^2 v' = a_s^2 \frac{\partial^2 v'}{\partial x^2}$$

Letting $v' = \text{Re } \hat{v} e^{j(\omega t - kx)}$

we have

$$(\omega - kV_0)^2 = a_s^2 k^2$$

Solving for ω , we obtain

$$\omega = k(V_0 \pm a_s)$$

Part b

Solving for k , we have

$$k = \frac{\omega}{V_0 \pm a_s}$$

For $V_0 > a_s$, both waves propagate in the positive x - direction.

PROBLEM 13.12

Part a

We assume that

$$\begin{aligned} \bar{E} &= \bar{i}_z E_z(x,t) \\ \bar{J} &= \bar{i}_z J_z(x,t) \\ \bar{B} &= \bar{i}_y \mu_0 [H_0 + H'_y(x,t)] \end{aligned}$$

We also assume that all quantities can be written in the form of Eq. (13.2.91) .

$$\rho_0 \frac{\partial v_x}{\partial t} = - \frac{\partial p'}{\partial x} - J_z \mu_0 H_0 \quad (\text{conservation of momentum linearized}) \quad (a)$$

The relevant electromagnetic equations are

$$\frac{\partial H'_y}{\partial x} = J_z \quad (b)$$

and

$$\frac{\partial E_z}{\partial x} = \mu_0 \frac{\partial H'_y}{\partial t} \quad (c)$$

and the constitutive law is

$$J_z = \sigma(E_z + v_x \mu_0 H_0) \quad (d)$$

We recognize that Eqs. (13.2.94), (13.2.96) and (13.2.97) are still valid, so

$$\frac{1}{\rho_0} \frac{\partial \rho'}{\partial t} = - \frac{\partial v_x}{\partial x} \quad (e)$$

PROBLEM 13.12 (continued)

and

$$p' = a_s^2 \rho' \quad (f)$$

Part b

We assume all perturbation quantities are of the form

$$\mathbf{v}_x = \text{Re}[\hat{\mathbf{v}} e^{j(\omega t - kx)}]$$

Using (b), (a) may be rewritten as

$$\rho_o j\omega \hat{\mathbf{v}} = +jk\hat{p} + \mu_o H_o jk\hat{H} \quad (g)$$

and (c) may now be written as

$$-jk\hat{E} = \mu_o j\omega \hat{H} \quad (h)$$

Then, from (b) and (d)

$$-jk\hat{H} = \sigma(\hat{E} + \hat{\mathbf{v}}\mu_o H_o) \quad (i)$$

 Solving (g) and (h) for \hat{H} in terms of $\hat{\mathbf{v}}$, we have

$$\hat{H} = \frac{\hat{\mathbf{v}}\sigma\mu_o H_o}{\left(-jk + \sigma\mu_o \frac{\omega}{k}\right)} \quad (j)$$

 From (e) and (f), we solve for \hat{p} in terms of $\hat{\mathbf{v}}$ to be

$$\hat{p} = \frac{k}{\omega} \rho_o a_s^2 \hat{\mathbf{v}} \quad (k)$$

Substituting (j) and (k) back into (g), we find

$$\hat{\mathbf{v}} \left[\rho_o j\omega - \frac{jk^2}{\omega} \rho_o a_s^2 - \frac{jk(\mu_o H_o)^2 \sigma}{\left[-jk + \frac{\sigma\mu_o \omega}{k}\right]} \right] = 0 \quad (l)$$

Thus, the dispersion relation is

$$\left(\omega^2 - k^2 a_s^2\right) - \frac{j(\mu_o H_o)^2 \omega k^2}{\left(+\frac{k^2}{\sigma} + j\mu_o \omega\right) \rho_o} = 0 \quad (m)$$

 We see that in the limit as $\sigma \rightarrow \infty$, this dispersion relation reduces to the lossless dispersion relation

$$\omega^2 - k^2 \left(a_s^2 + \frac{\mu_o H_o^2}{\rho_o}\right) = 0 \quad (n)$$

Part c

 If σ is very small, we can approximate (m) as

$$\omega^2 - k^2 a_s^2 - j(\mu_o H_o)^2 \frac{\omega \sigma}{\rho_o} \left(1 - \frac{j\omega \mu_o \sigma}{k^2}\right) = 0 \quad (o)$$

for which we can rewrite (o) as

PROBLEM 13.12 (continued)

$$k^4 a_s^2 - k^2 \left[\omega^2 - j\omega\sigma \frac{(\mu_o H_o)^2}{\rho_o} \right] + \left(\frac{\mu_o H_o}{\rho_o} \right)^2 \omega^2 \sigma^2 \mu_o = 0 \quad (p)$$

Solving for k^2 , we obtain

$$k^2 = \frac{\omega^2 - j\omega\sigma \frac{(\mu_o H_o)^2}{\rho_o}}{2 a_s^2} \pm \sqrt{\left[\frac{\omega^2 - j\omega\sigma \frac{(\mu_o H_o)^2}{\rho_o}}{2 a_s^2} \right]^2 - \frac{\left(\frac{\mu_o \omega^2 \sigma^2}{\rho_o} \right) (\mu_o H_o)^2}{a_s^2}} \quad (q)$$

Since σ is very small, we expand the radical in (q) to obtain

$$k^2 = \frac{\left[\omega^2 - j\omega\sigma \frac{(\mu_o H_o)^2}{\rho_o} \right]}{2 a_s^2} \pm \left[\frac{\omega^2 - \frac{j\omega\sigma}{\rho_o} (\mu_o H_o)^2}{2 a_s^2} - \frac{\left(\frac{\mu_o \omega^2 \sigma^2}{\rho_o} \right) (\mu_o H_o)^2}{\left[\omega^2 - \frac{j\omega\sigma}{\rho_o} (\mu_o H_o)^2 \right]} \right] \quad (r)$$

Thus, our approximate solutions for k^2 are

$$k^2 \approx \frac{\left[\omega^2 - j\omega\sigma \frac{(\mu_o H_o)^2}{\rho_o} \right]}{a_s^2} \quad (s)$$

and

$$k^2 \approx \frac{\left(\frac{\mu_o \omega^2 \sigma^2}{\rho_o} \right) (\mu_o H_o)^2}{\left[\omega^2 - \frac{j\omega\sigma}{\rho_o} (\mu_o H_o)^2 \right]} \approx \left(\frac{\mu_o \sigma^2}{\rho_o} \right) (\mu_o H_o)^2 \quad (t)$$

The wavenumbers for the first pair of waves are approximately:

$$k \approx \pm \left(\frac{\omega - j \frac{\sigma}{2\rho_o} (\mu_o H_o)^2}{a_s} \right) \quad (u)$$

while for the second pair, we obtain

$$k \approx \pm \sigma (\mu_o H_o) \sqrt{\frac{\mu_o}{\rho_o}} \quad (v)$$

The wavenumbers from (u) represent a forward and backward traveling wave, both with amplitudes exponentially decreasing. Such waves are called 'diffusion waves'. The wavenumbers from (v) represent pure propagating waves in the forward and reverse directions.

PROBLEM 13.12 (continued)

Part d

If σ is very large, then (m) reduces to

$$\omega^2 - k^2 a^2 - j \frac{H_o^2}{\rho_o} \frac{k^4}{\sigma \omega} = 0 ; \quad a^2 = a_s^2 + \frac{\mu_o H_o^2}{\rho_o} \quad (w)$$

This can be put in the form

$$k^2 = \frac{\omega^2}{a^2} - j \frac{f(\omega, k)}{\sigma} \quad (x)$$

where

$$f(\omega, k) = \frac{H_o^2 k^4}{\rho_o \omega a^2}$$

As σ becomes very large, the second term in (x) becomes negligible, and so

$$k^2 \approx \frac{\omega^2}{a^2} \quad (y)$$

However, it is this second term which represents the damping in space; that is,

$$k \approx \pm \left[\frac{\omega}{a} - j \frac{f(\omega, k)}{2\sigma \omega} a \right] \quad (z)$$

Thus, the approximate decay rate, k_i , is

$$k_i \approx \frac{f(\omega, k) a}{2\sigma \omega} = \frac{H_o^2 k^4}{2\rho_o \omega a^2 \sigma} \quad (aa)$$

or

$$k_i \approx \frac{H_o^2}{2\rho_o} \frac{k^4}{a\sigma \omega^2} = \frac{H_o^2}{2\rho_o a^3 \sigma} \omega^2$$